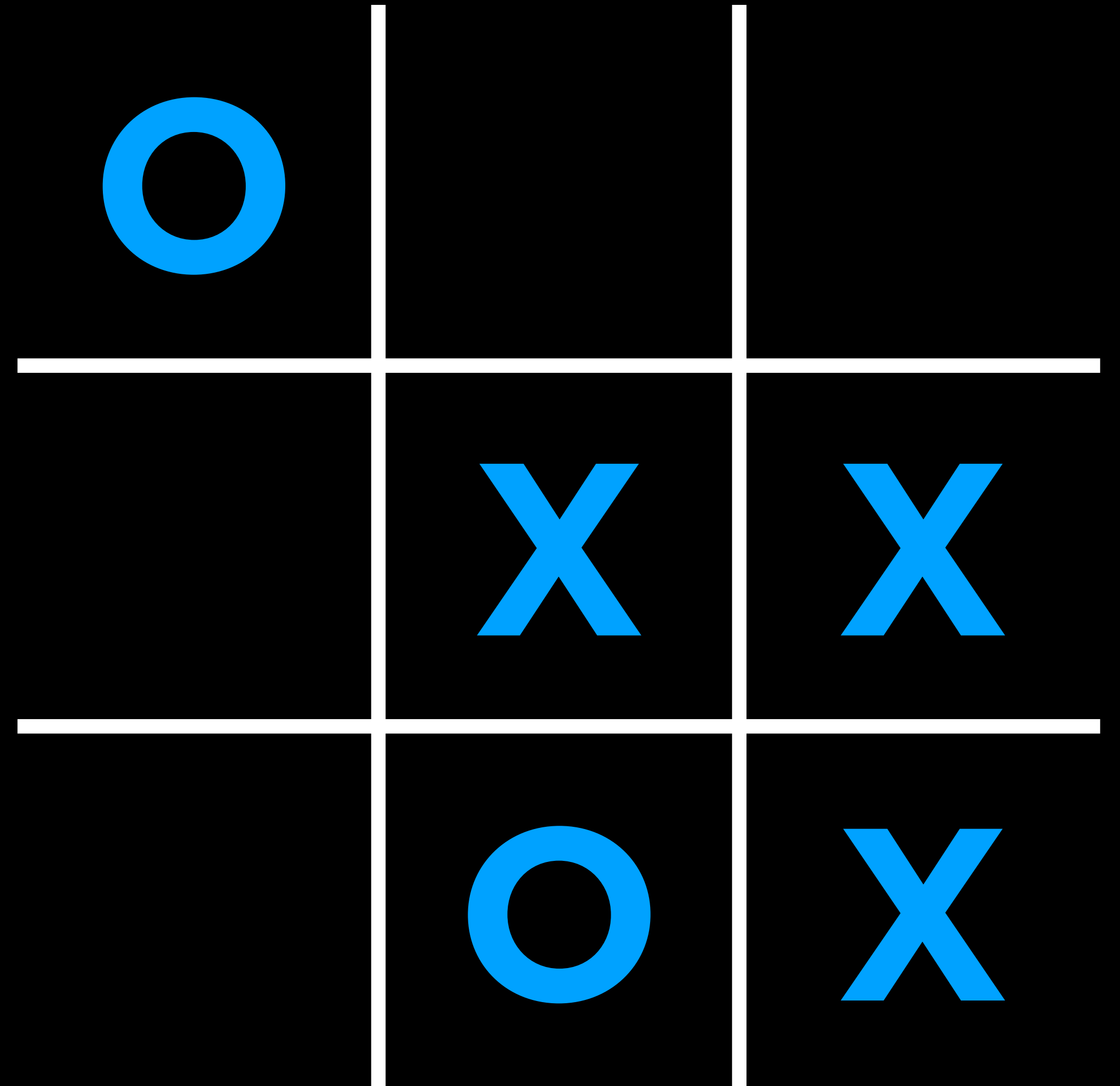


Introduction to
Artificial Intelligence
with Python

Artificial Intelligence

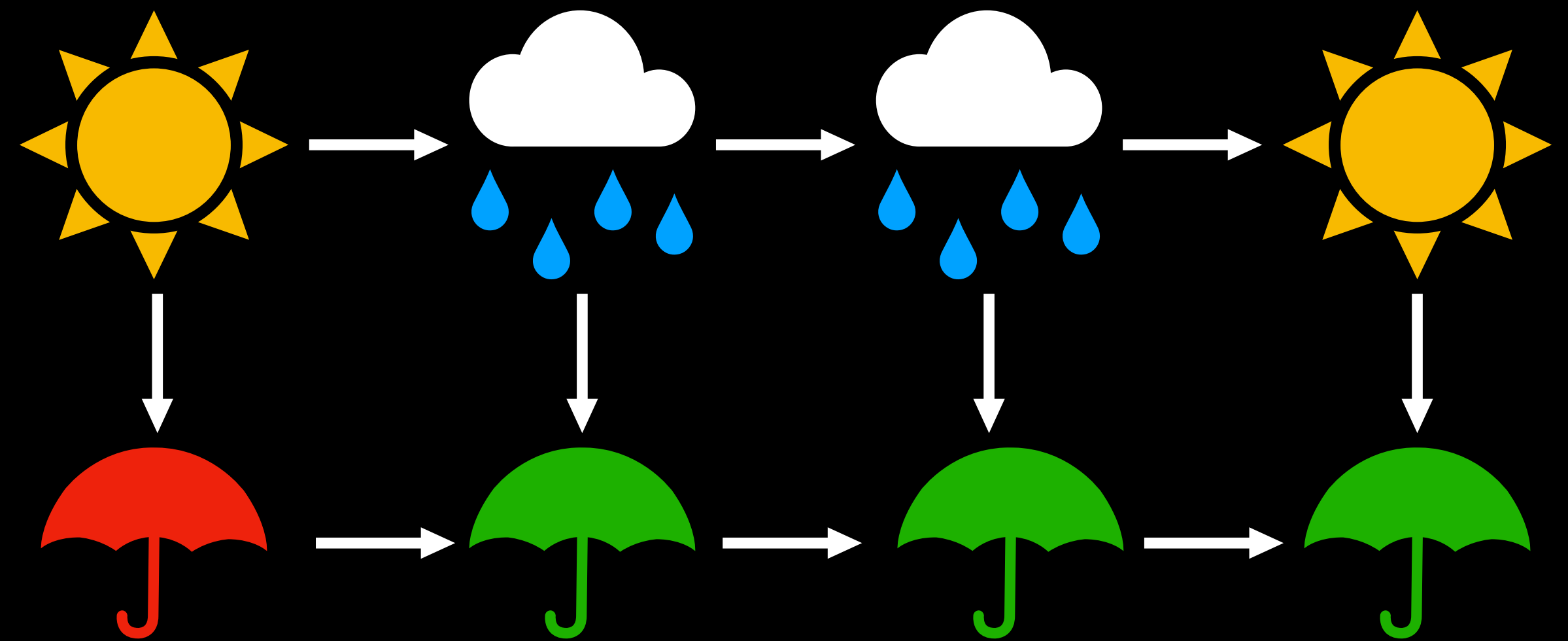
Search



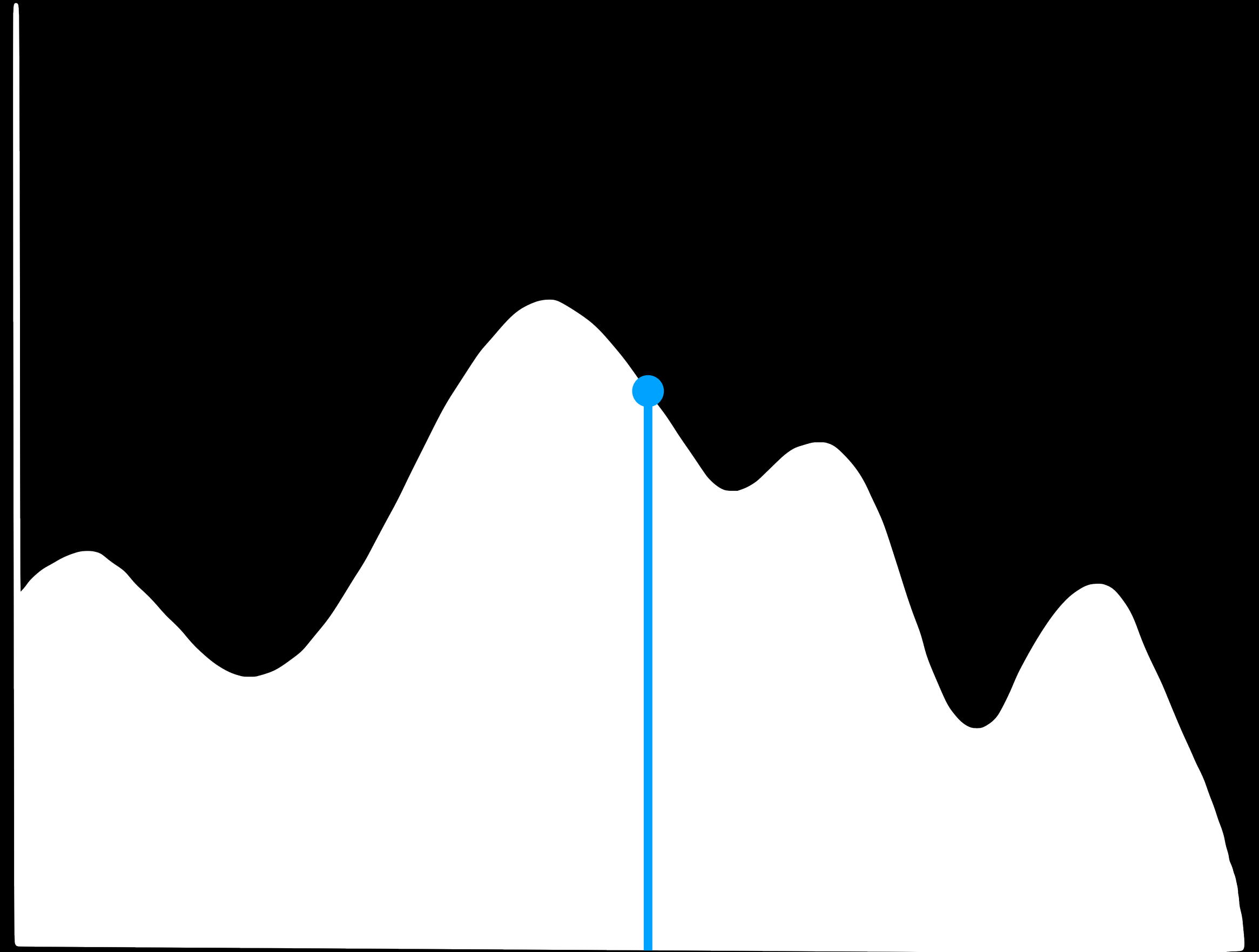
Knowledge

$$\frac{P \rightarrow Q \quad P}{Q}$$

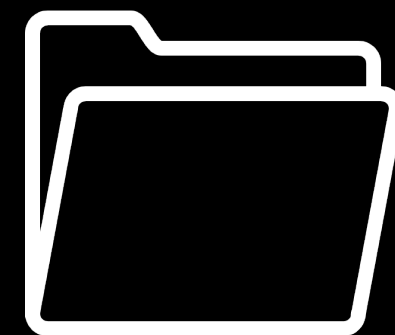
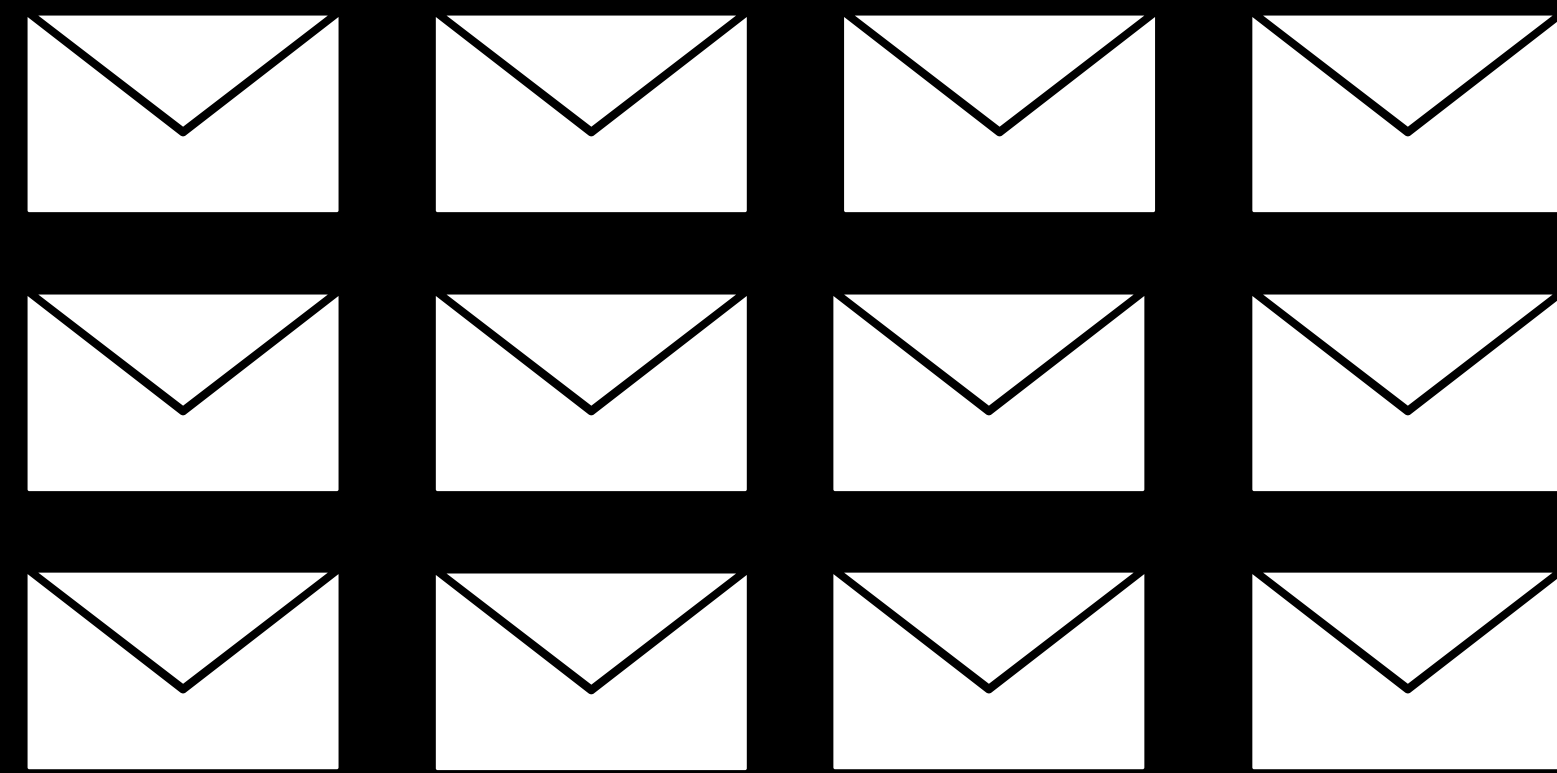
Uncertainty



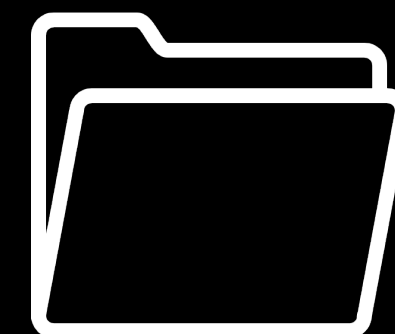
Optimization



Learning

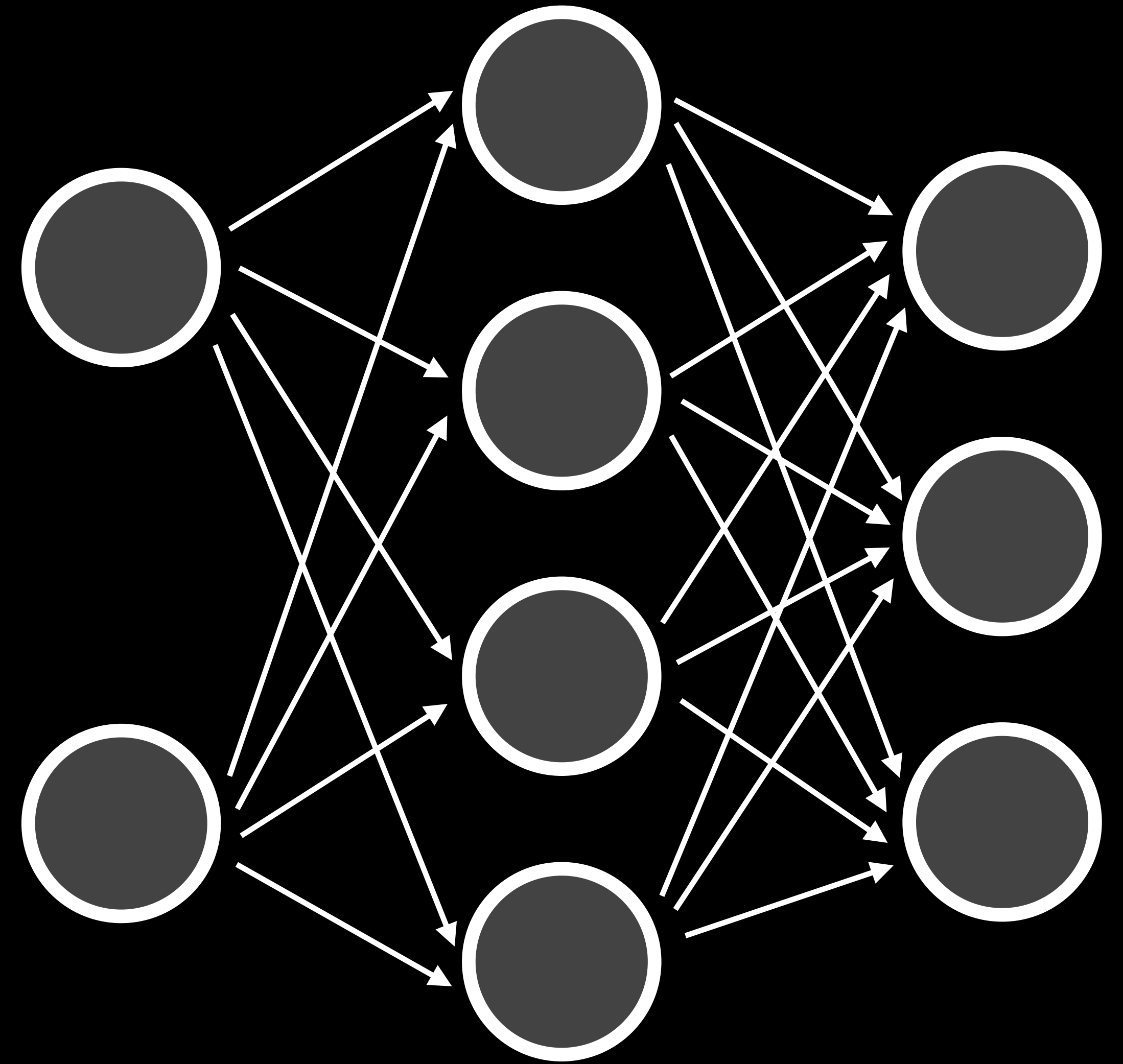


Inbox

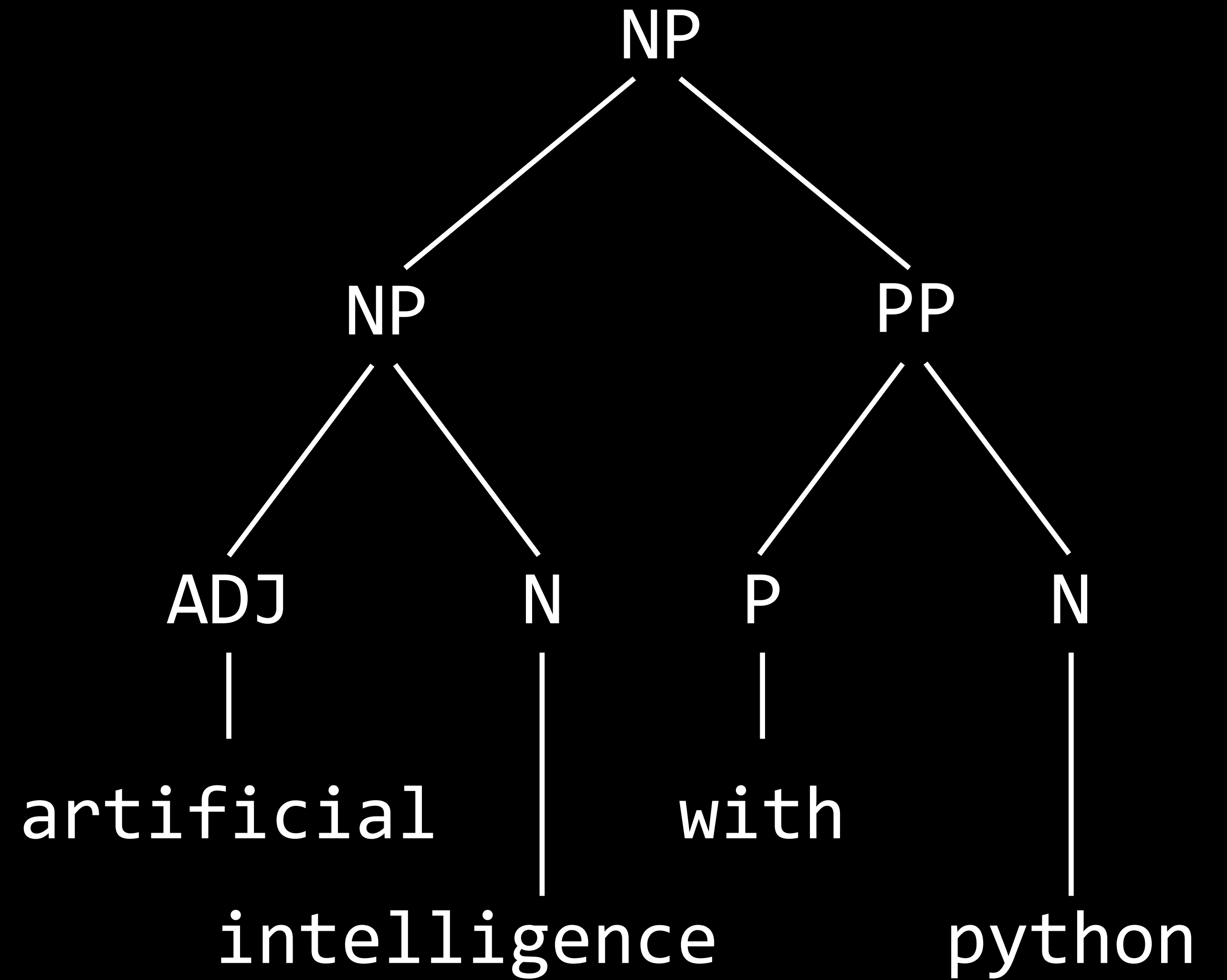


Spam

Neural Networks



Language



Search

1

2

3

4

5

6

7

8

9

10

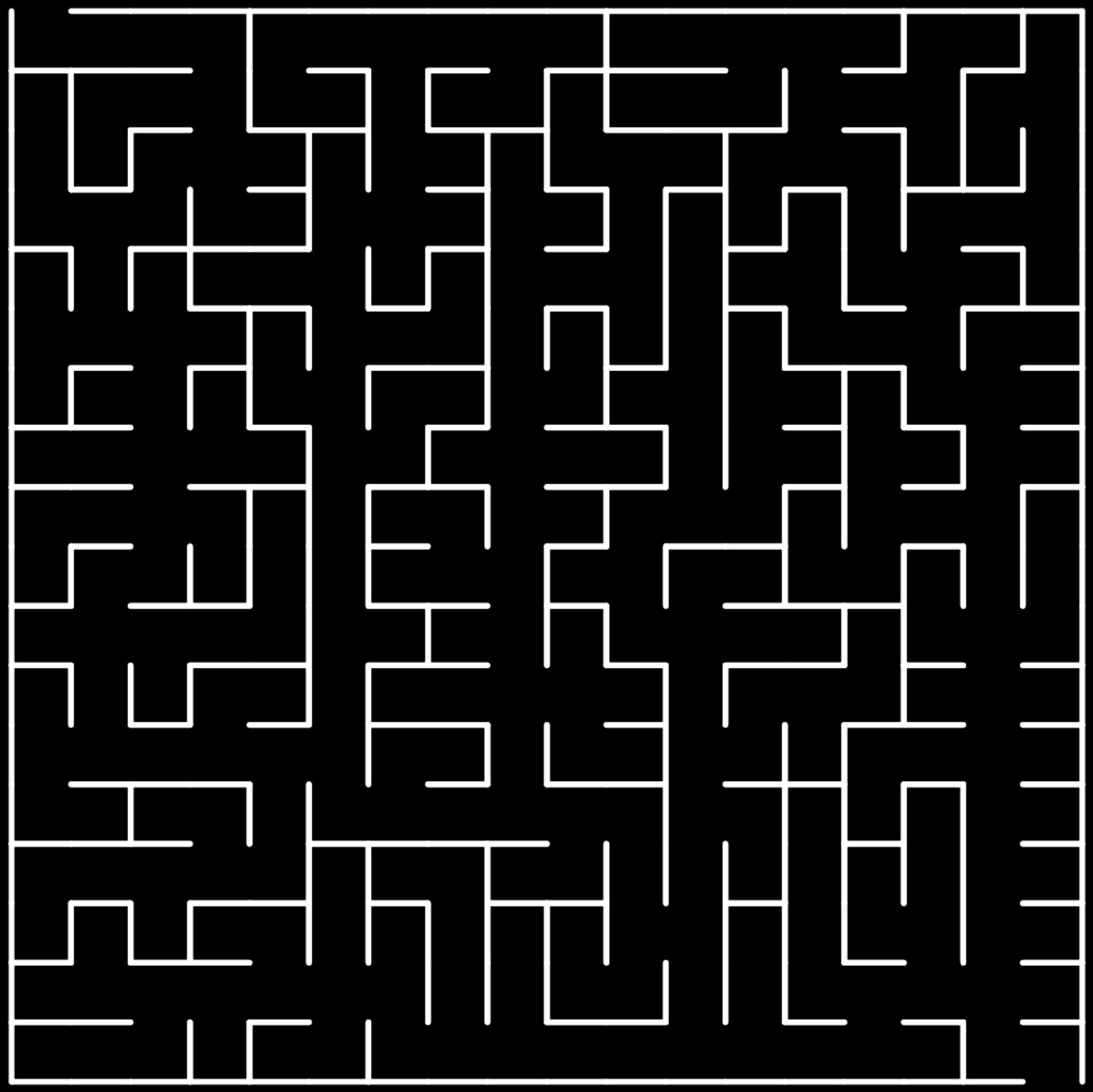
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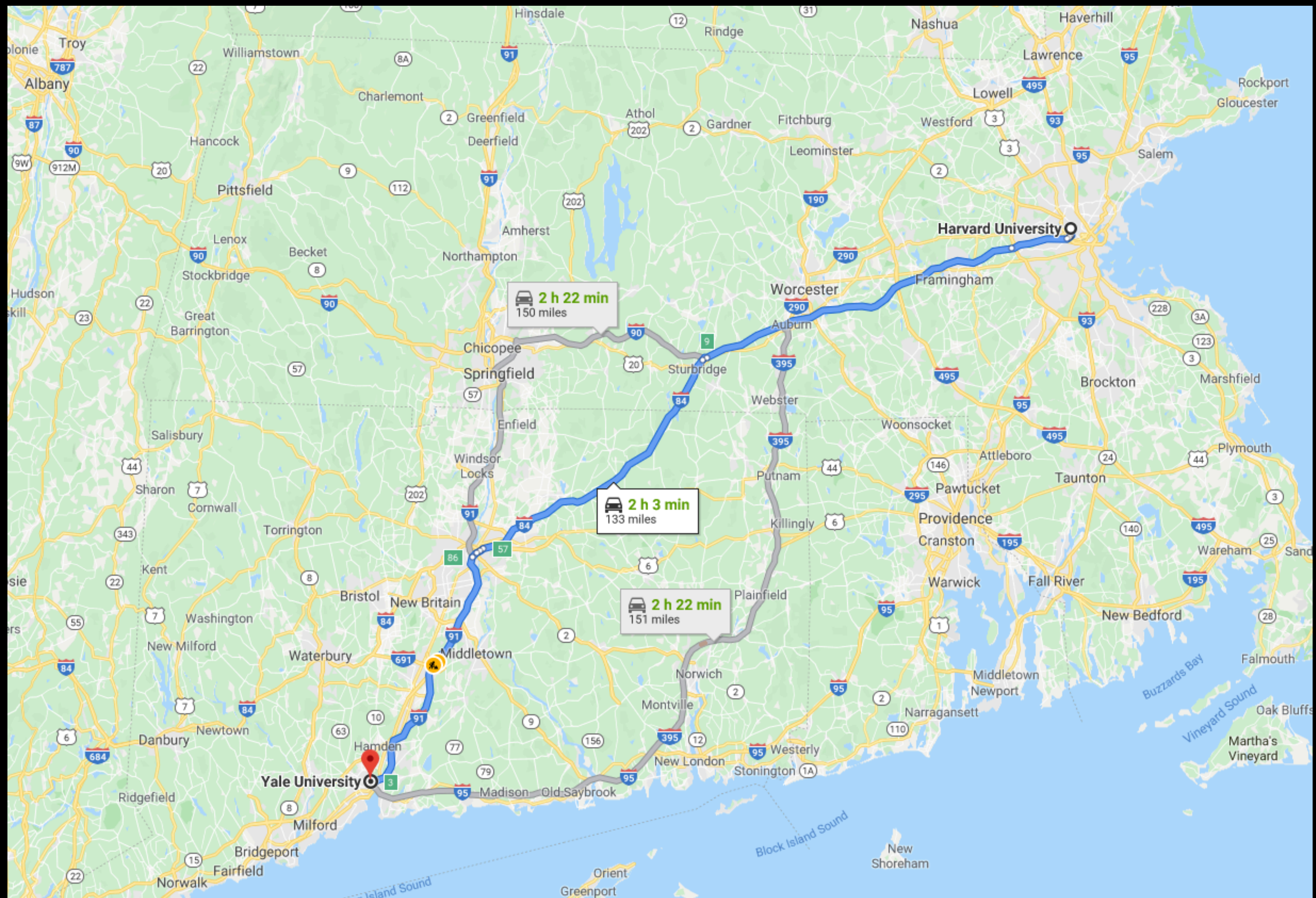
12

13

14

15





Search Problems

agent

entity that perceives its environment
and acts upon that environment

state

a configuration of the agent and
its environment

2	4	5	7
8	3	1	11
14	6		10
9	13	15	12

12	9	4	2
8	7	3	14
	1	6	11
5	13	10	15

15	4	10	3
13	1	11	12
9	5	14	7
6	8		2

initial state

the state in which the agent begins

initial state

2	4	5	7
8	3	1	11
14	6		10
9	13	15	12

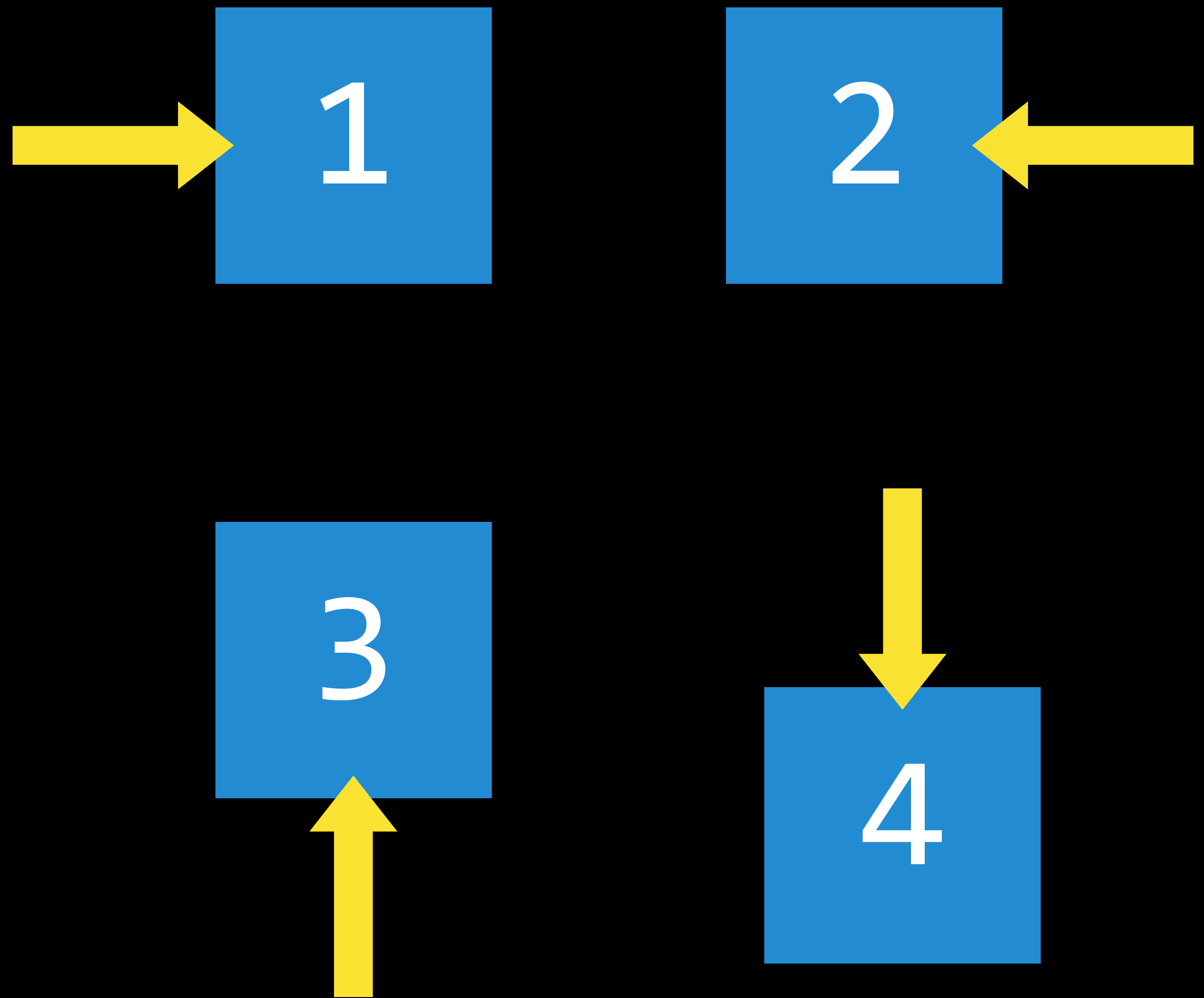
actions

choices that can be made in a state

actions

$\text{ACTIONS}(s)$ returns the set of actions that can be executed in state s

actions



transition model

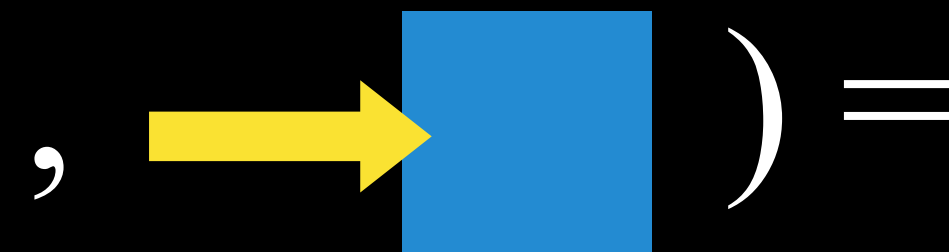
a description of what state results from performing any applicable action in any state

transition model

$\text{RESULT}(s, a)$ returns the state resulting from performing action a in state s

RESULT(

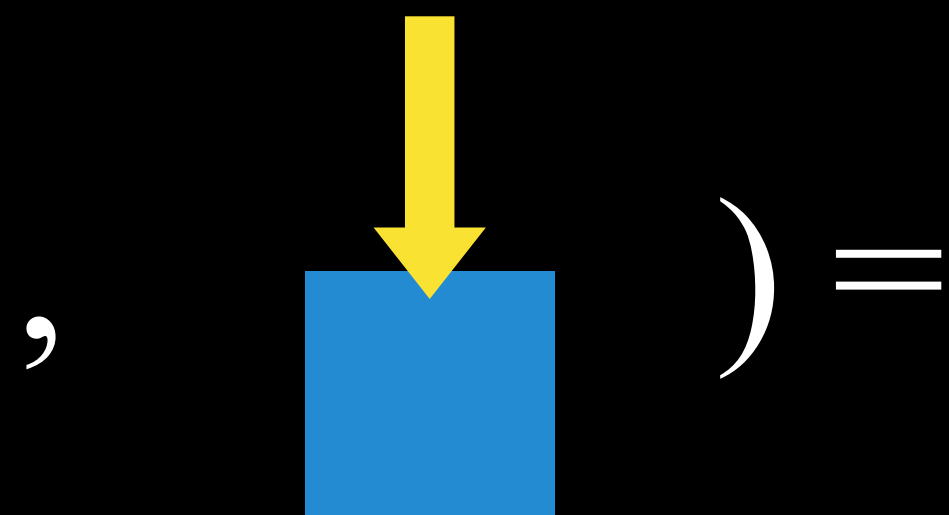
2	4	5	7
8	3	1	11
14	6	10	12
9	13	15	



2	4	5	7
8	3	1	11
14	6	10	12
9	13		15

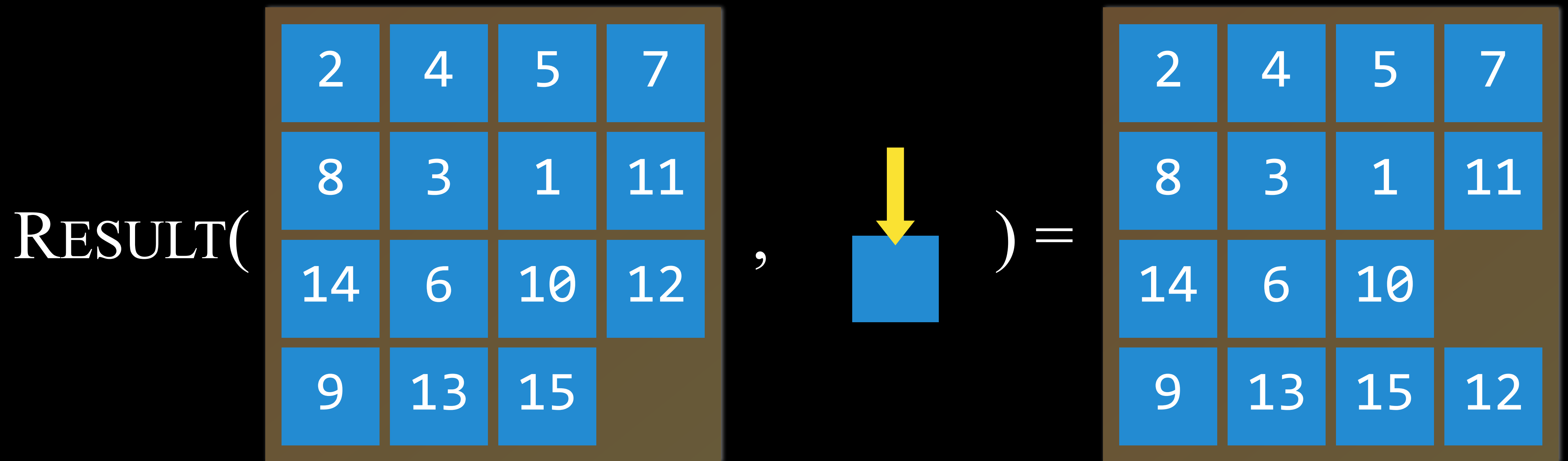
RESULT(

2	4	5	7
8	3	1	11
14	6	10	12
9	13	15	



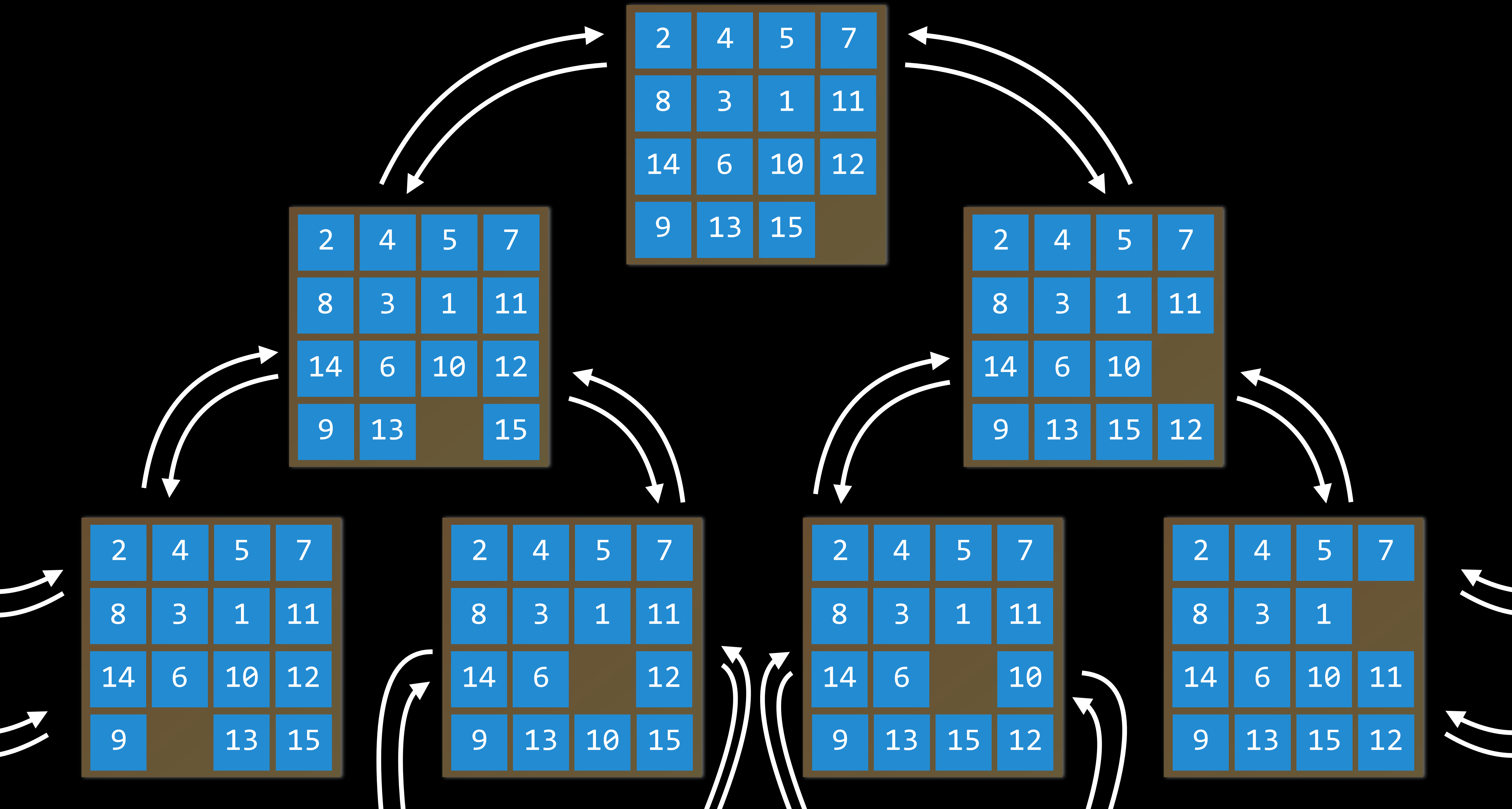
2	4	5	7
8	3	1	11
14	6	10	
9	13	15	12

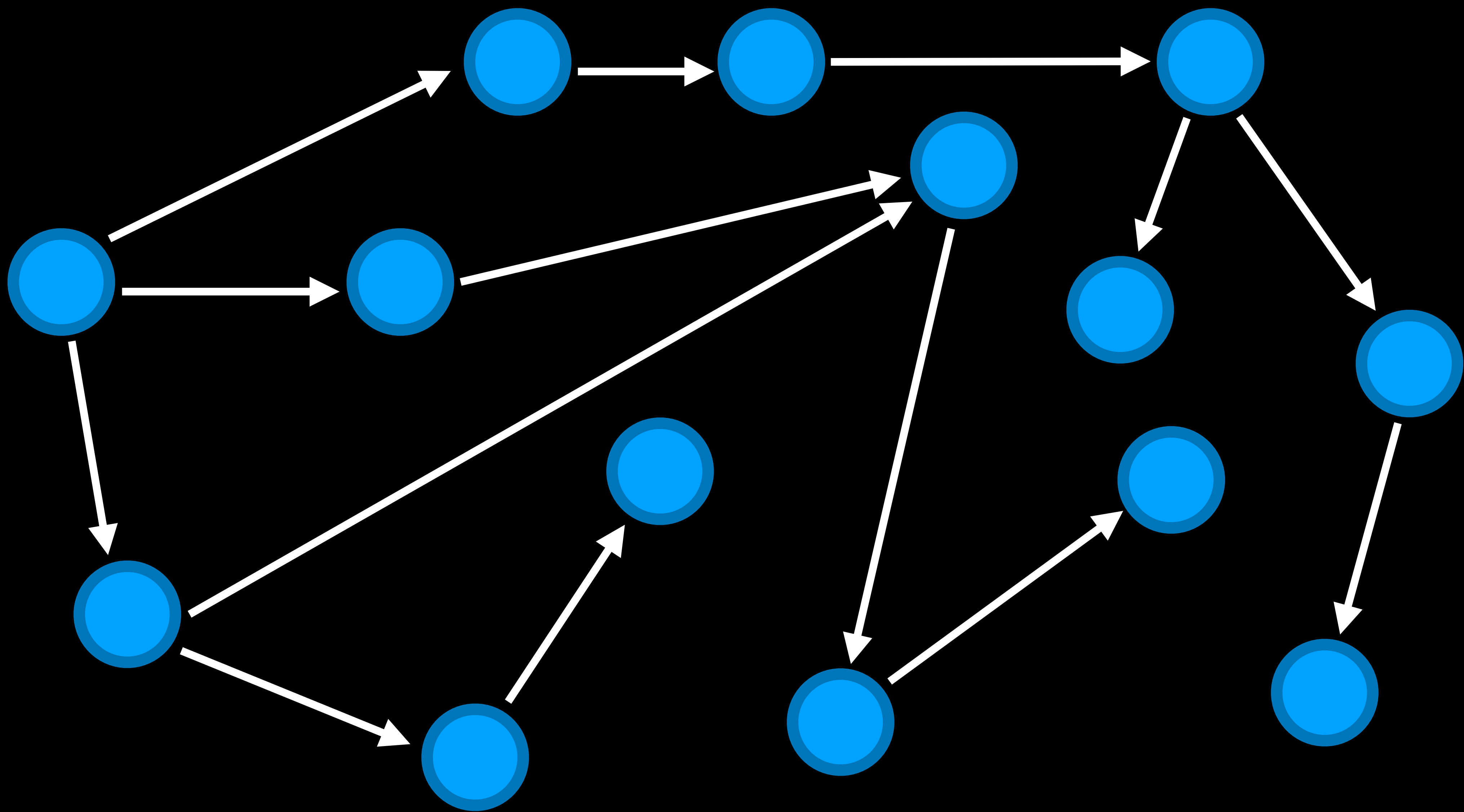
transition model



state space

the set of all states reachable from the initial state by any sequence of actions



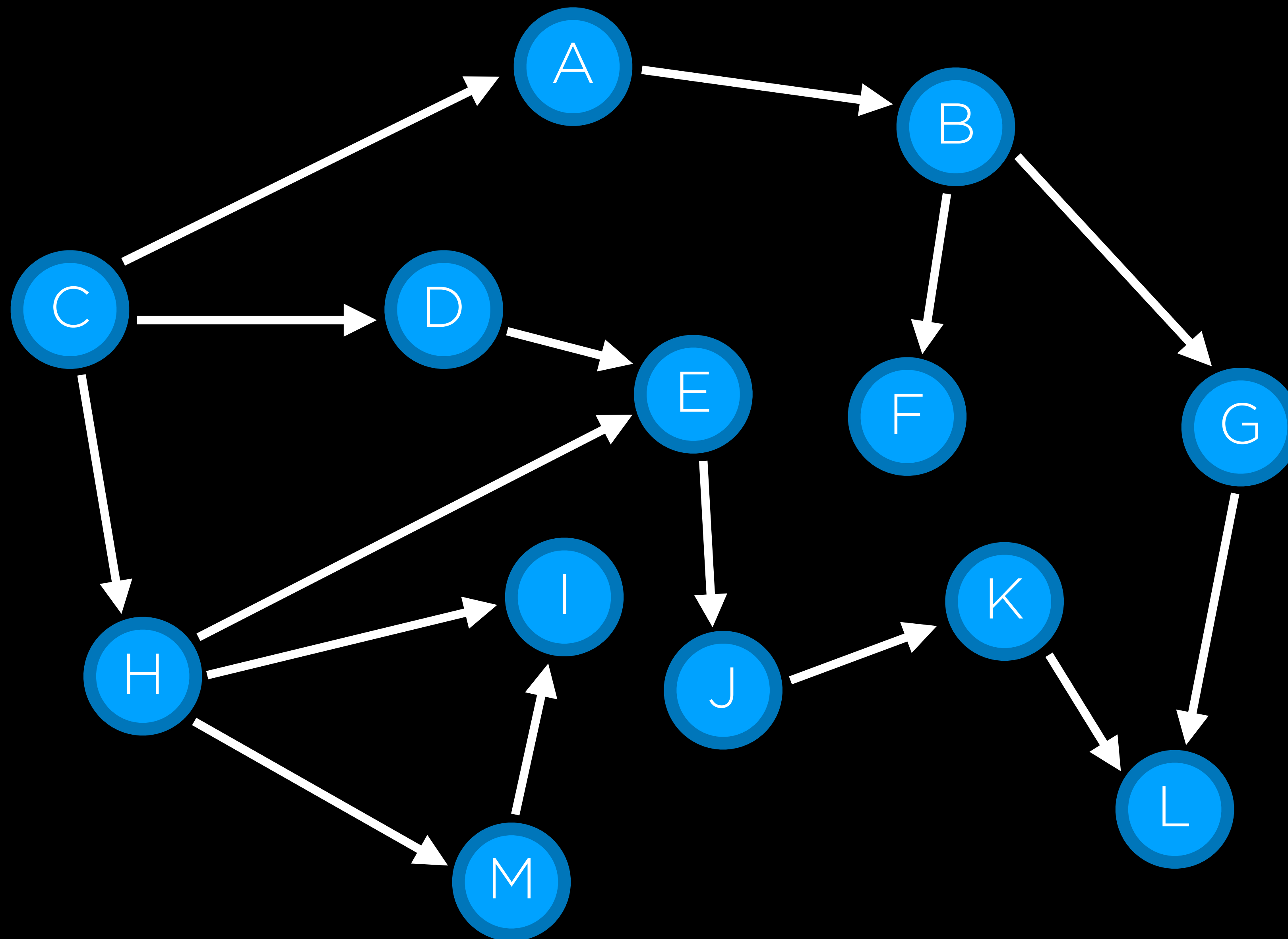


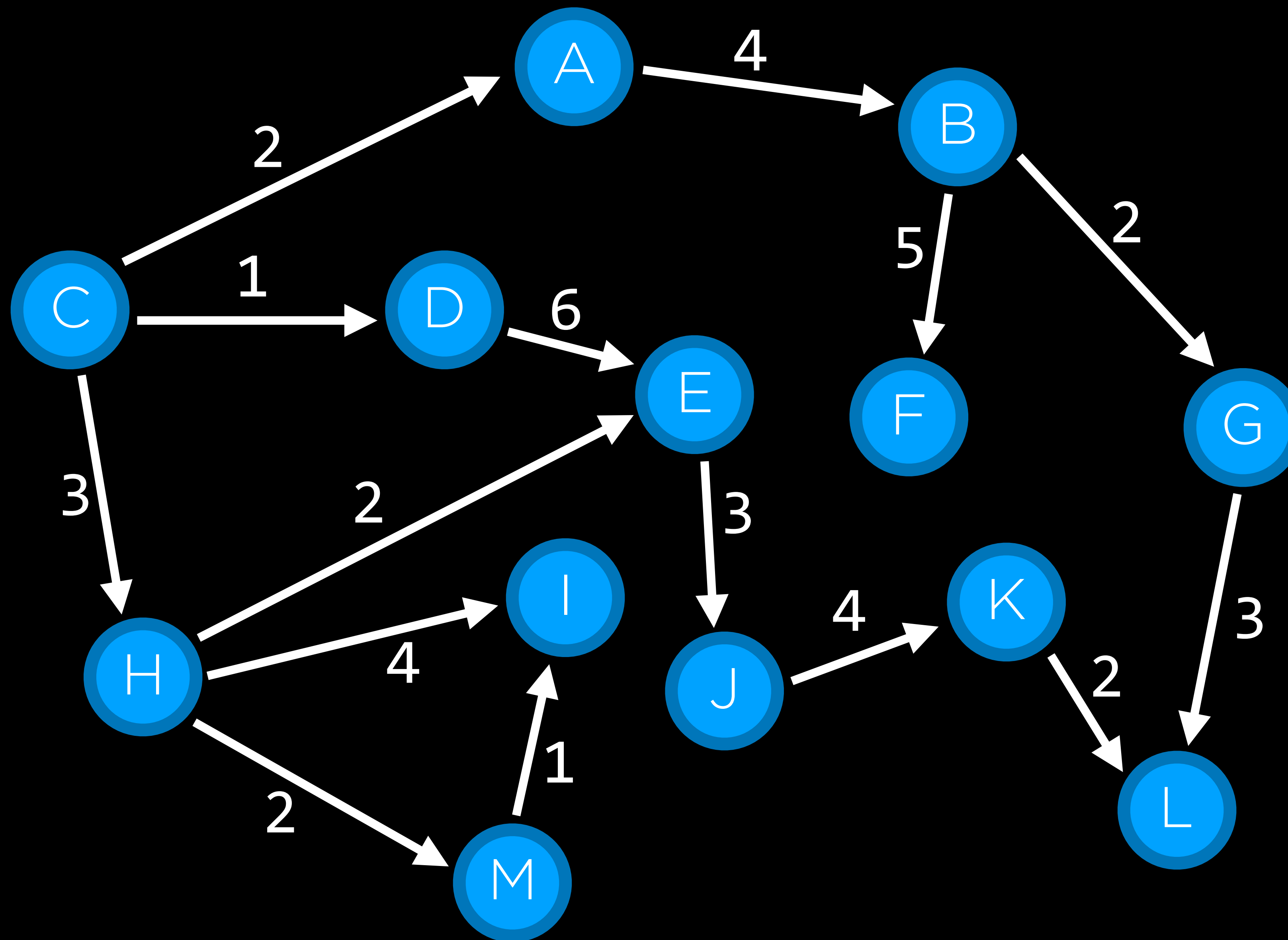
goal test

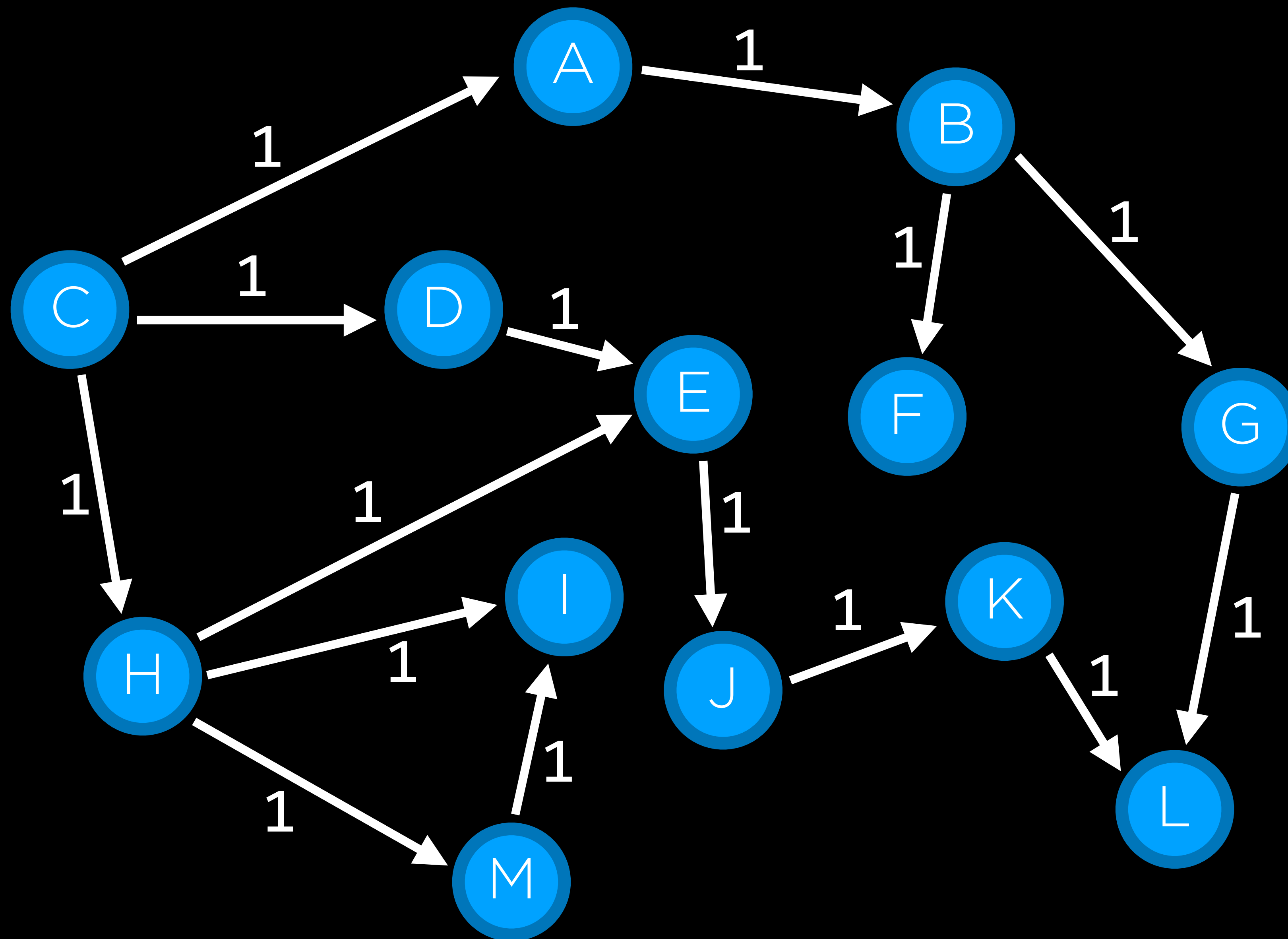
way to determine whether a given state
is a goal state

path cost

numerical cost associated with a given path







Search Problems

- initial state
- actions
- transition model
- goal test
- path cost function

solution

a sequence of actions that leads from the initial state to a goal state

optimal solution

a solution that has the lowest path cost
among all solutions

node

a data structure that keeps track of

- a **state**
- a **parent** (node that generated this node)
- an **action** (action applied to parent to get node)
- a **path cost** (from initial state to node)

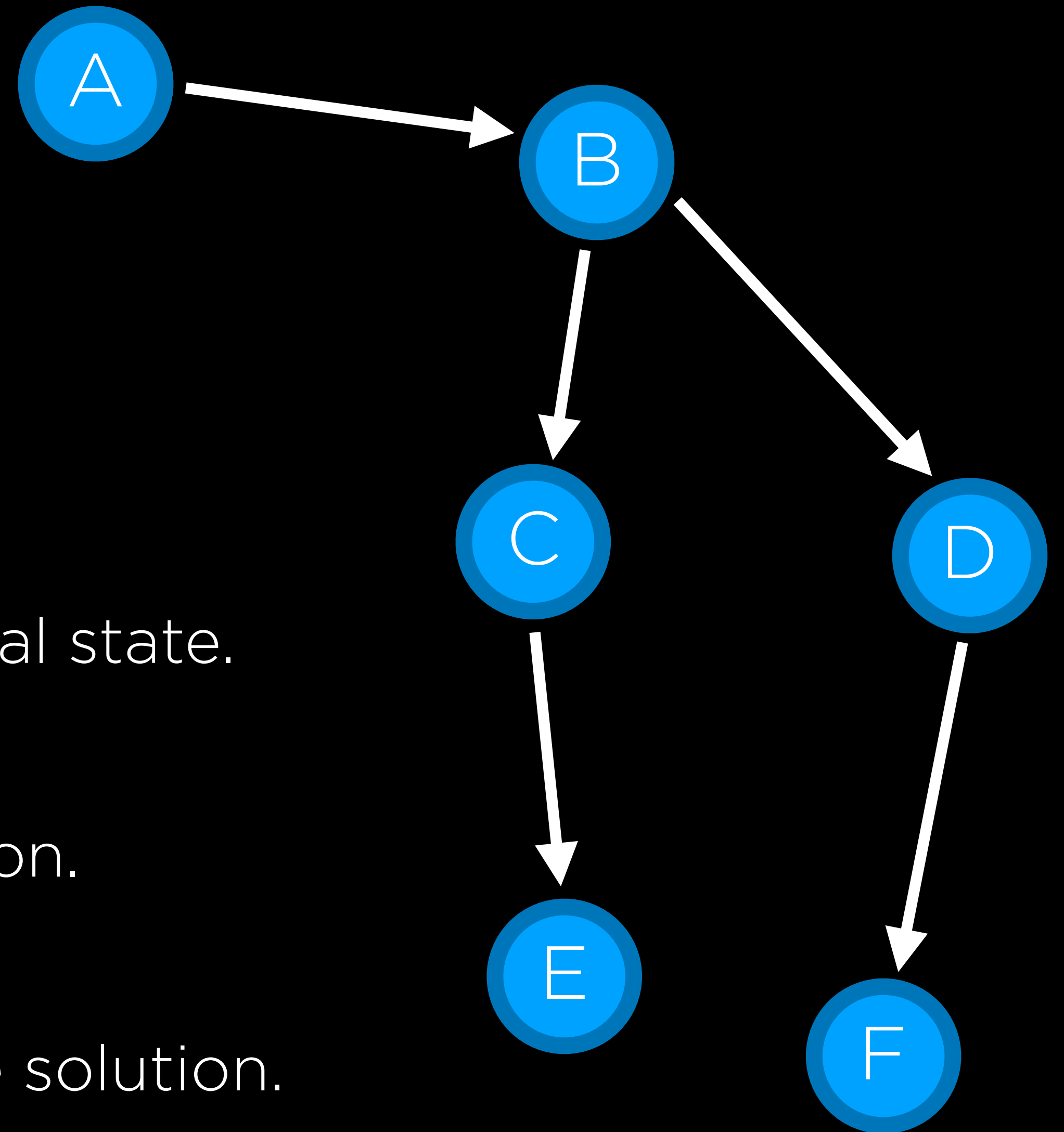
Approach

- Start with a **frontier** that contains the initial state.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - **Expand** node, add resulting nodes to the frontier.

Find a path from A to E.

Frontier

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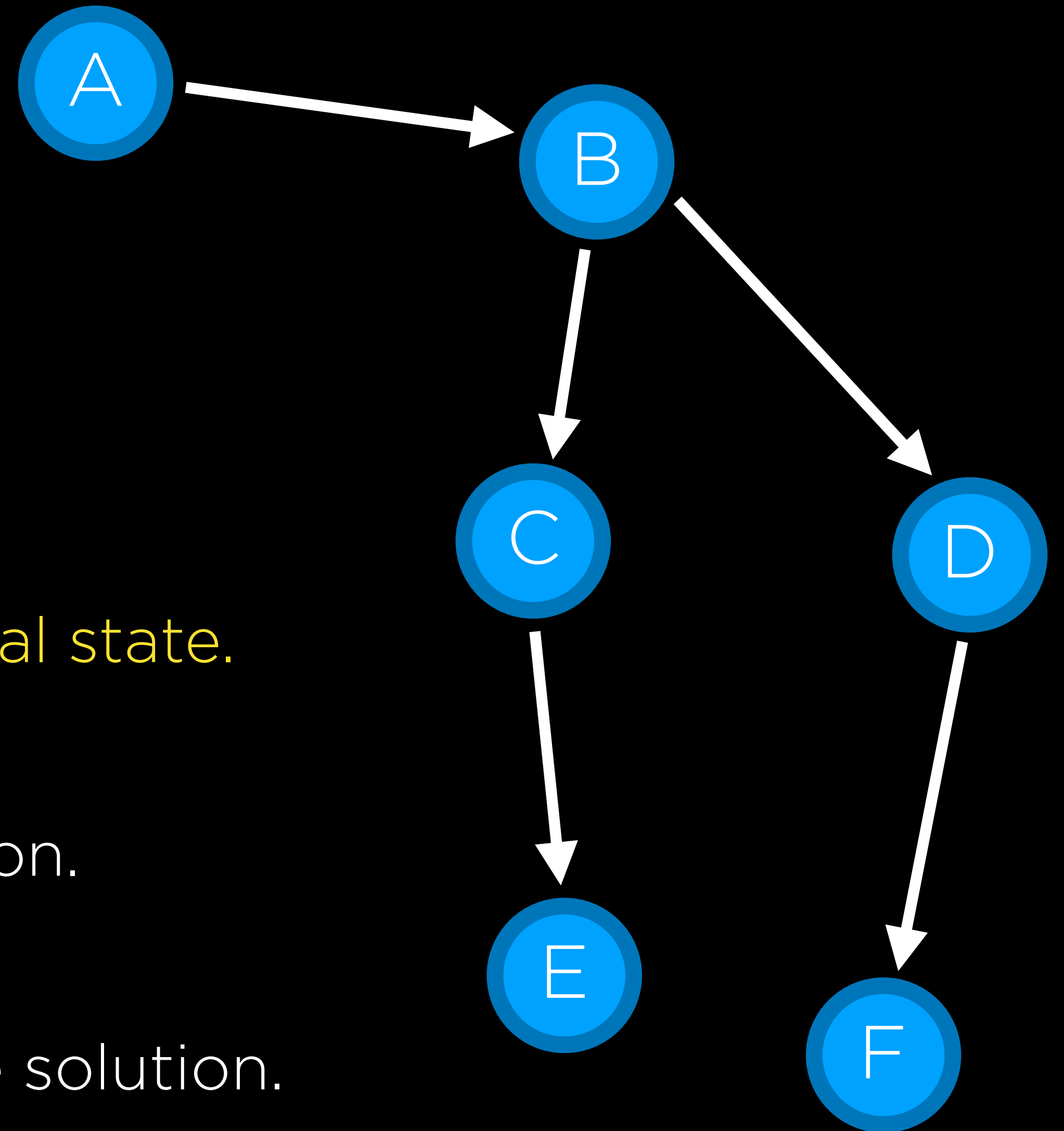


Find a path from A to E.

Frontier



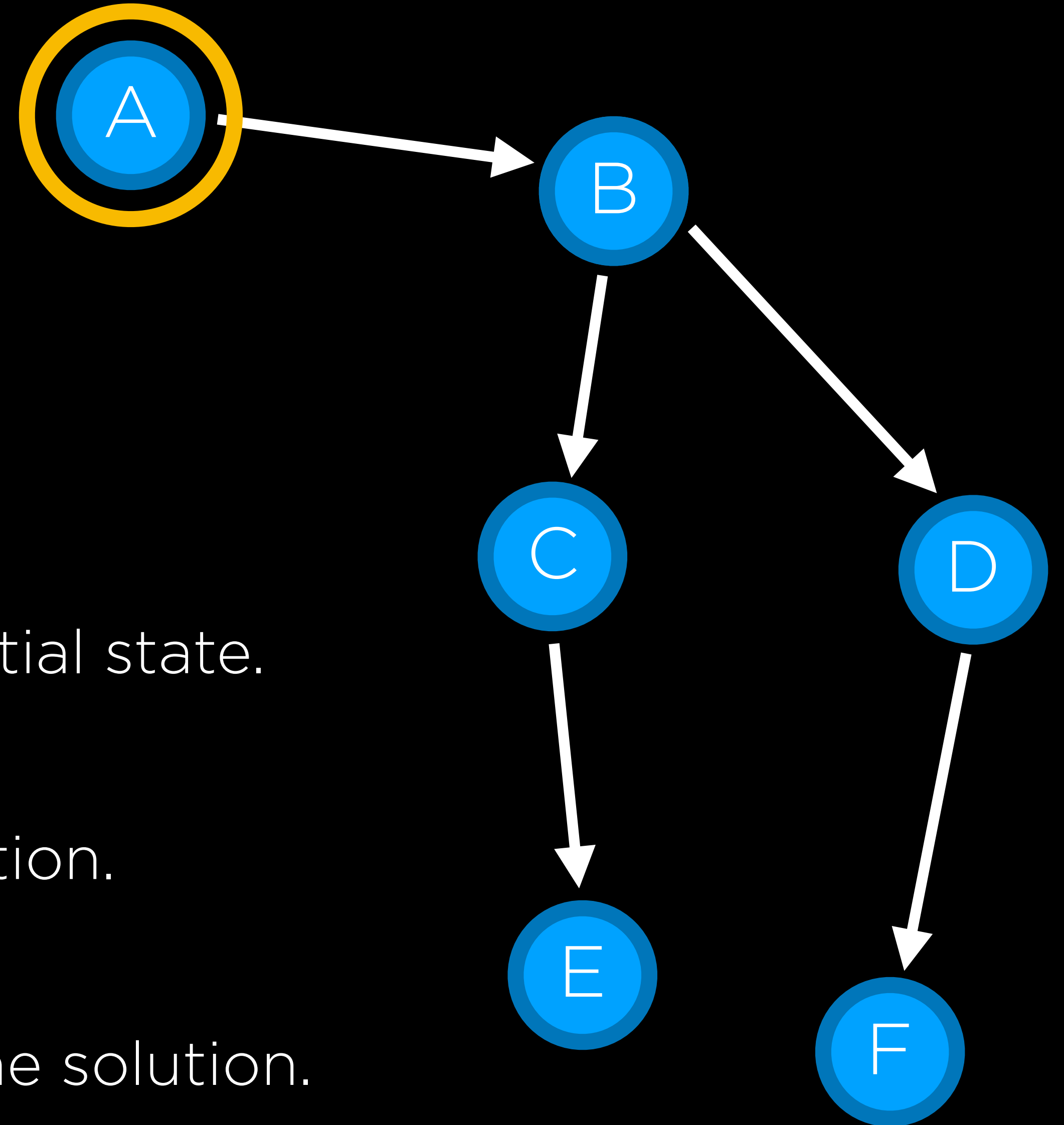
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Find a path from A to E.

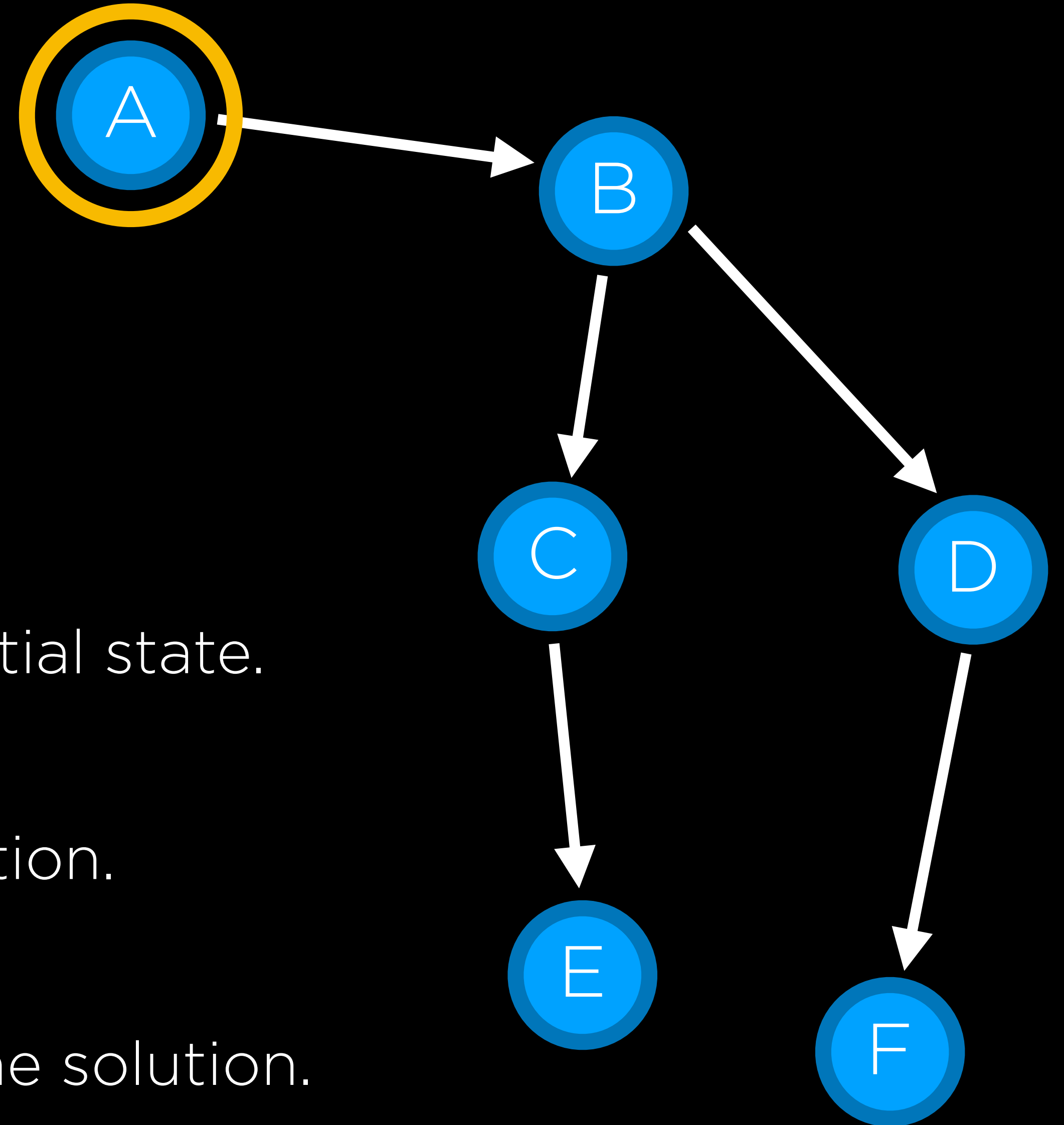
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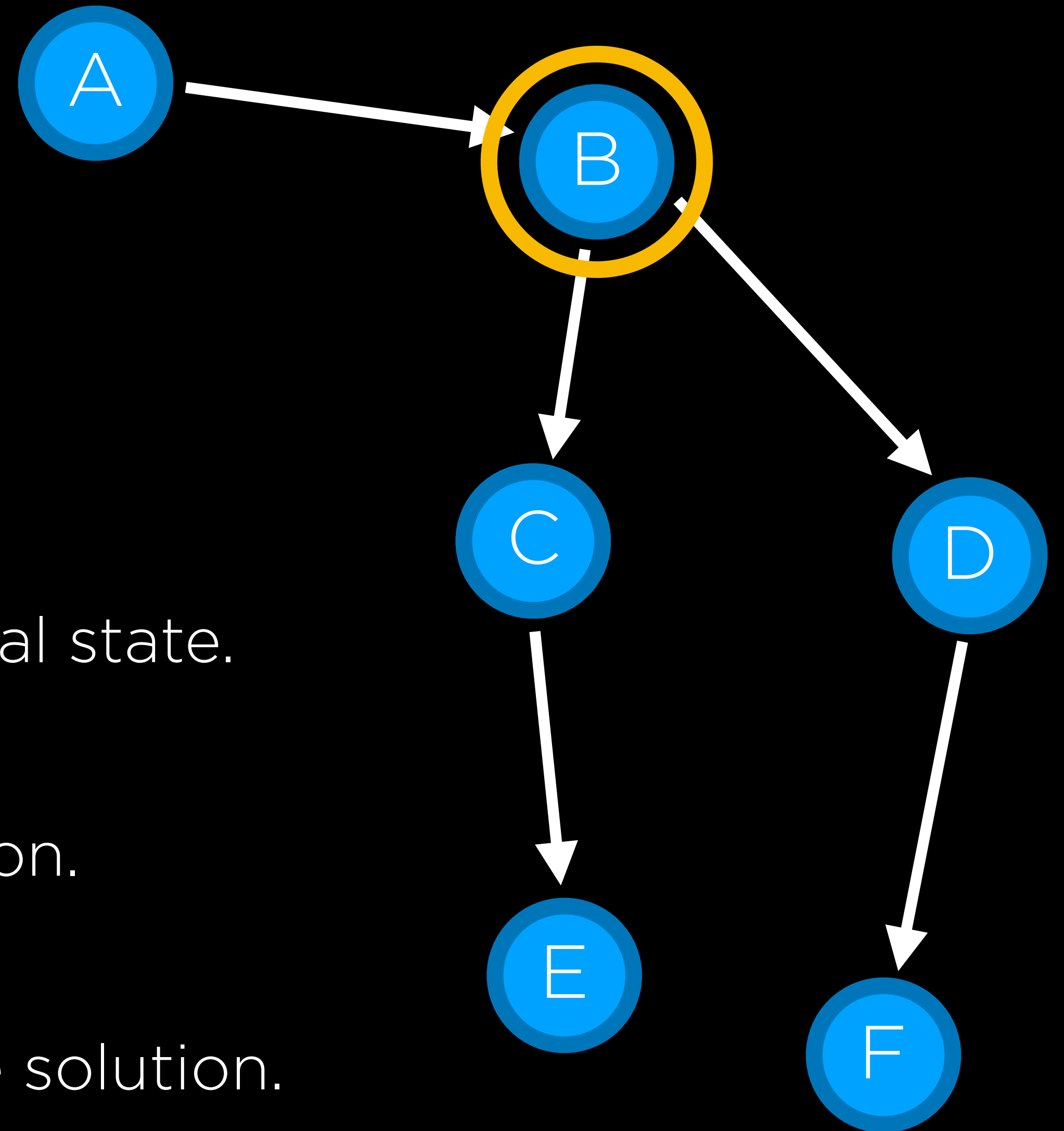


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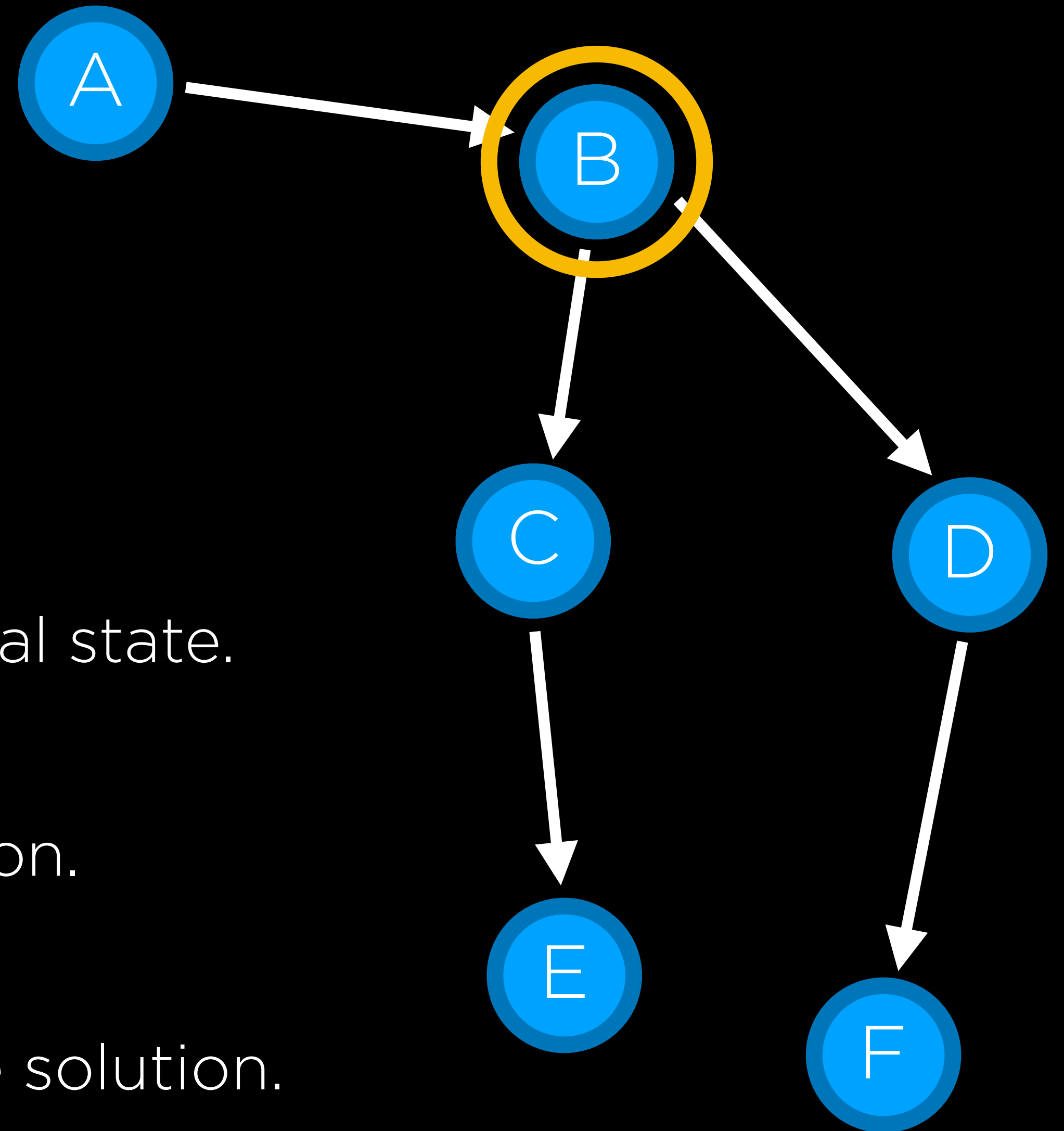
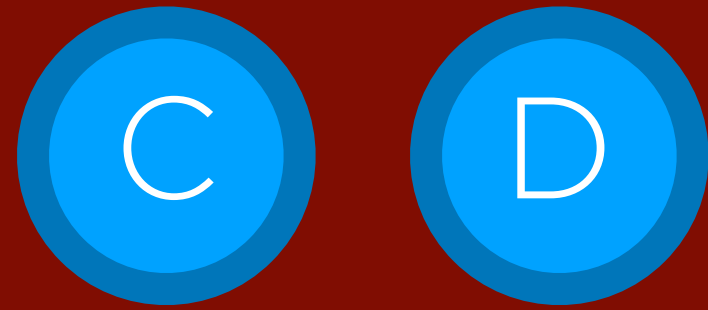
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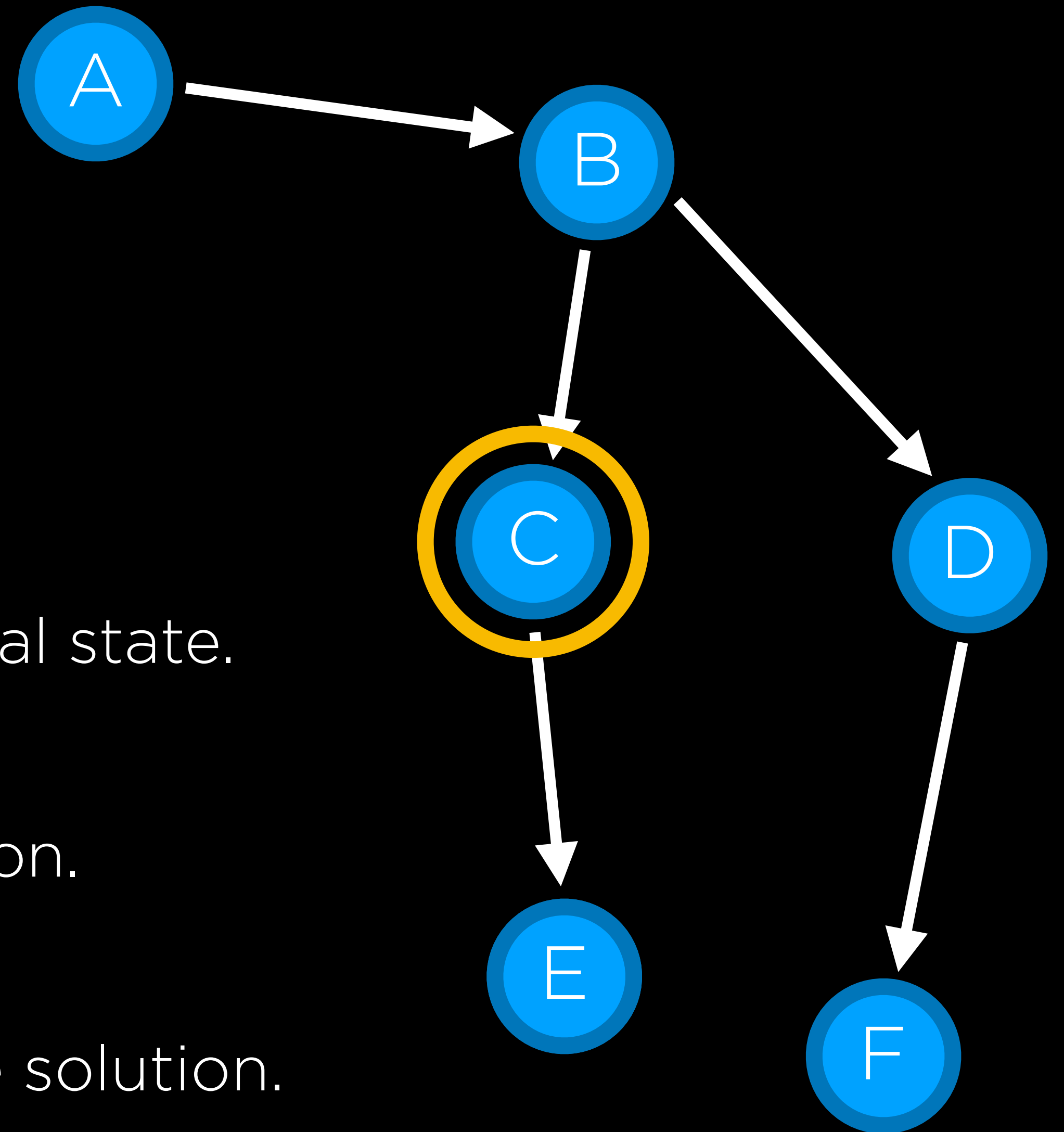
Find a path from A to E.

Frontier



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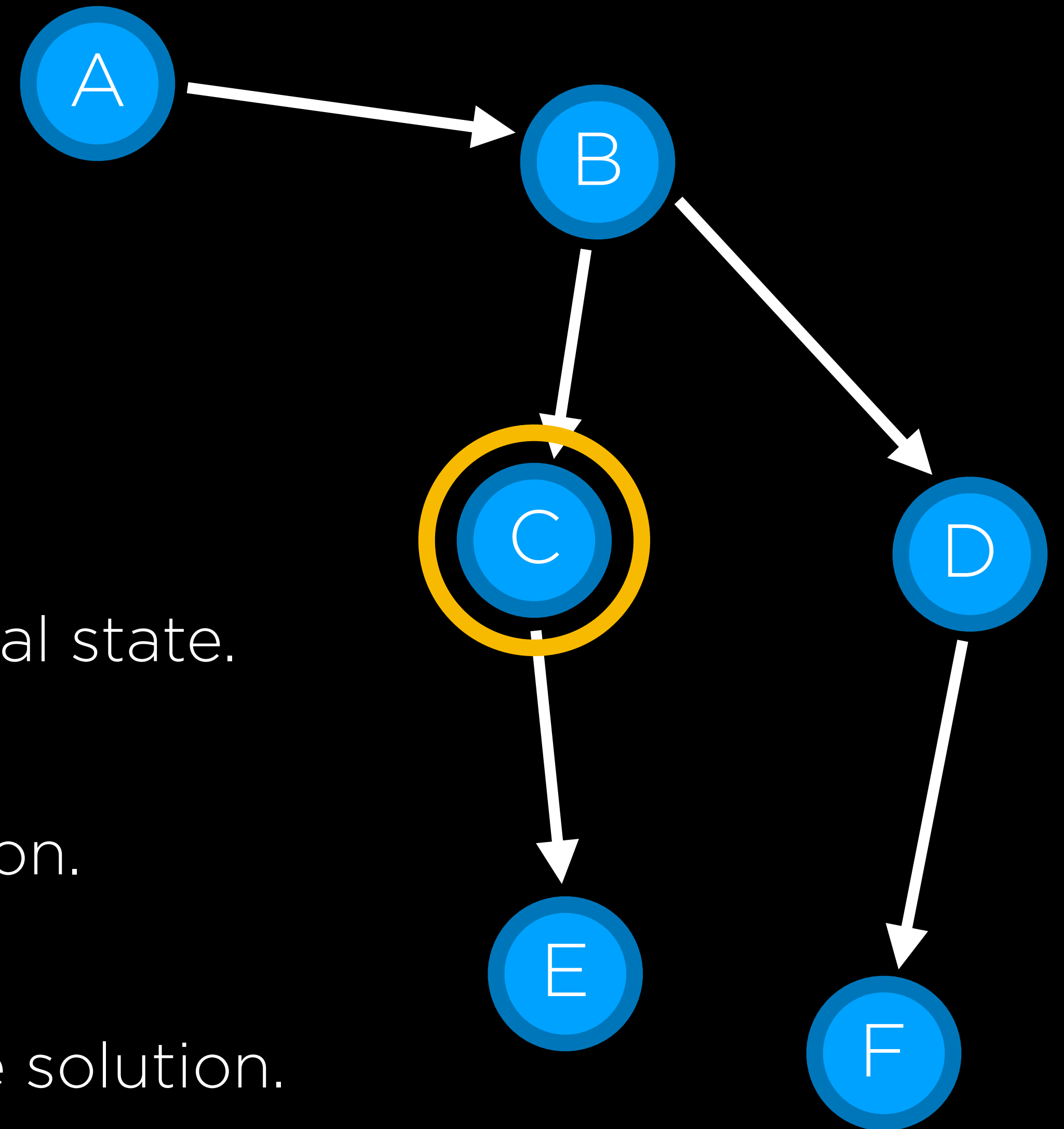
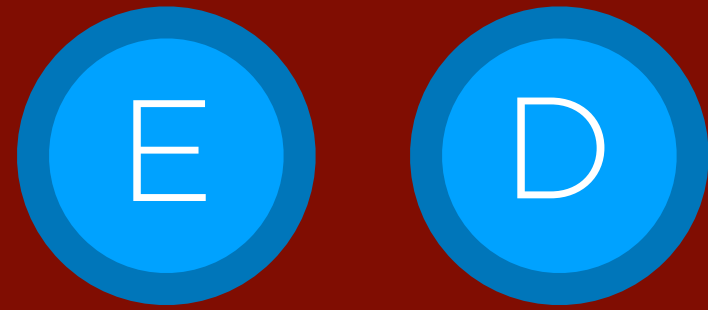
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Find a path from A to E.

Frontier



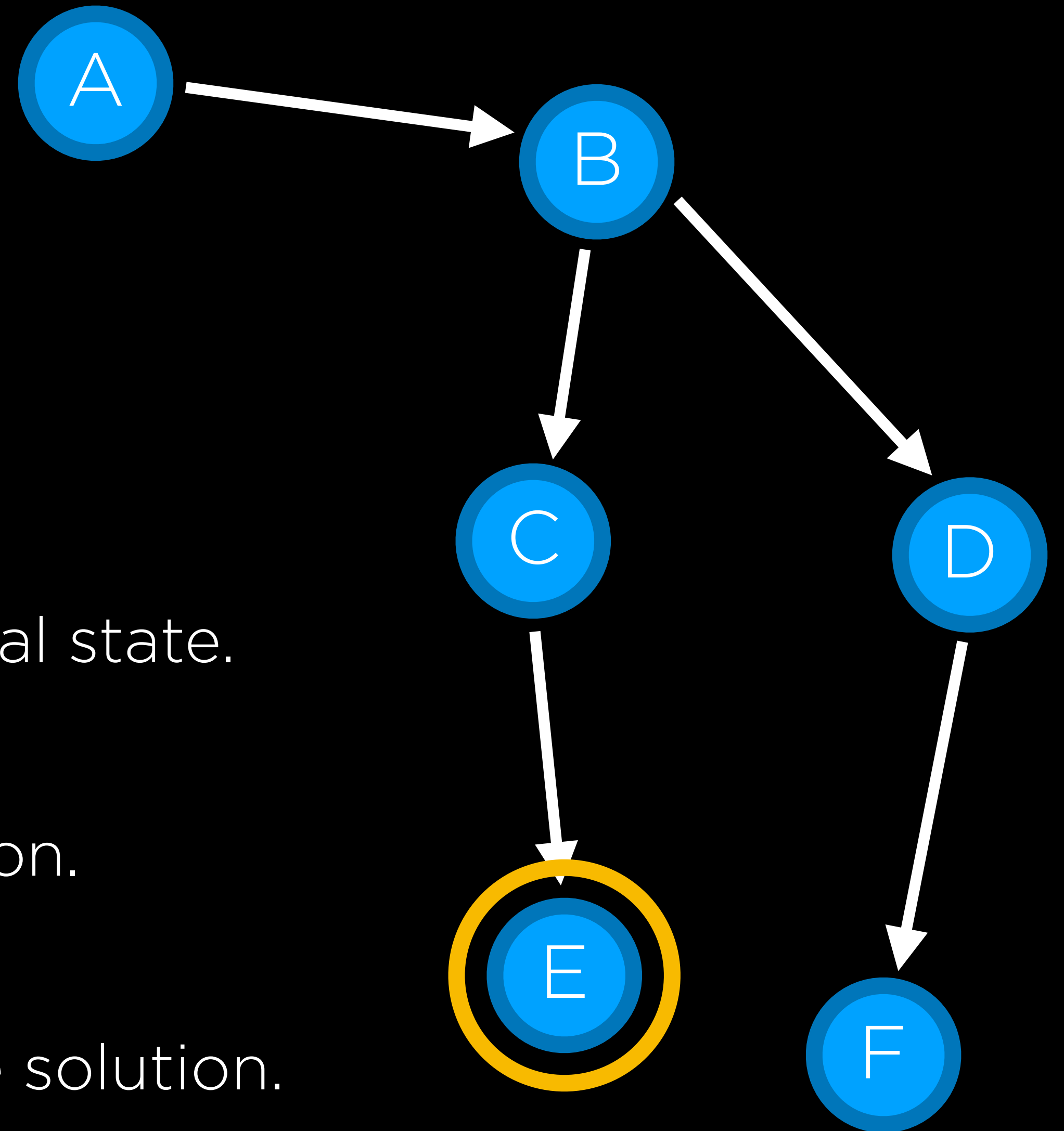
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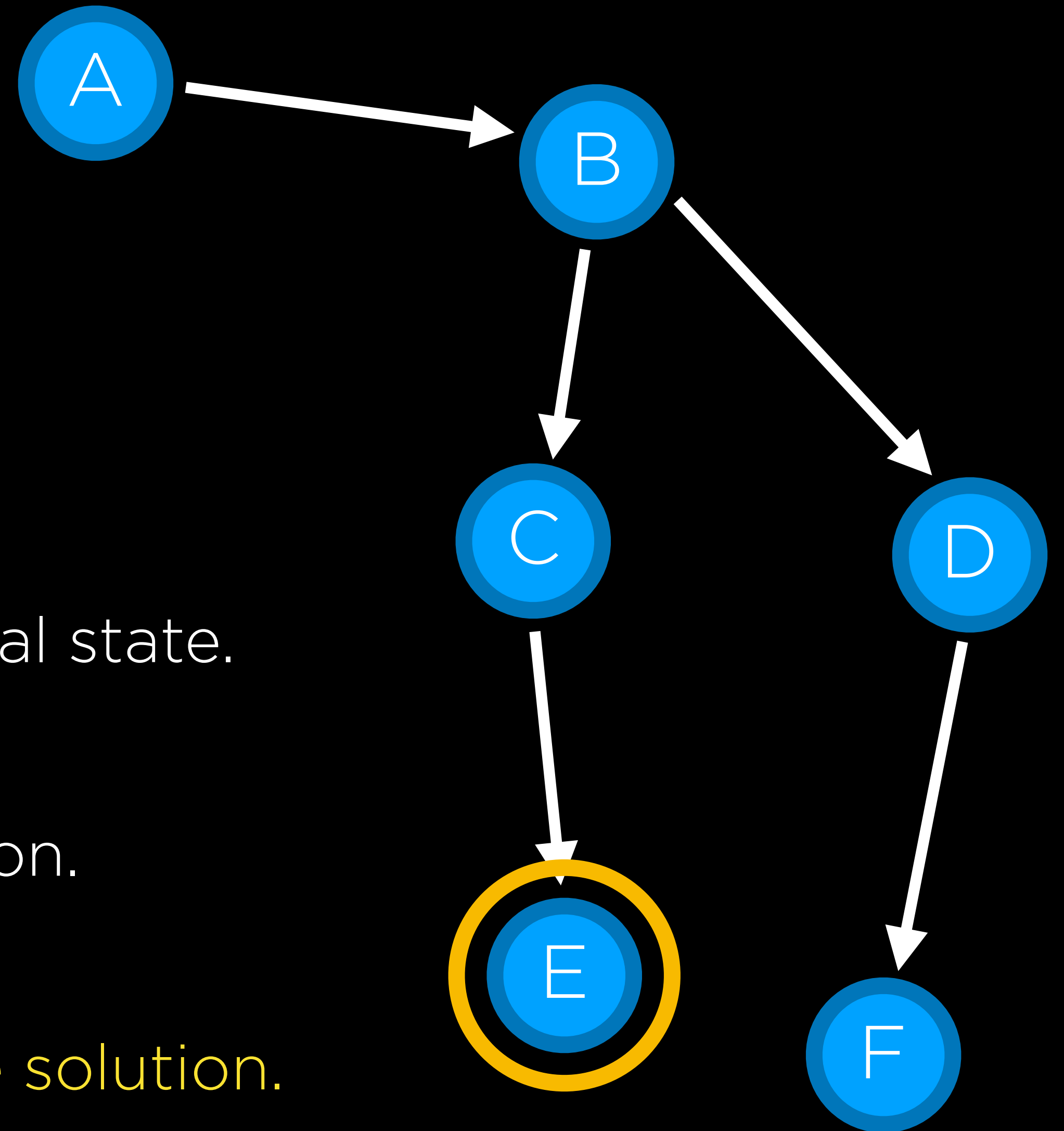


Find a path from A to E.

Frontier



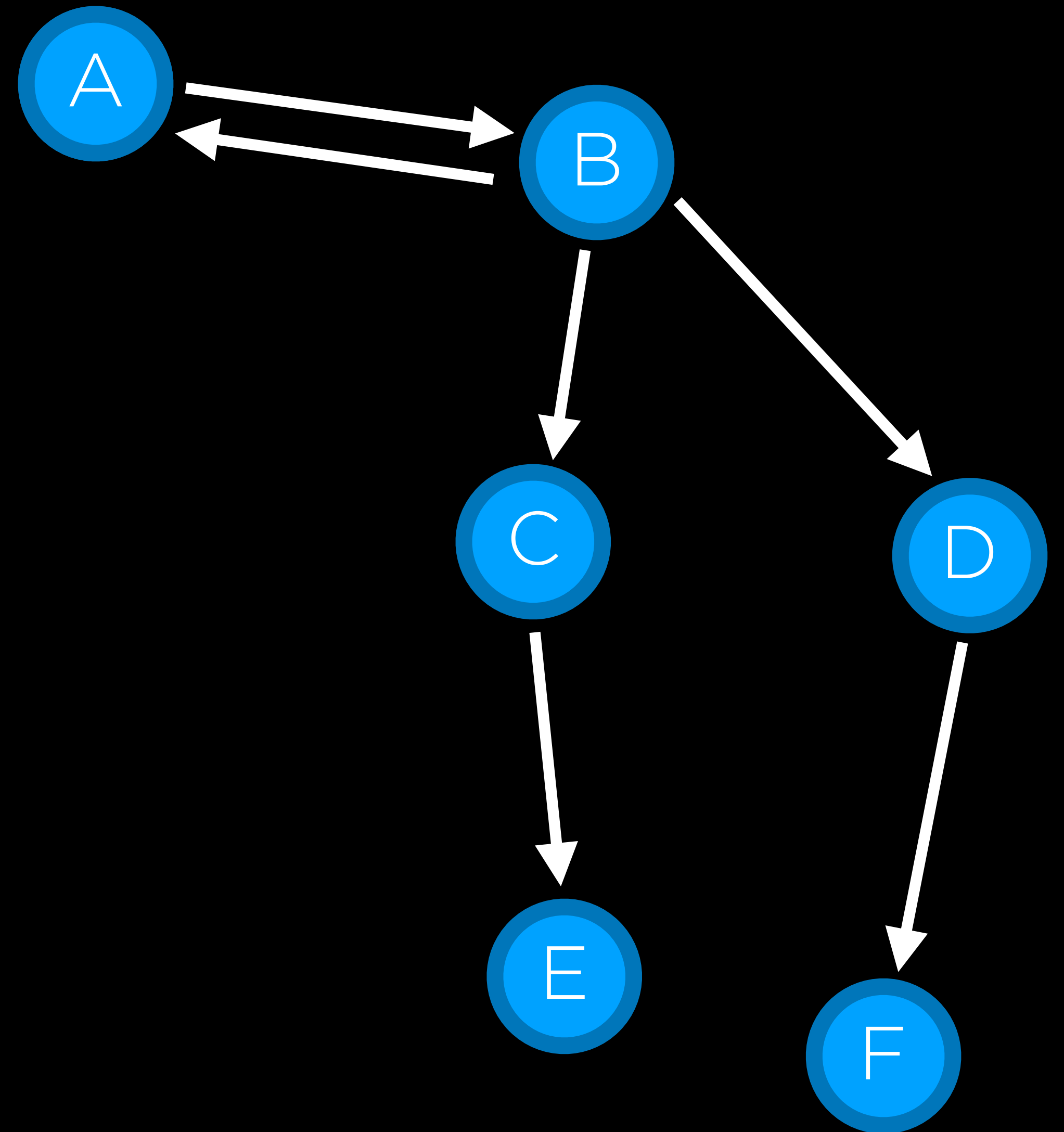
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What could go wrong?

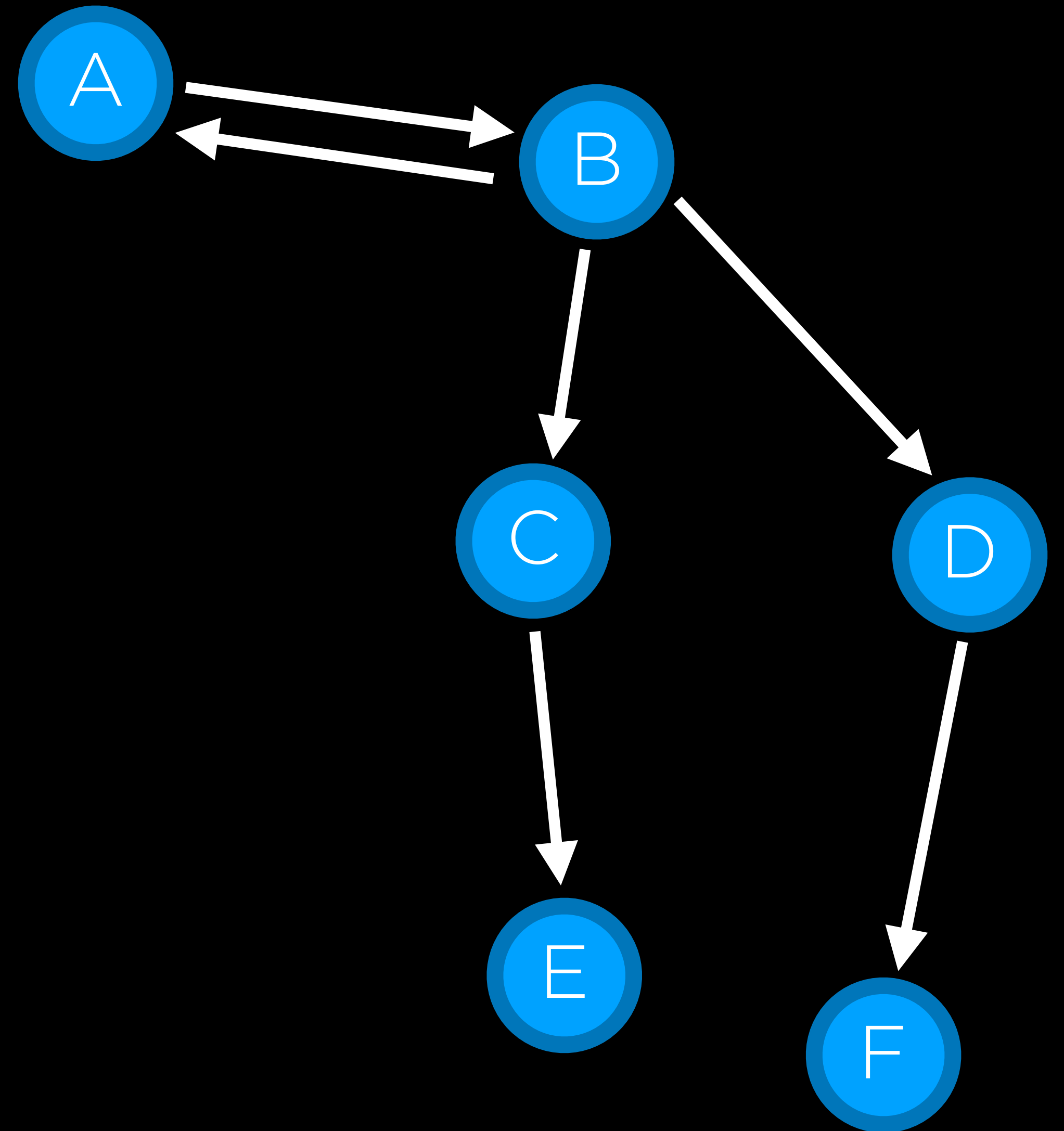
Find a path from A to E.

Frontier



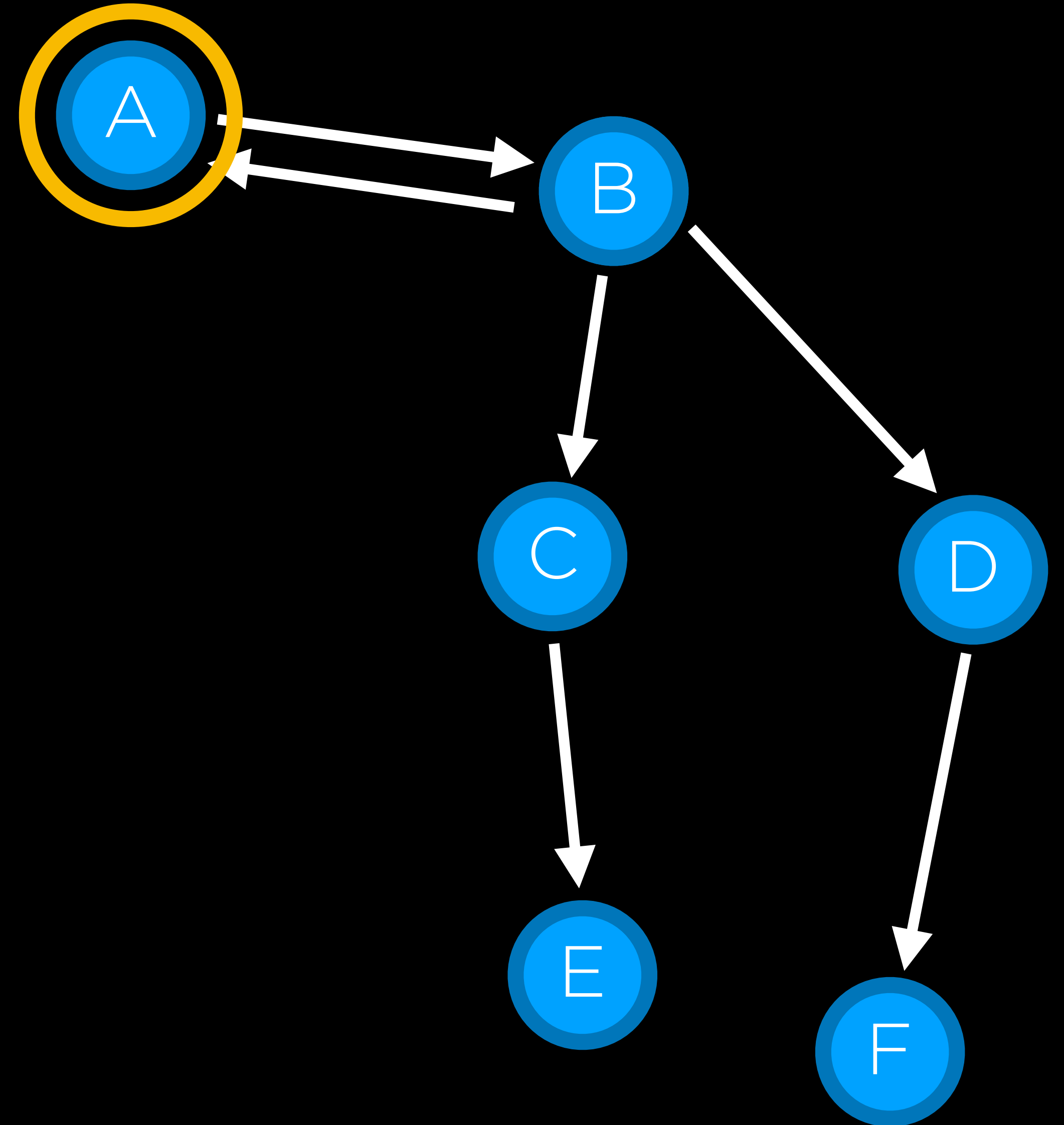
Find a path from A to E.

Frontier



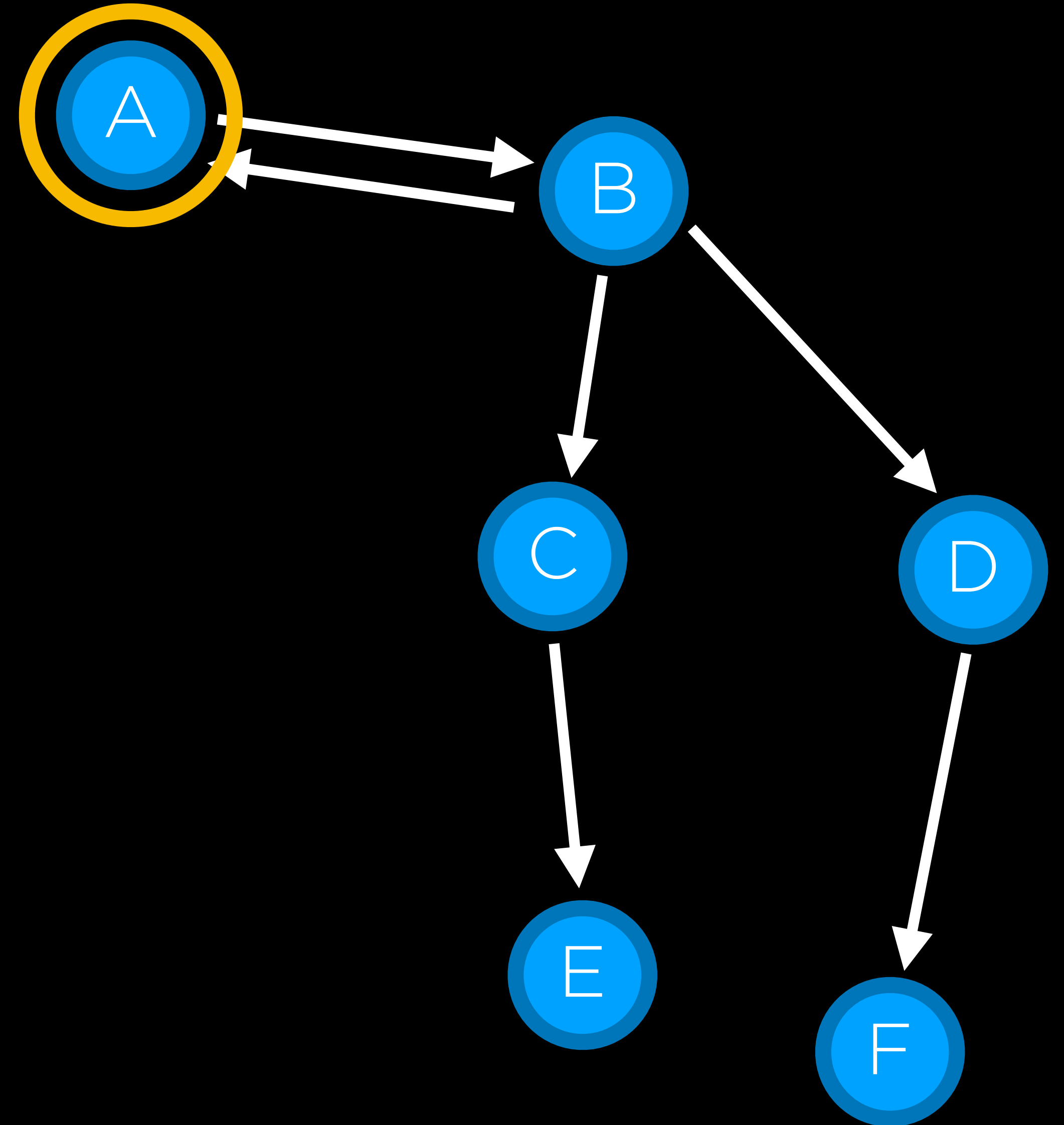
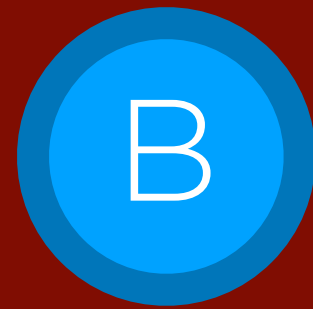
Find a path from A to E.

Frontier



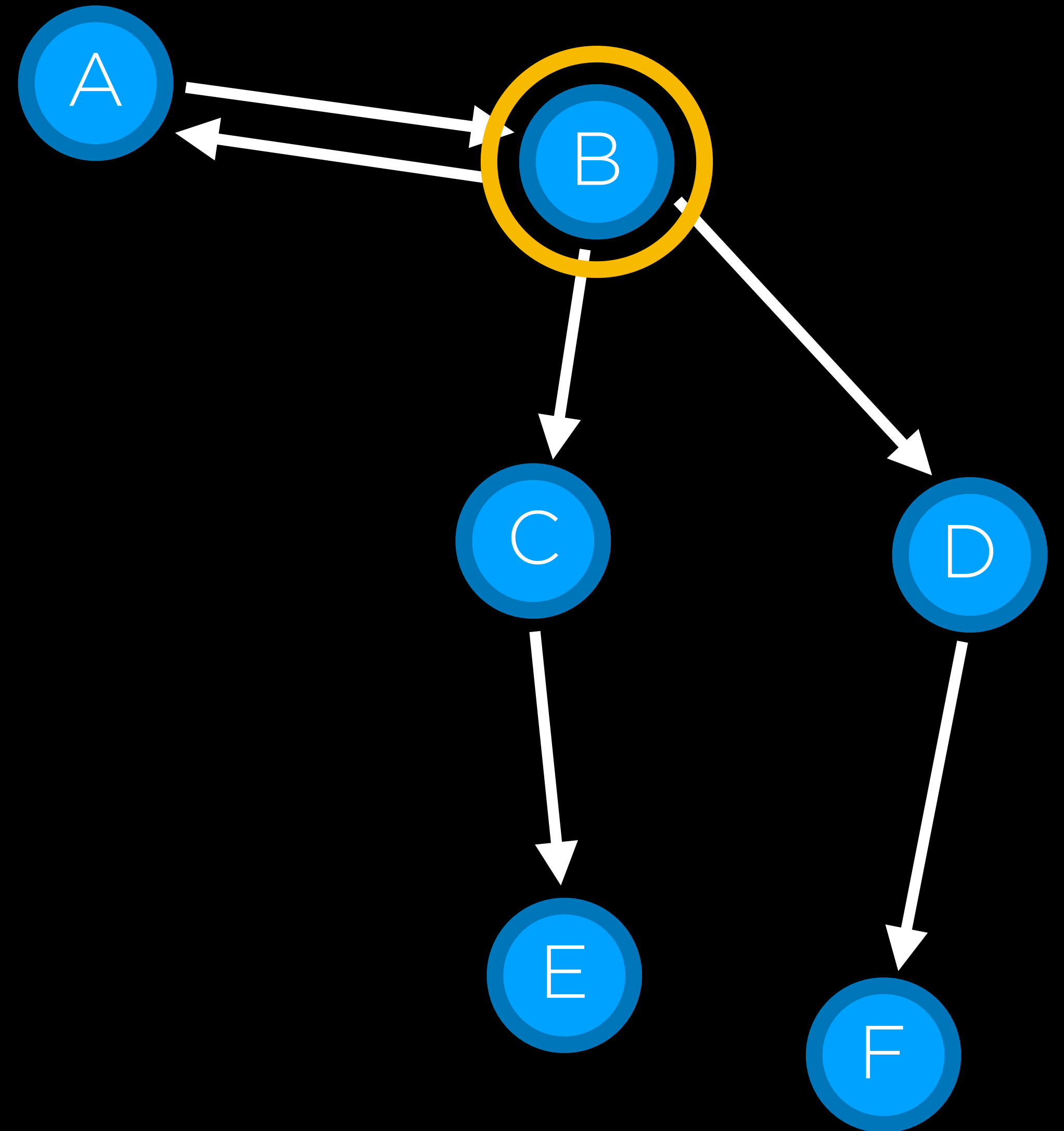
Find a path from A to E.

Frontier



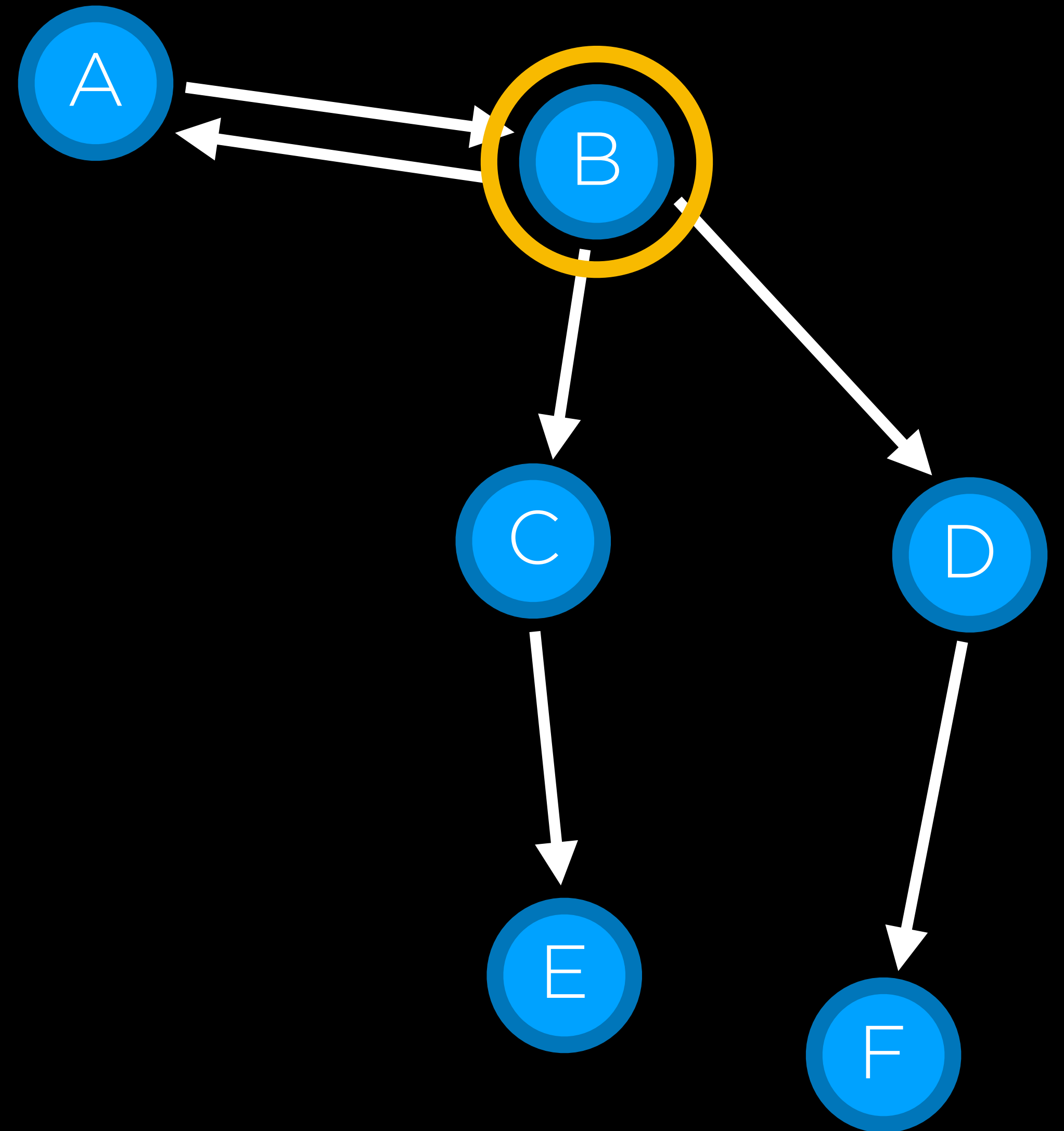
Find a path from A to E.

Frontier



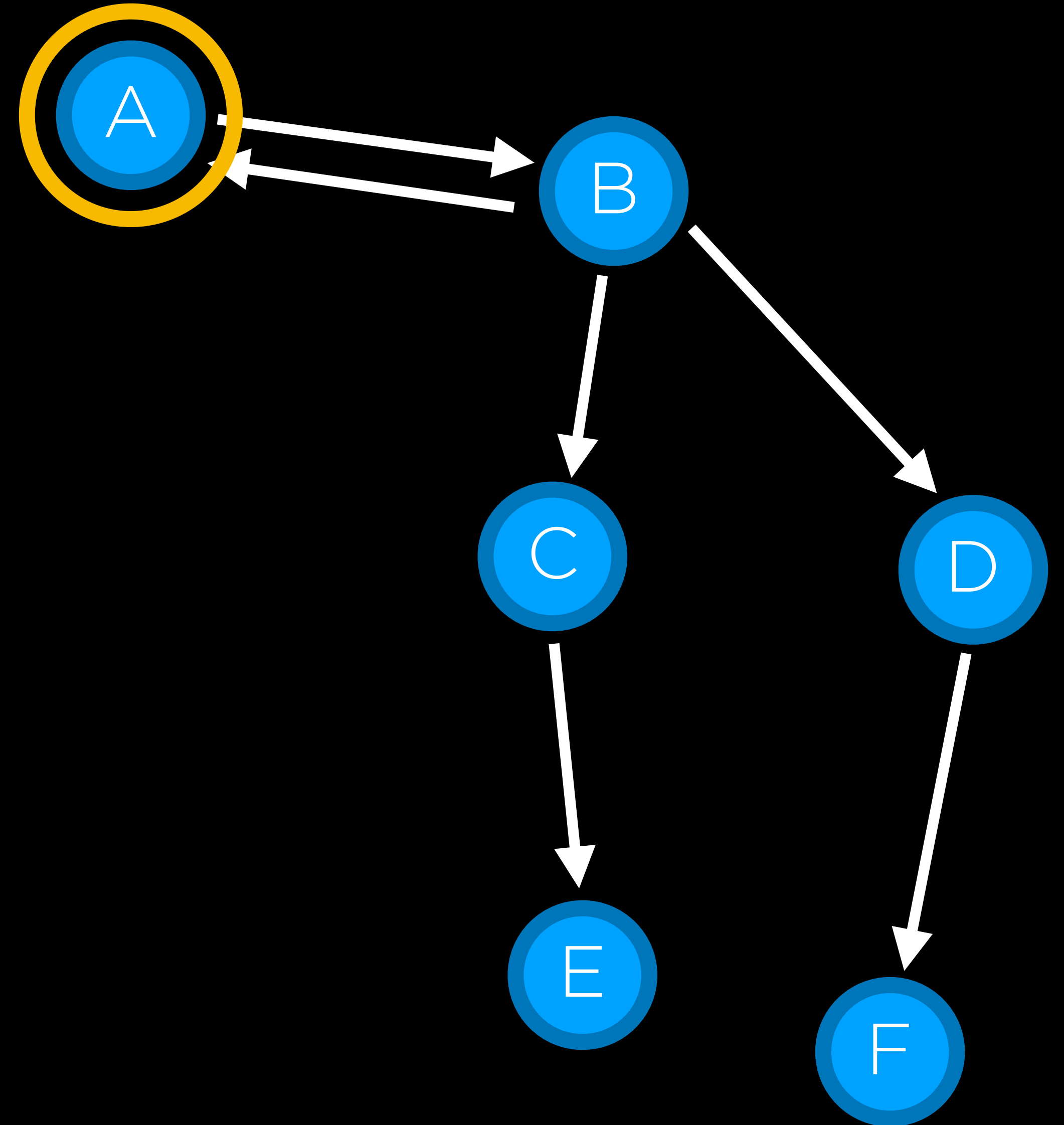
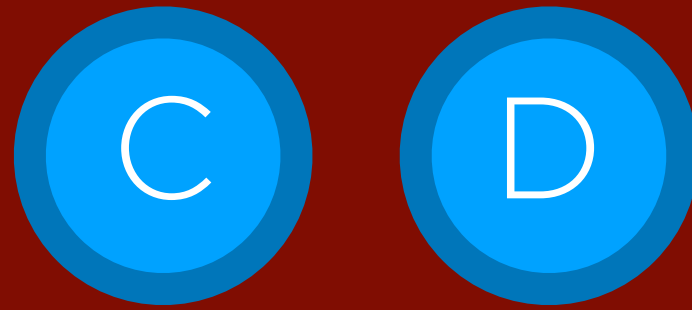
Find a path from A to E.

Frontier



Find a path from A to E.

Frontier



Revised Approach

- Start with a **frontier** that contains the initial state.
- Start with an empty **explored set**.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - Add the node to the explored set.
 - **Expand** node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

Revised Approach

- Start with a **frontier** that contains the initial state.
- Start with an empty **explored set**.
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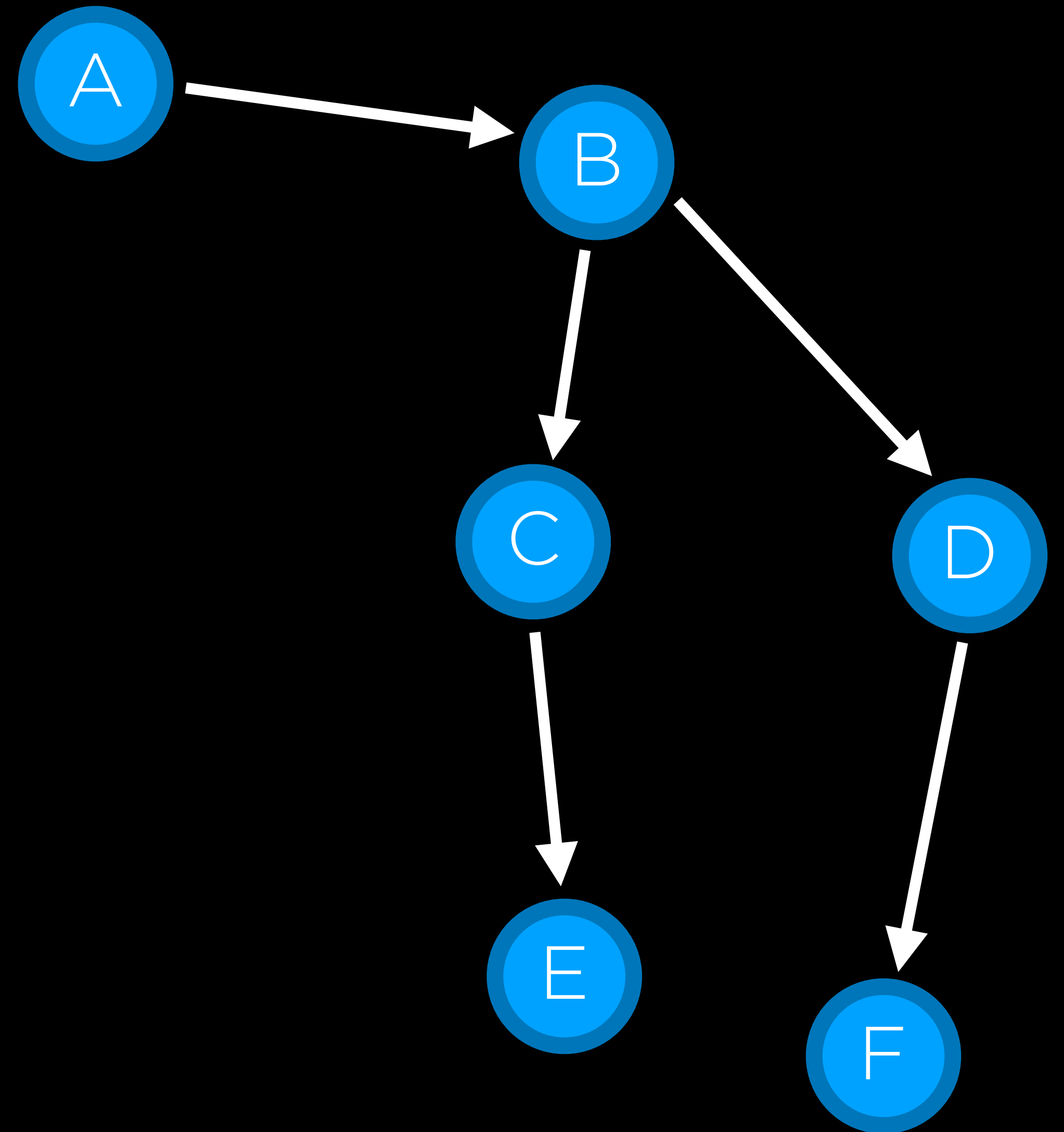
stack

last-in first-out data type

Find a path from A to E.

Frontier

Explored Set

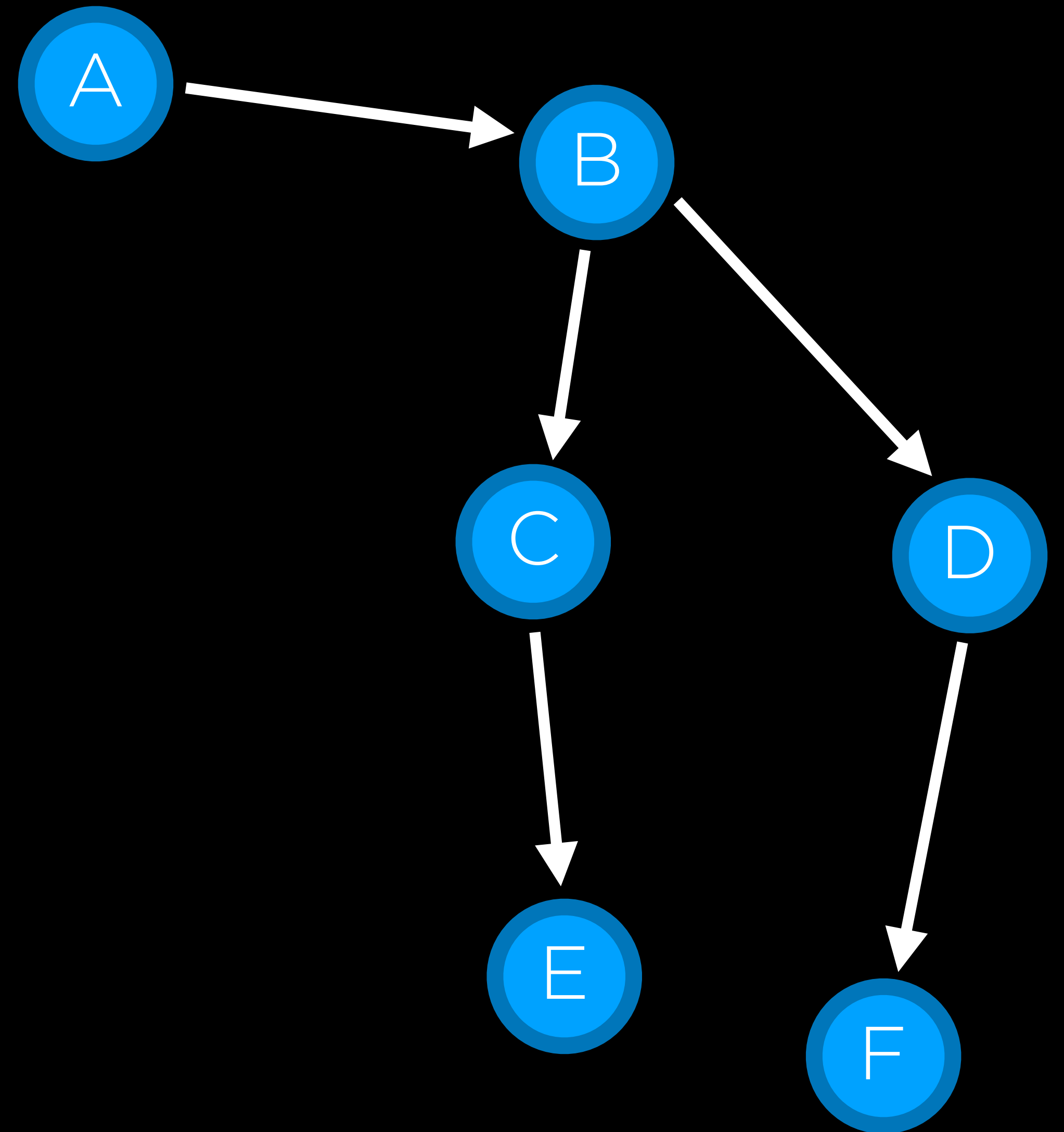


Find a path from A to E.

Frontier



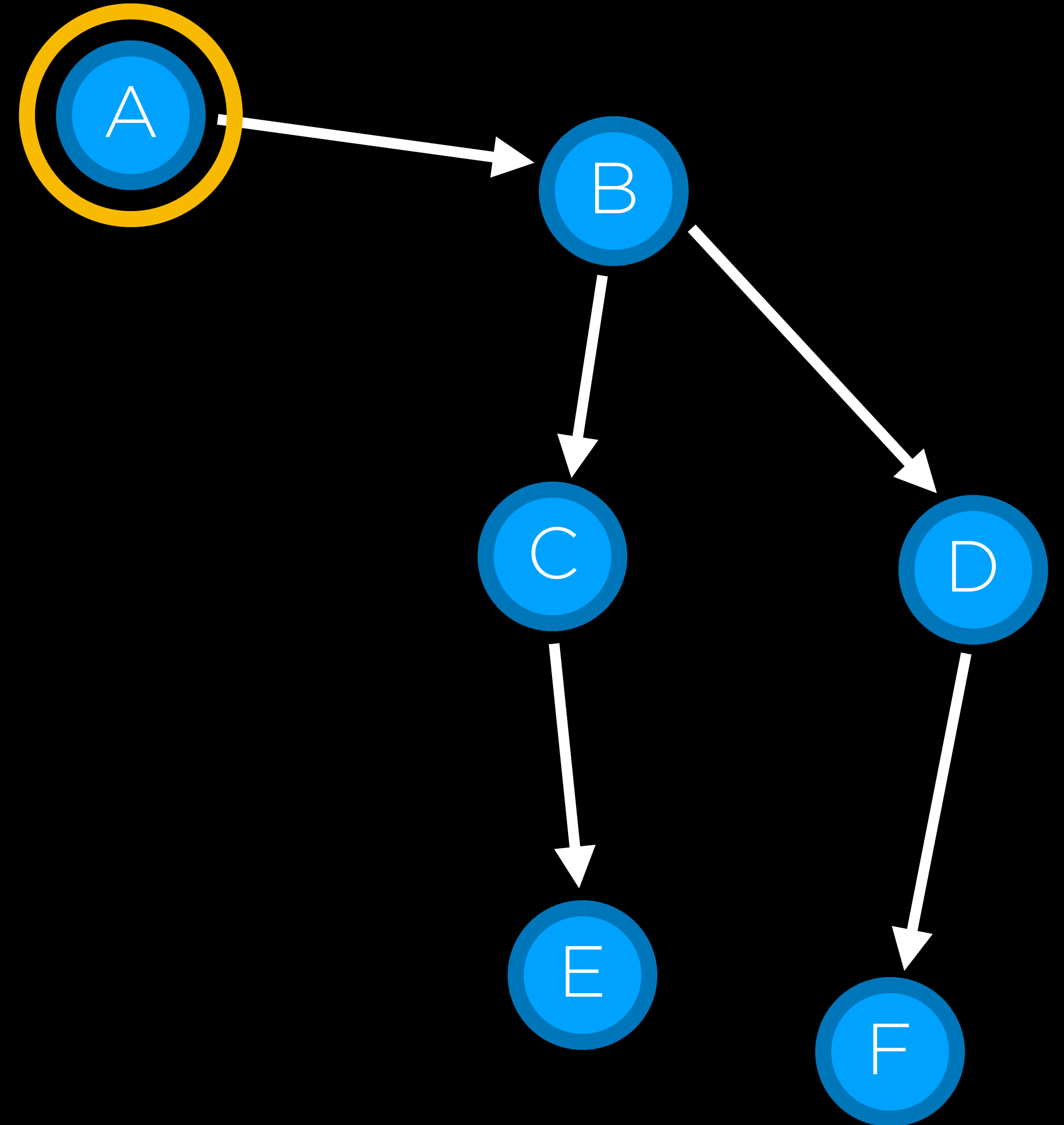
Explored Set



Find a path from A to E.

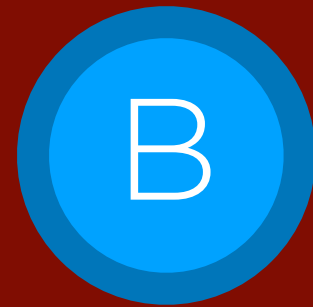
Frontier

Explored Set

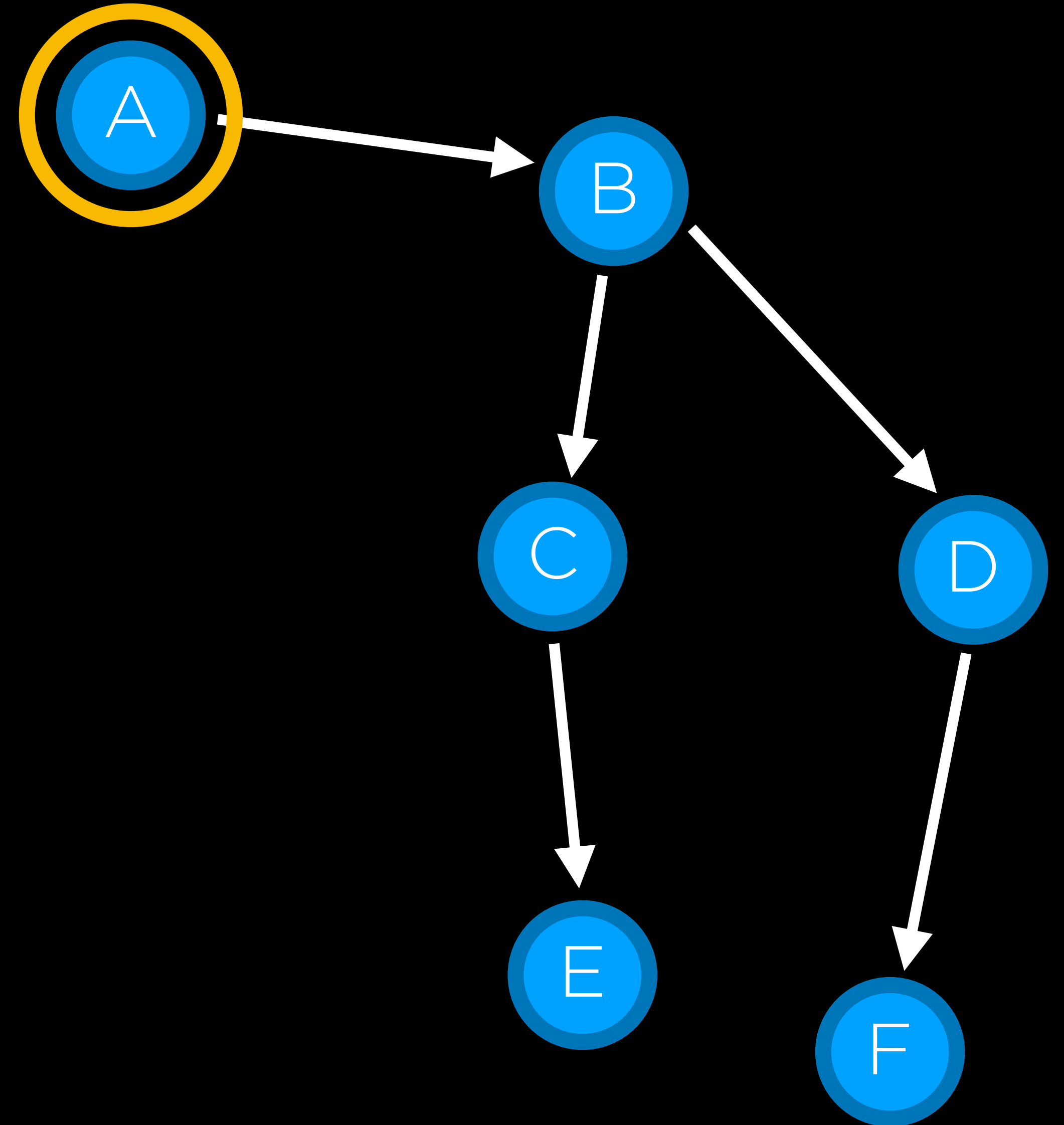


Find a path from A to E.

Frontier



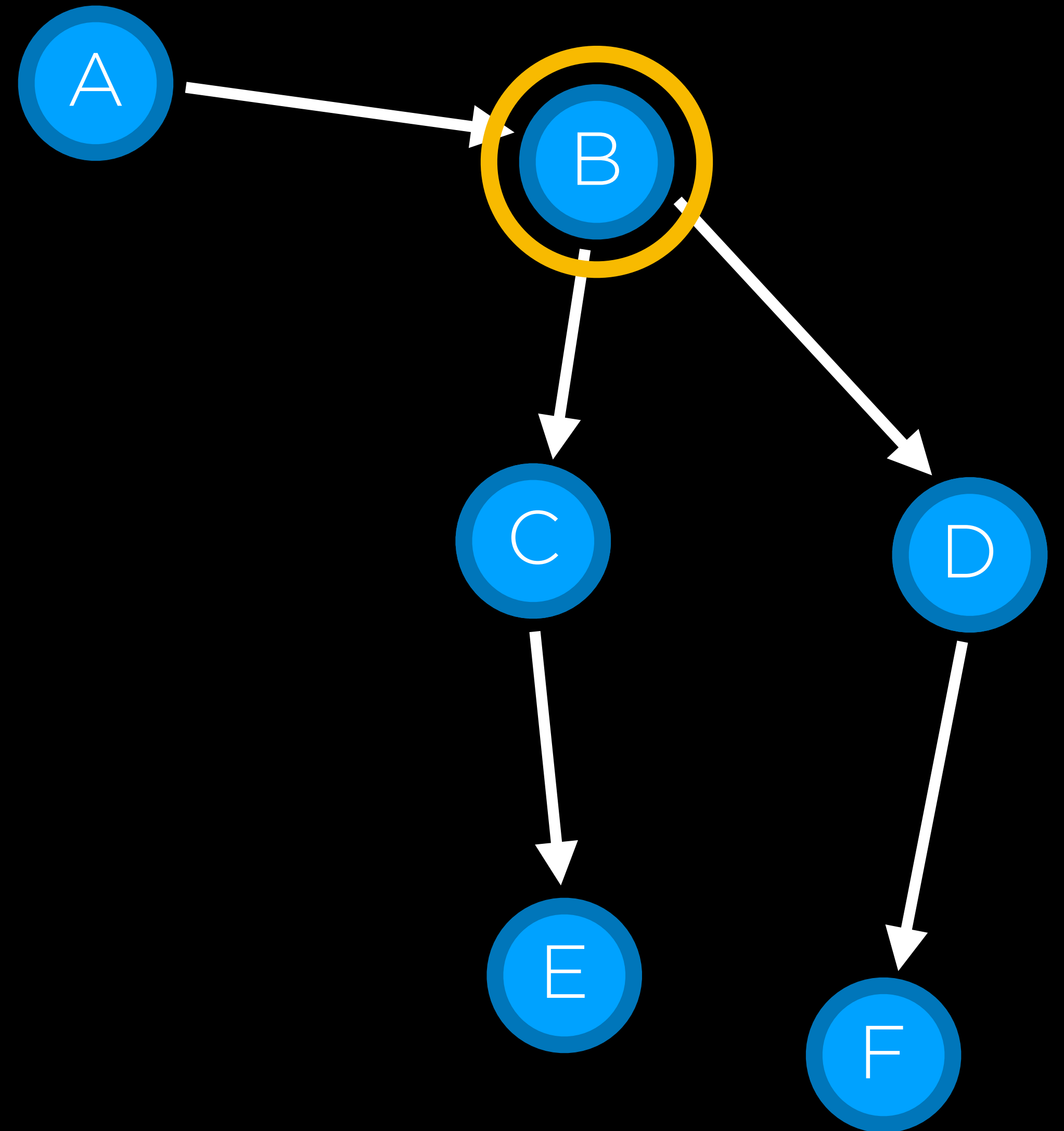
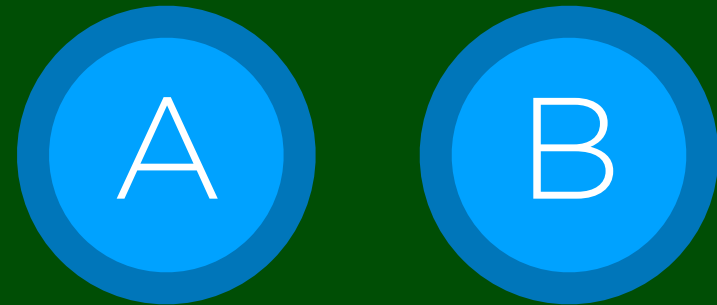
Explored Set



Find a path from A to E.

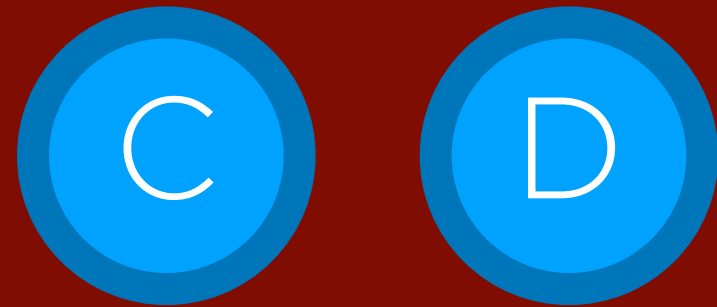
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Explored Set

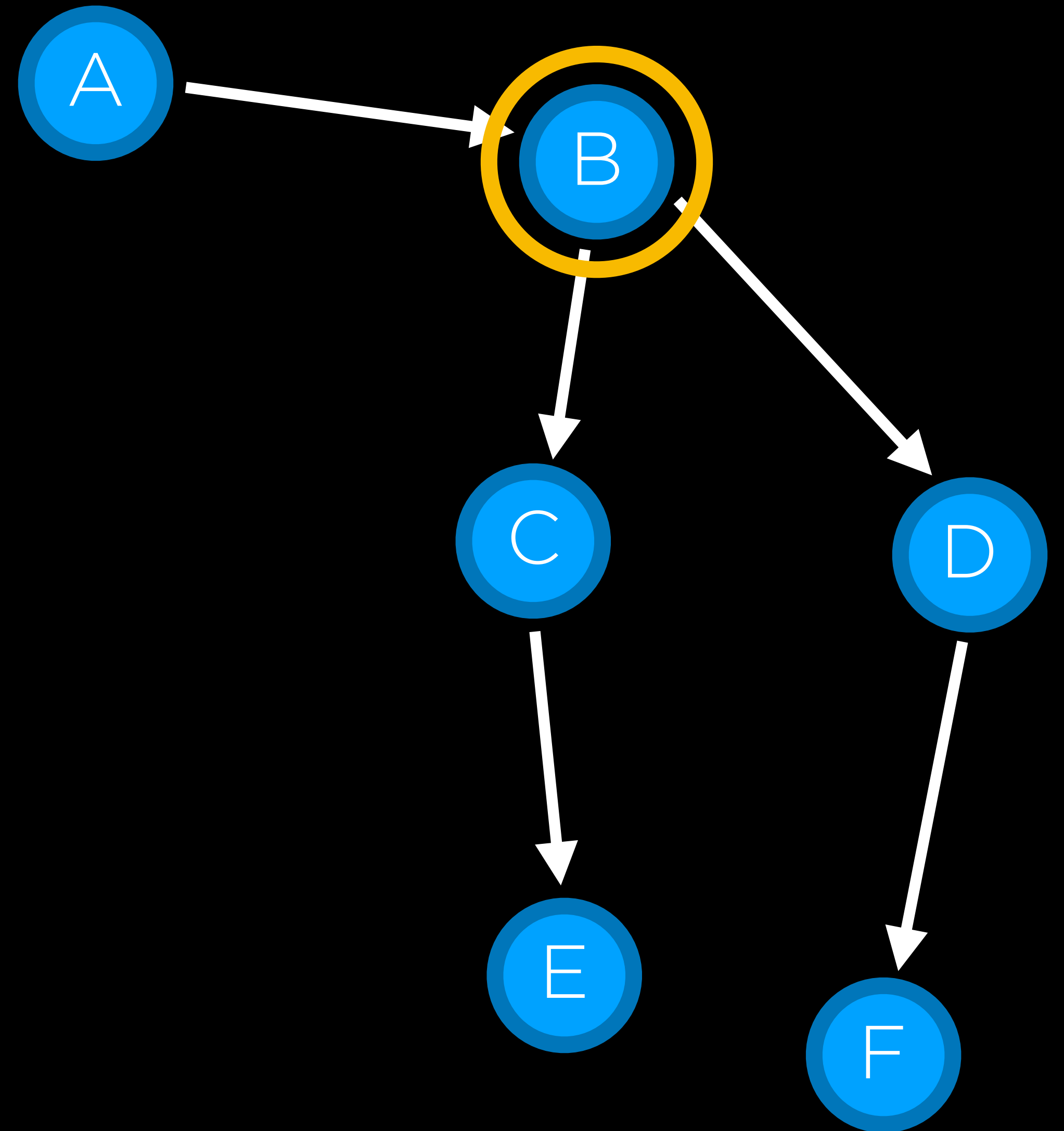


Find a path from A to E.

Frontier



Explored Set

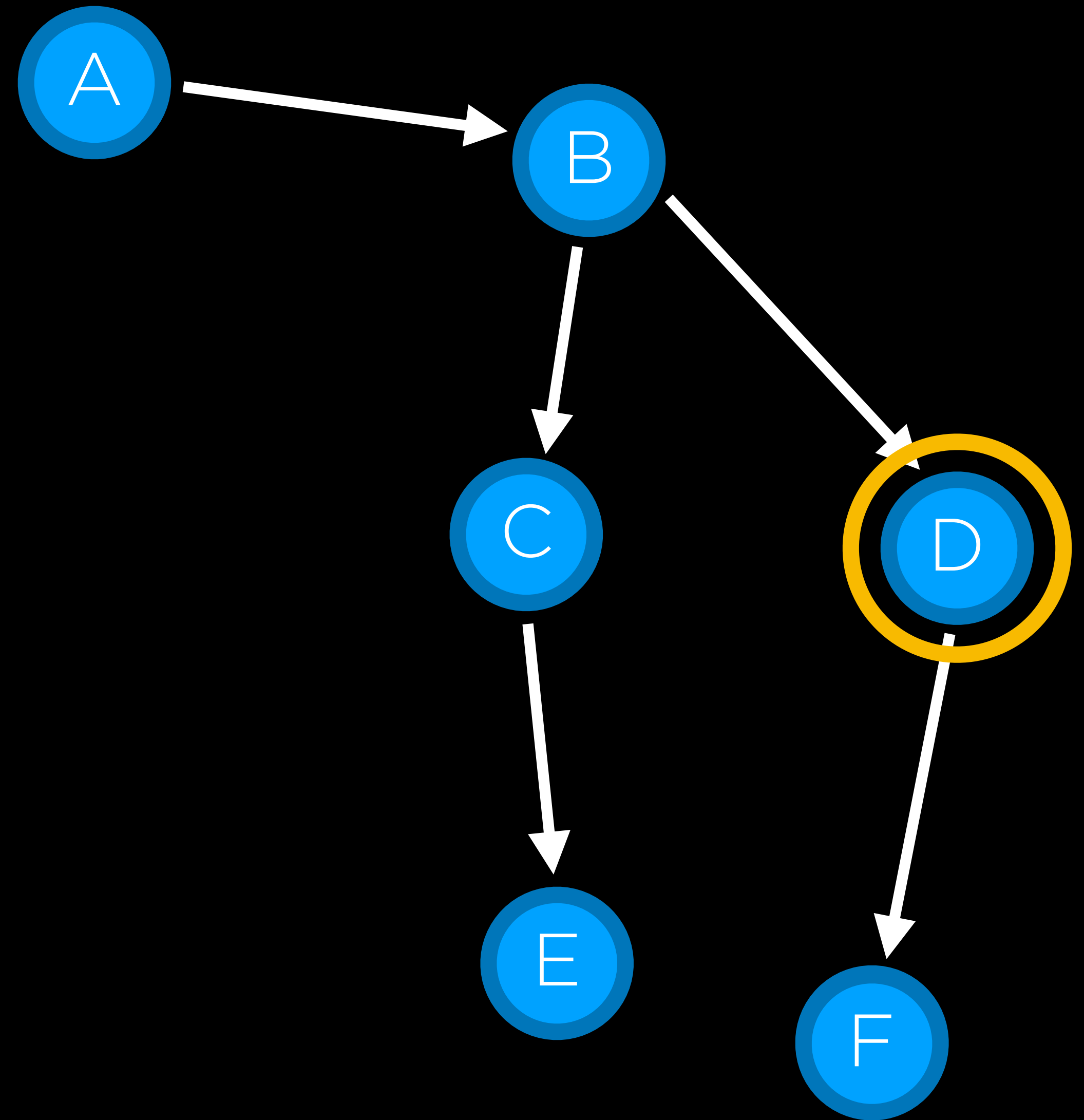
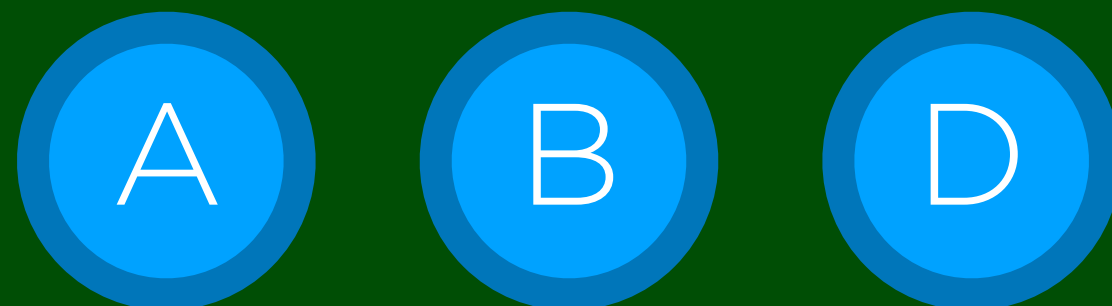


Find a path from A to E.

Frontier

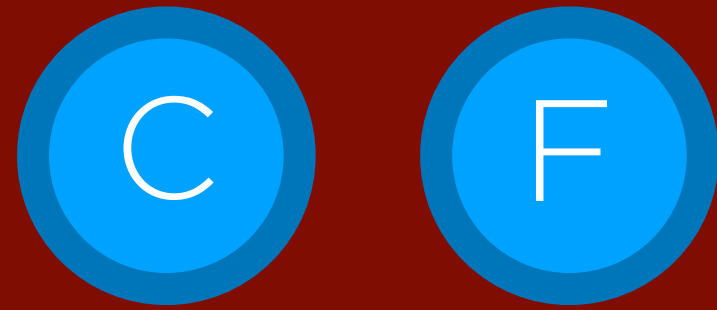


Explored Set

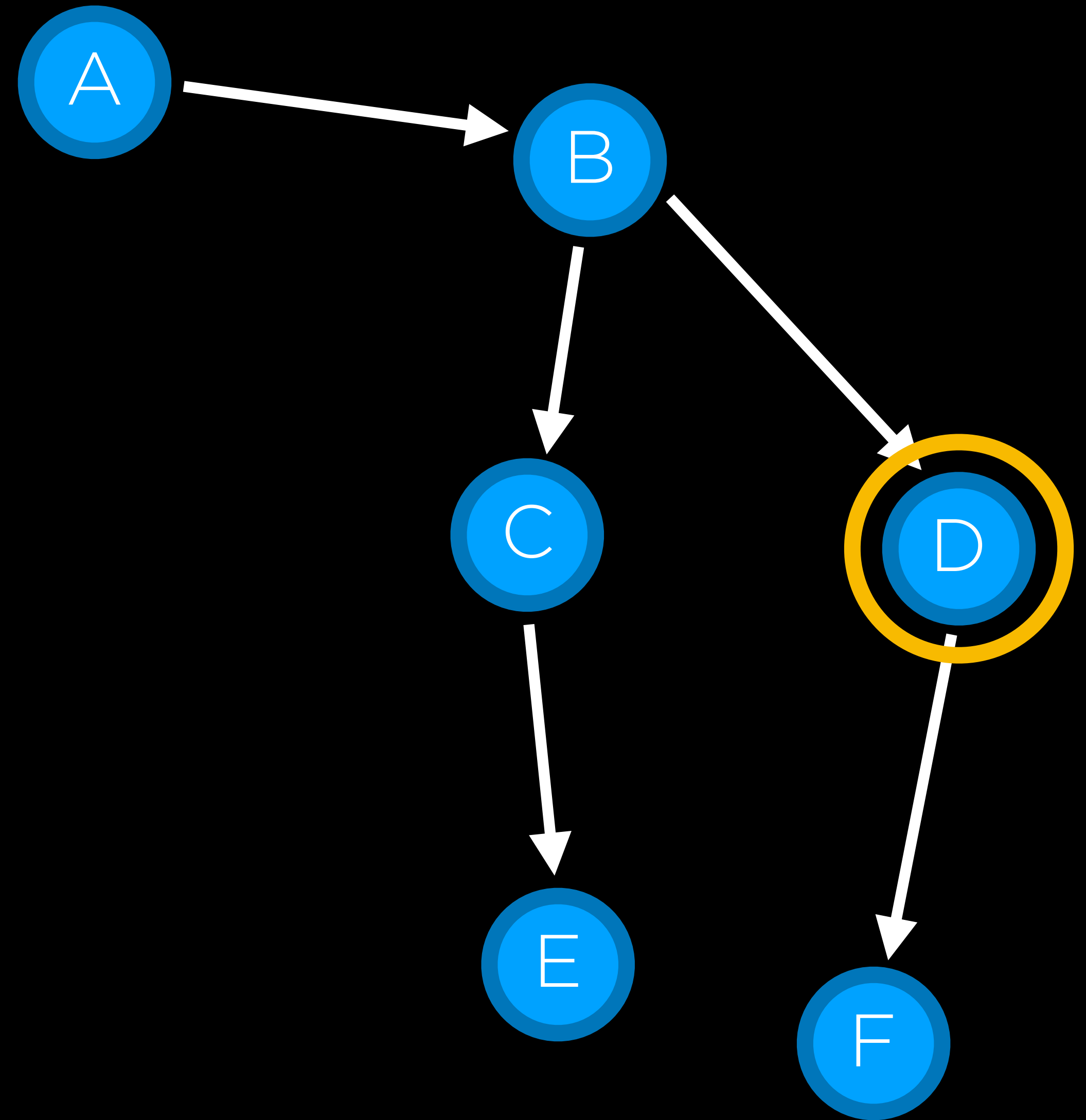
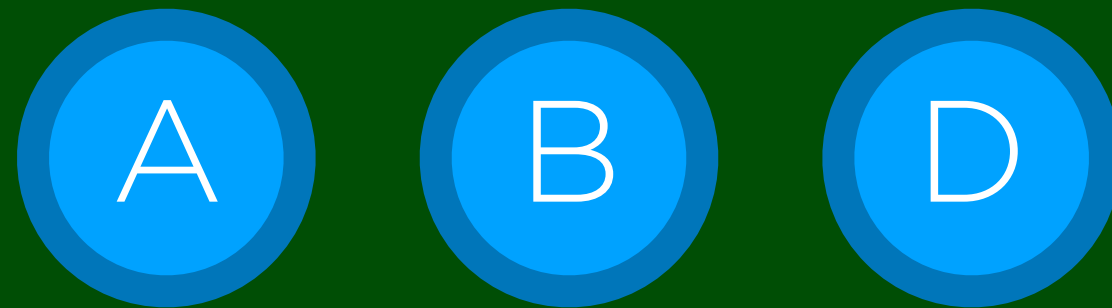


Find a path from A to E.

Frontier



Explored Set

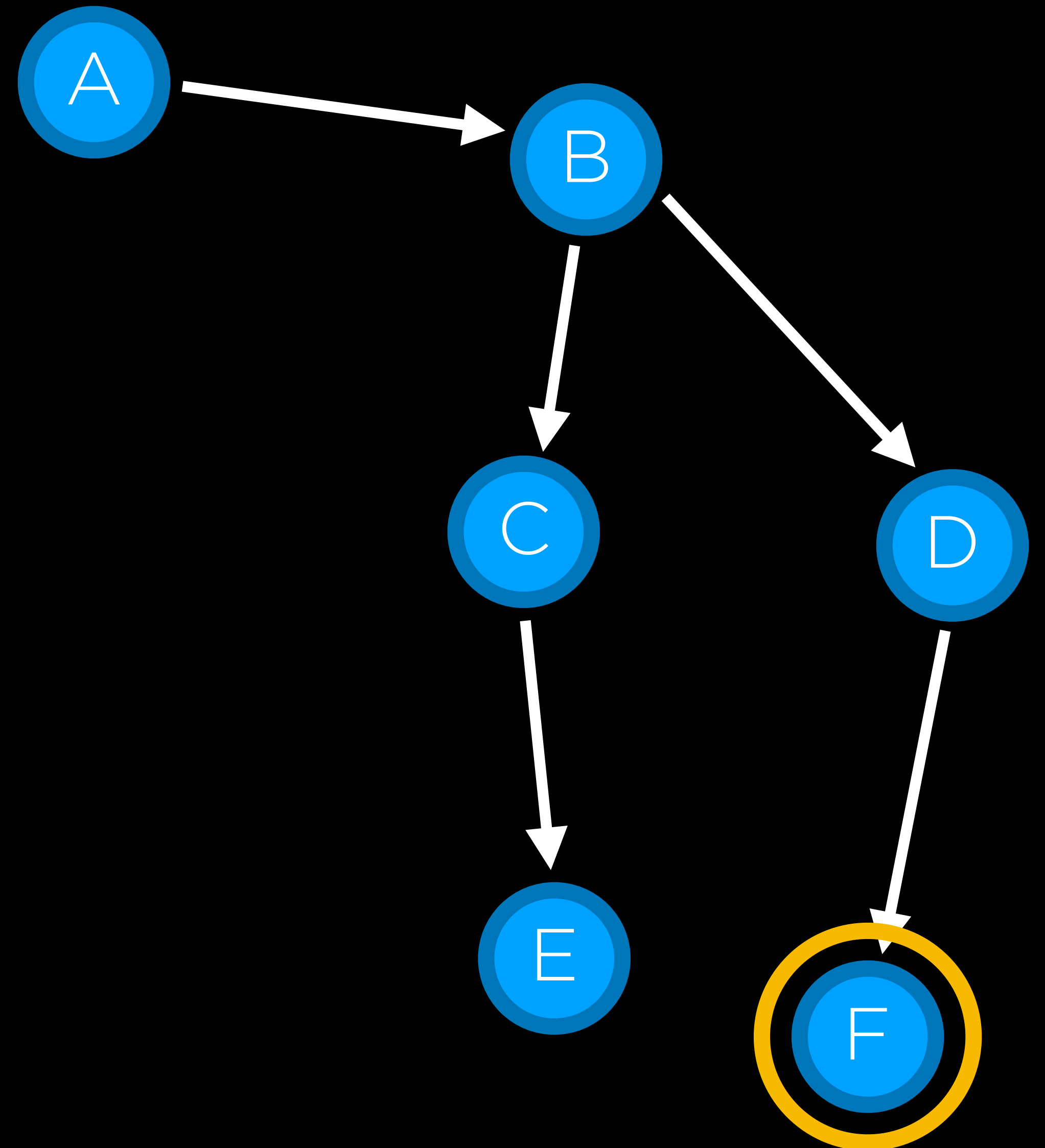
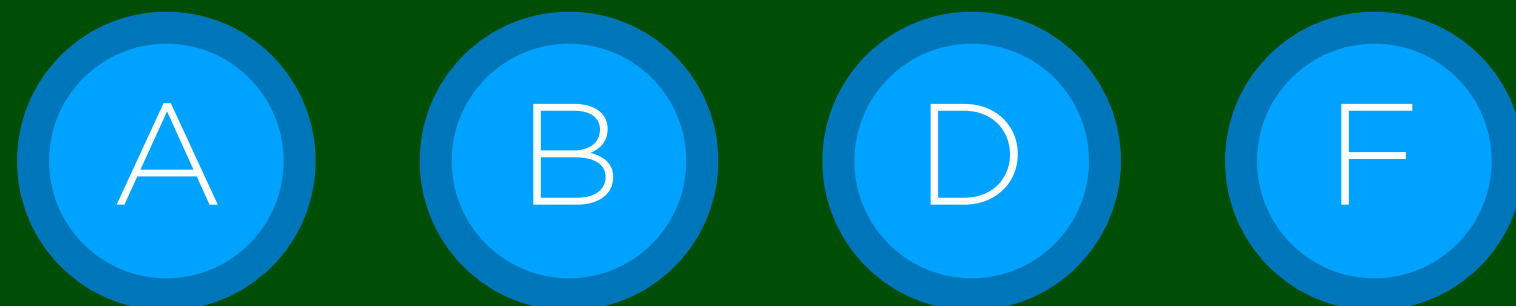


Find a path from A to E.

Frontier



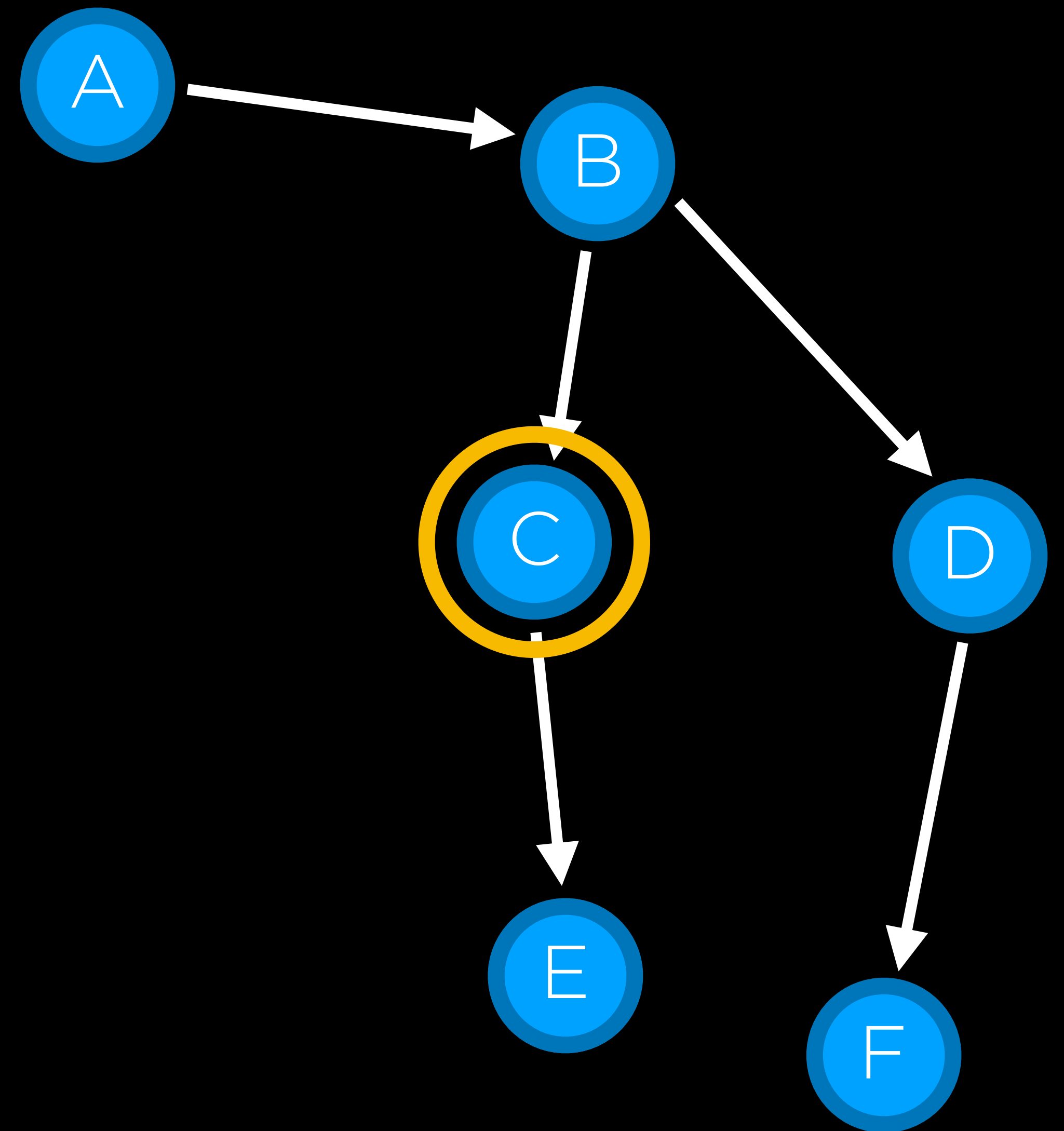
Explored Set



Find a path from A to E.

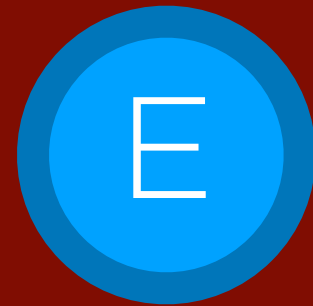
Frontier

Explored Set

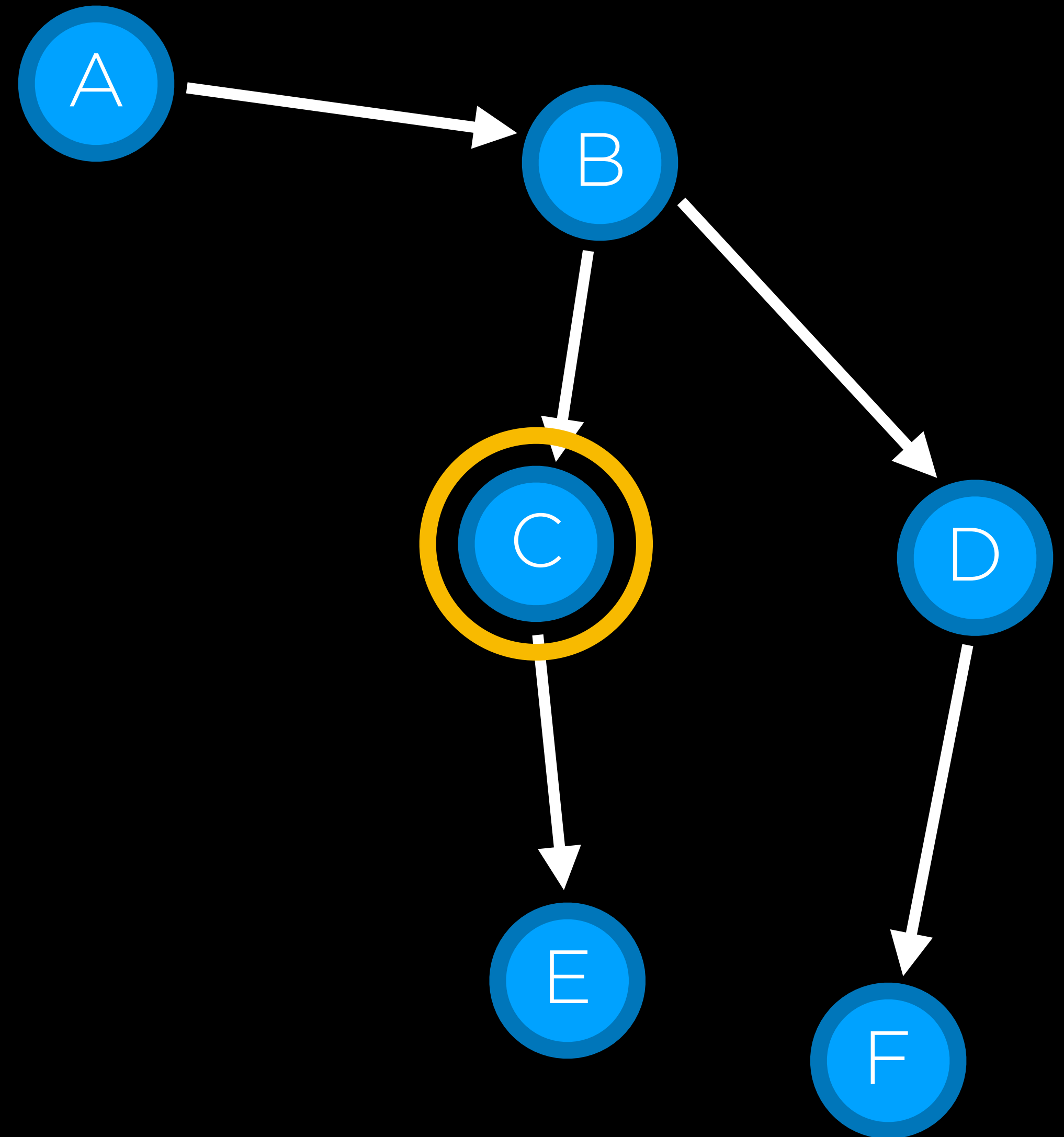


Find a path from A to E.

Frontier



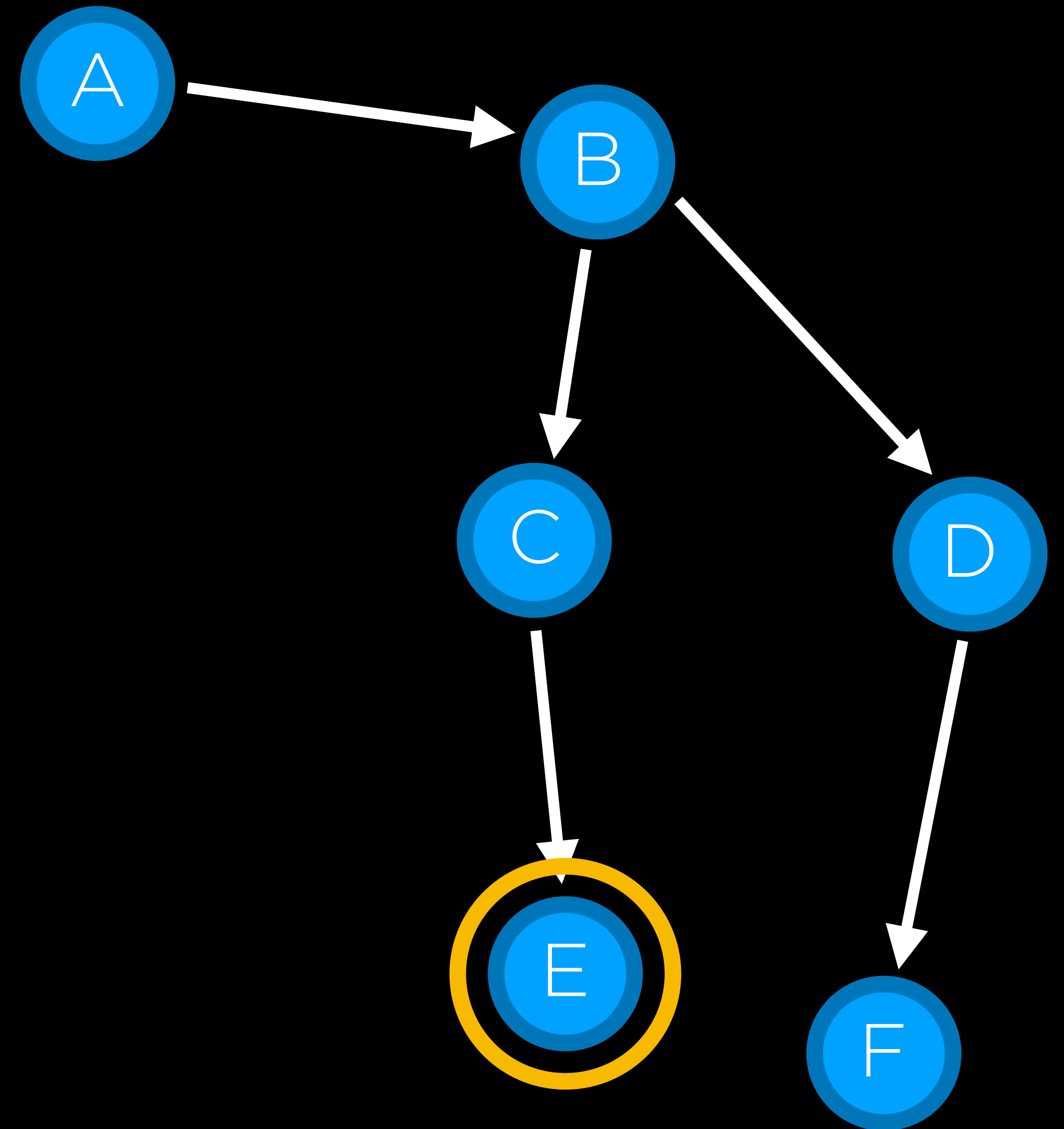
Explored Set



Find a path from A to E.

Frontier

Explored Set



Depth-First Search

depth-first search

search algorithm that always expands the deepest node in the frontier

Breadth-First Search

breadth-first search

search algorithm that always expands the shallowest node in the frontier

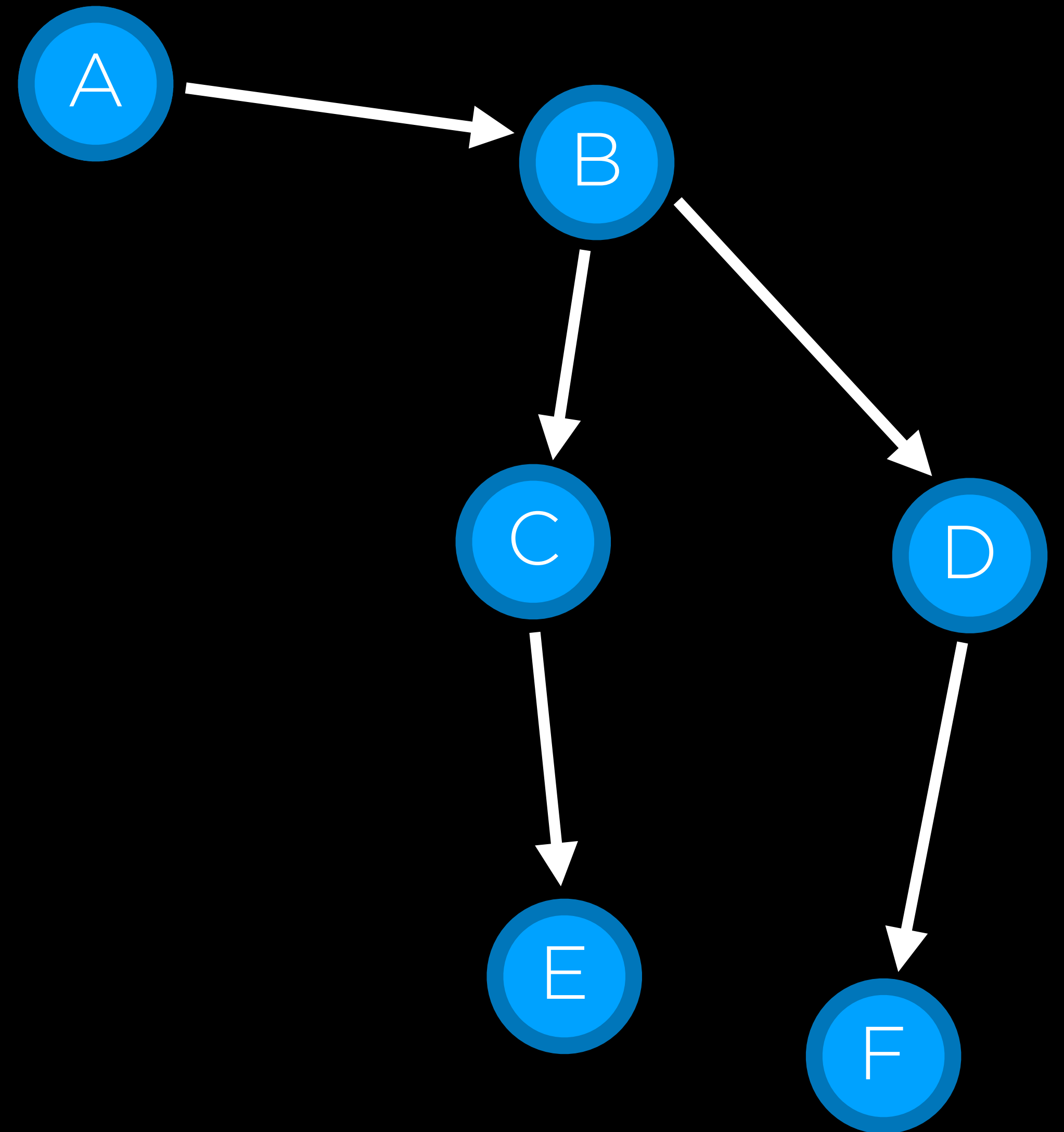
queue

first-in first-out data type

Find a path from A to E.

Frontier

Explored Set

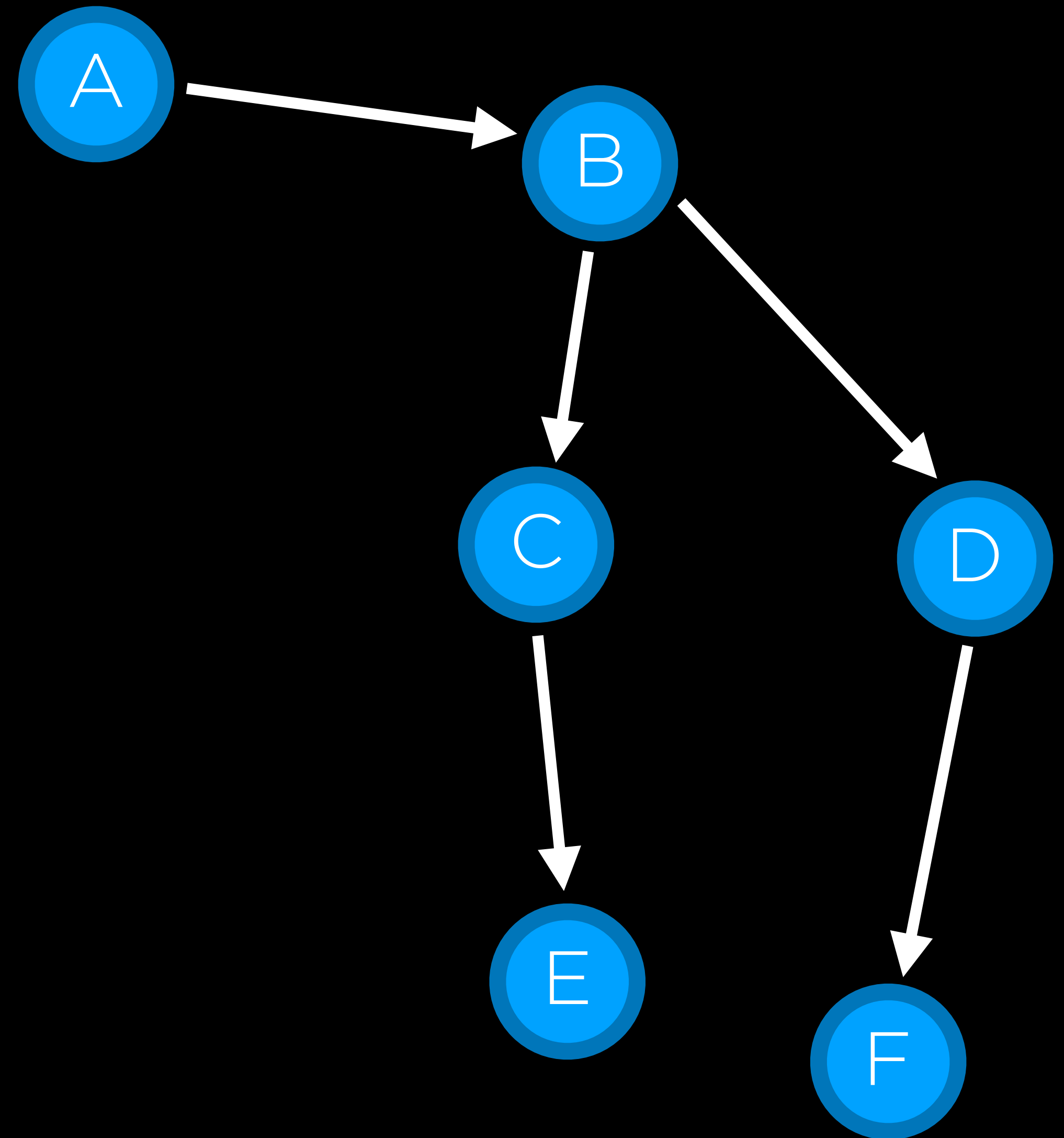


Find a path from A to E.

Frontier



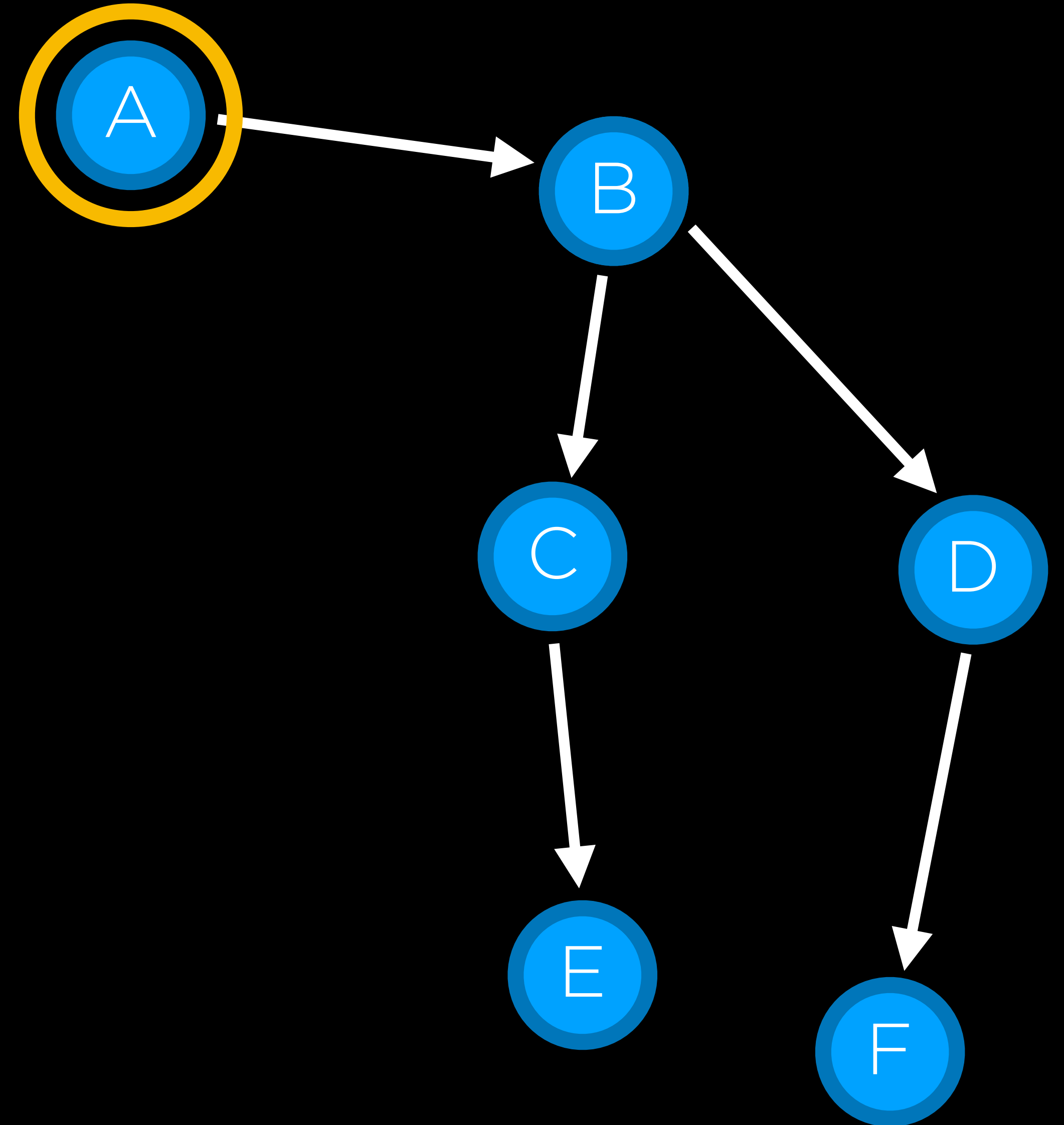
Explored Set



Find a path from A to E.

Frontier

Explored Set

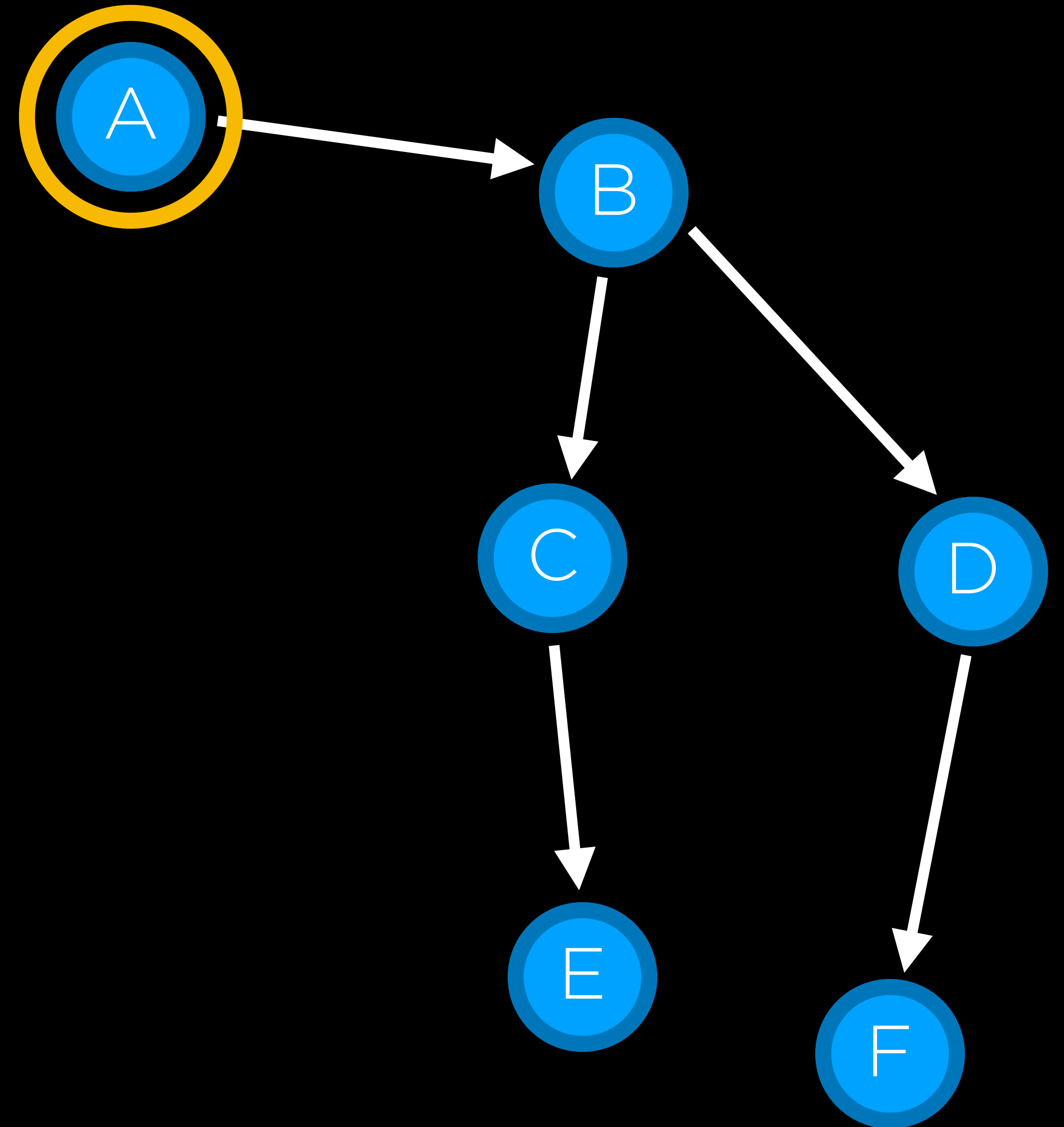


Find a path from A to E.

Frontier



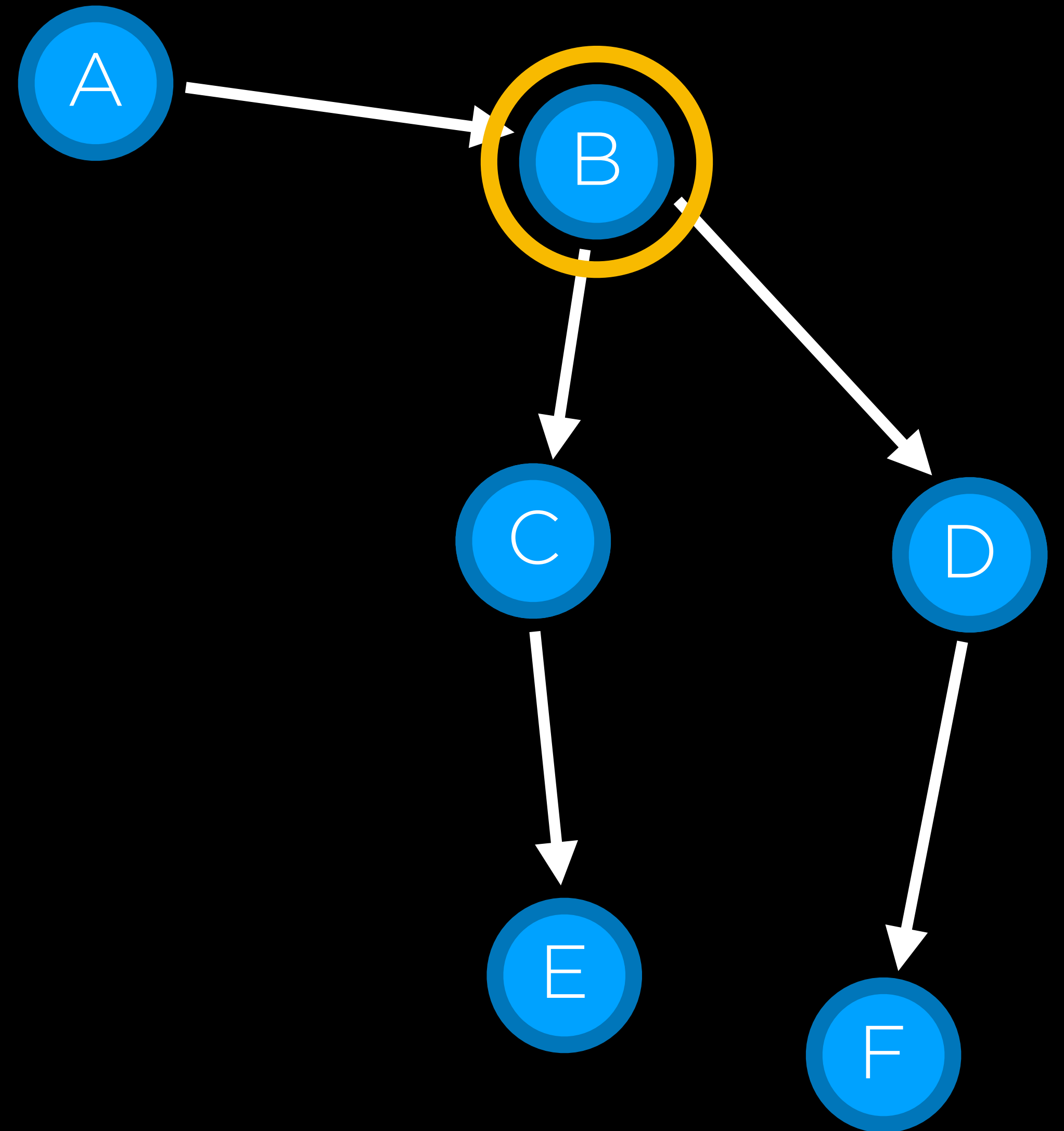
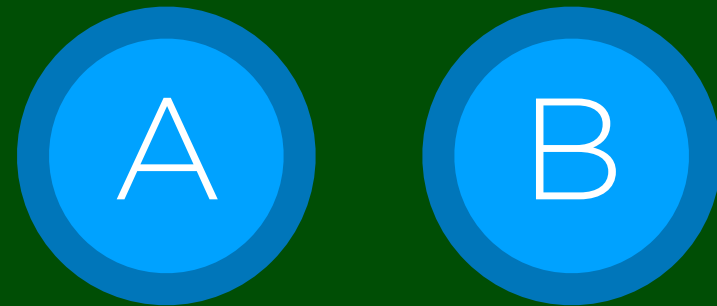
Explored Set



Find a path from A to E.

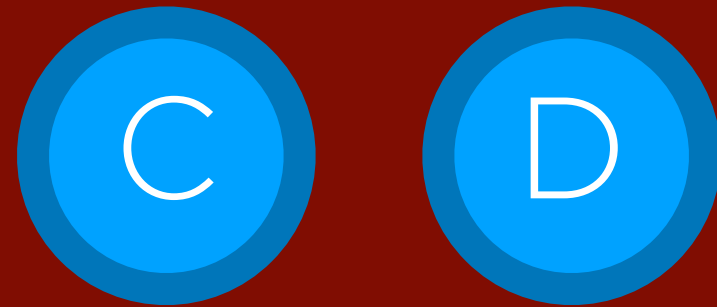
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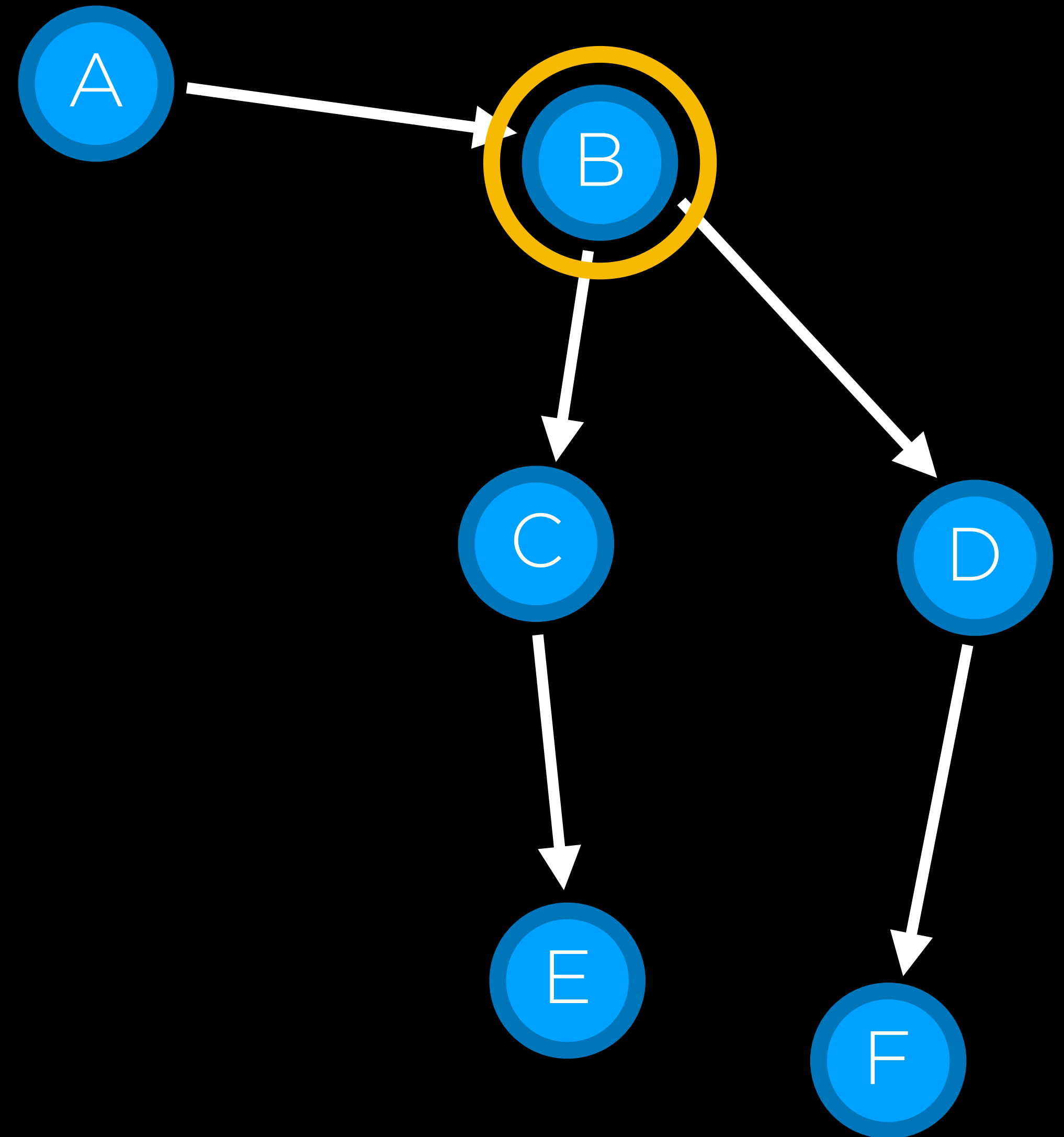


Find a path from A to E.

Frontier



Explored Set

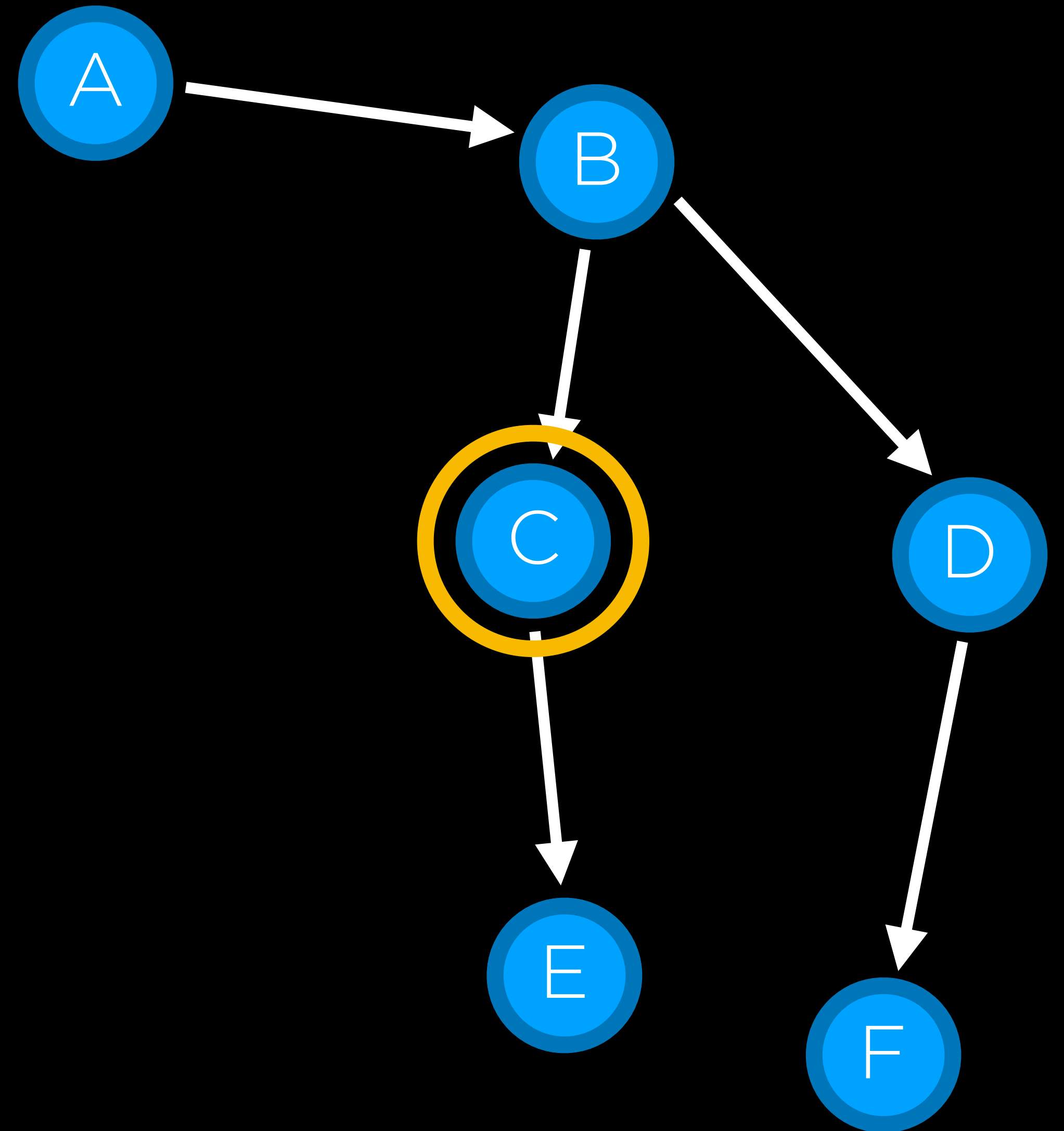
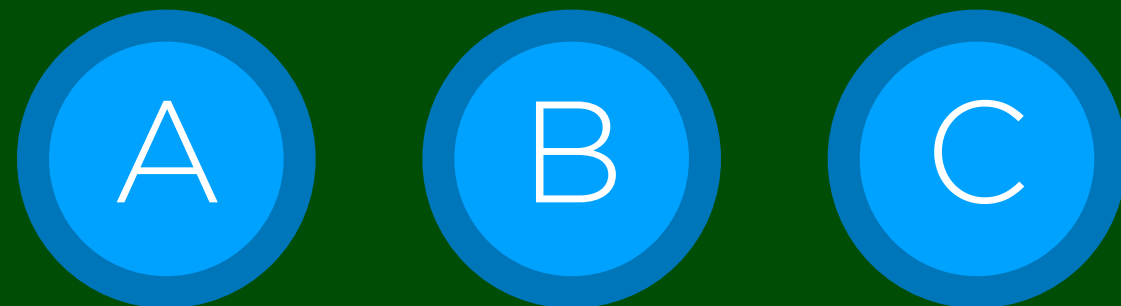


Find a path from A to E.

Frontier

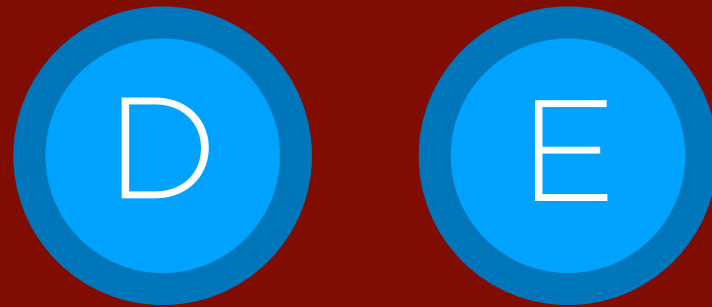


Explored Set

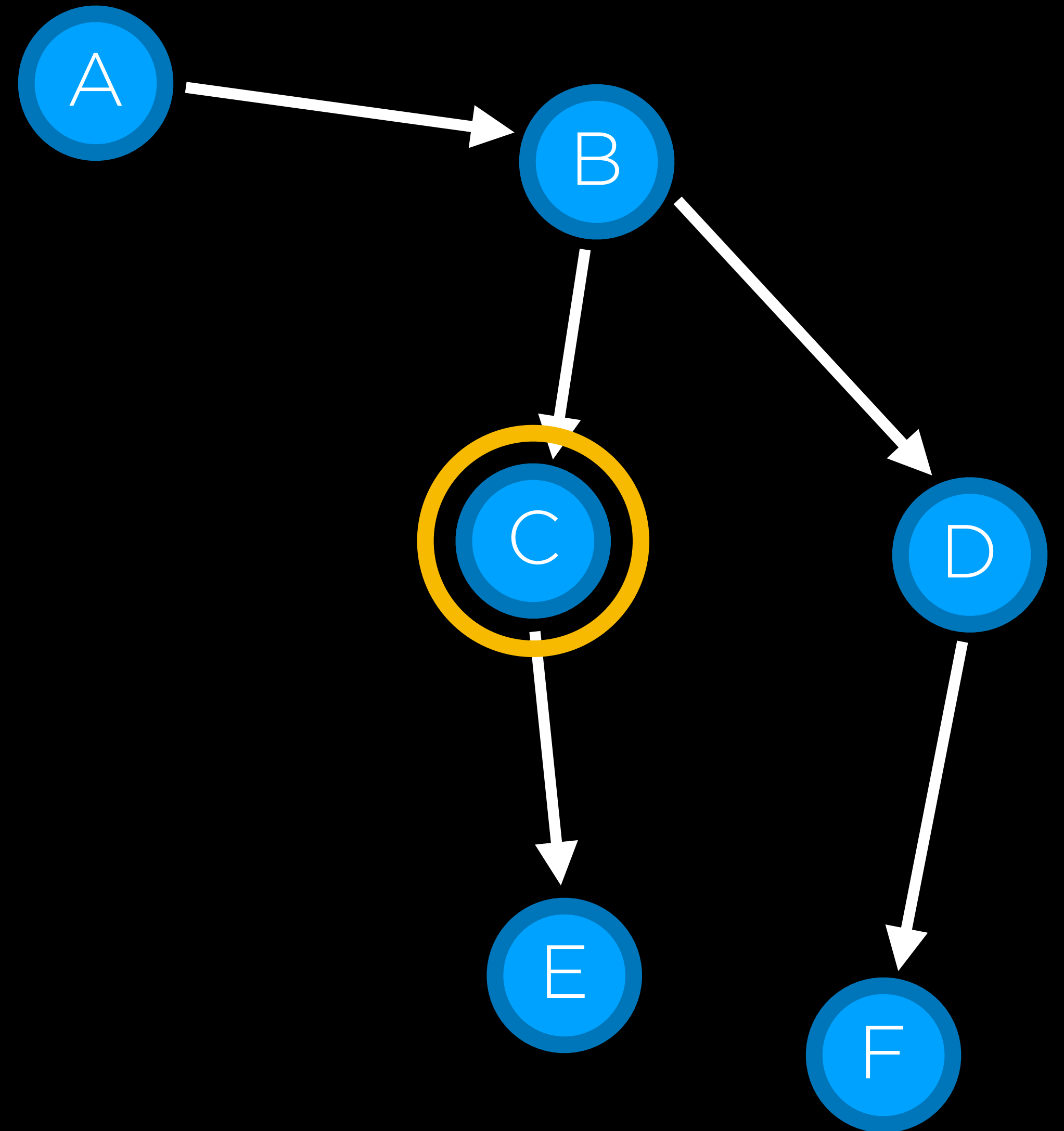
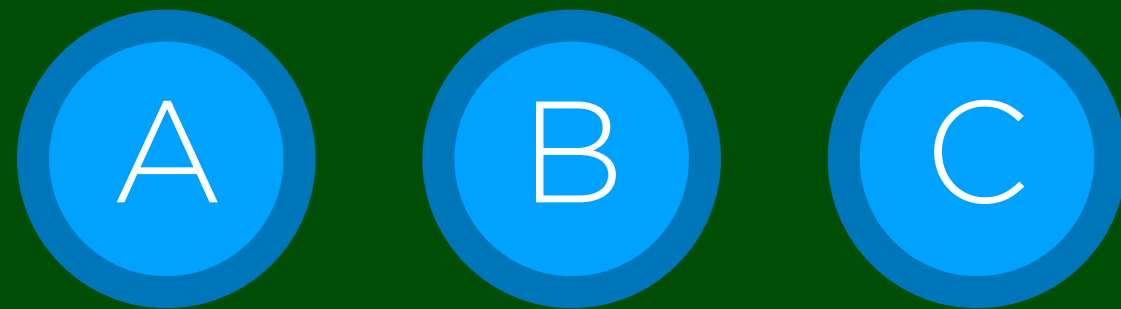


Find a path from A to E.

Frontier



Explored Set

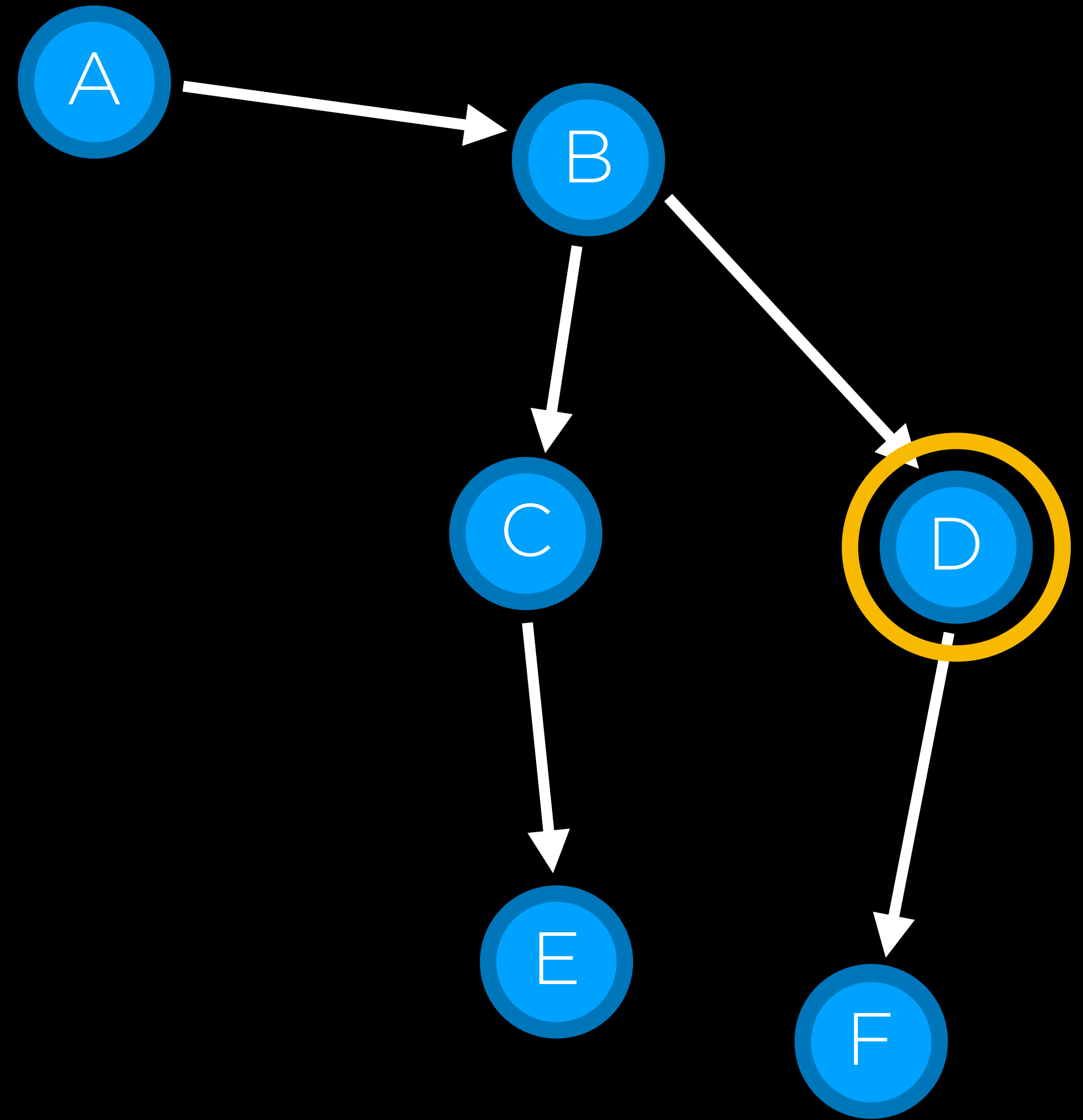
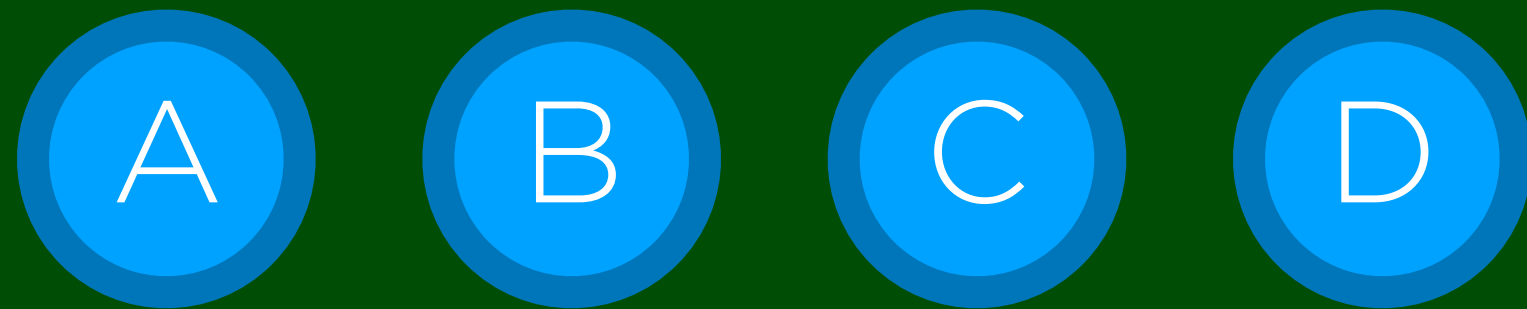


Find a path from A to E.

Frontier

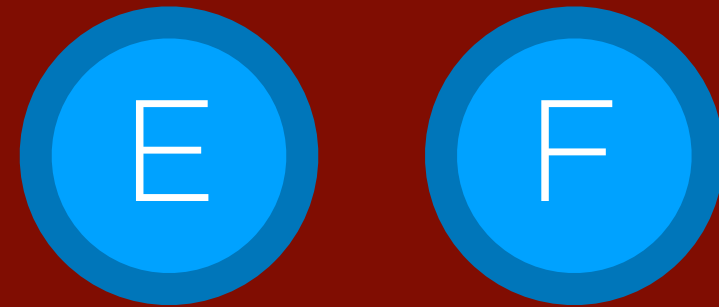


Explored Set

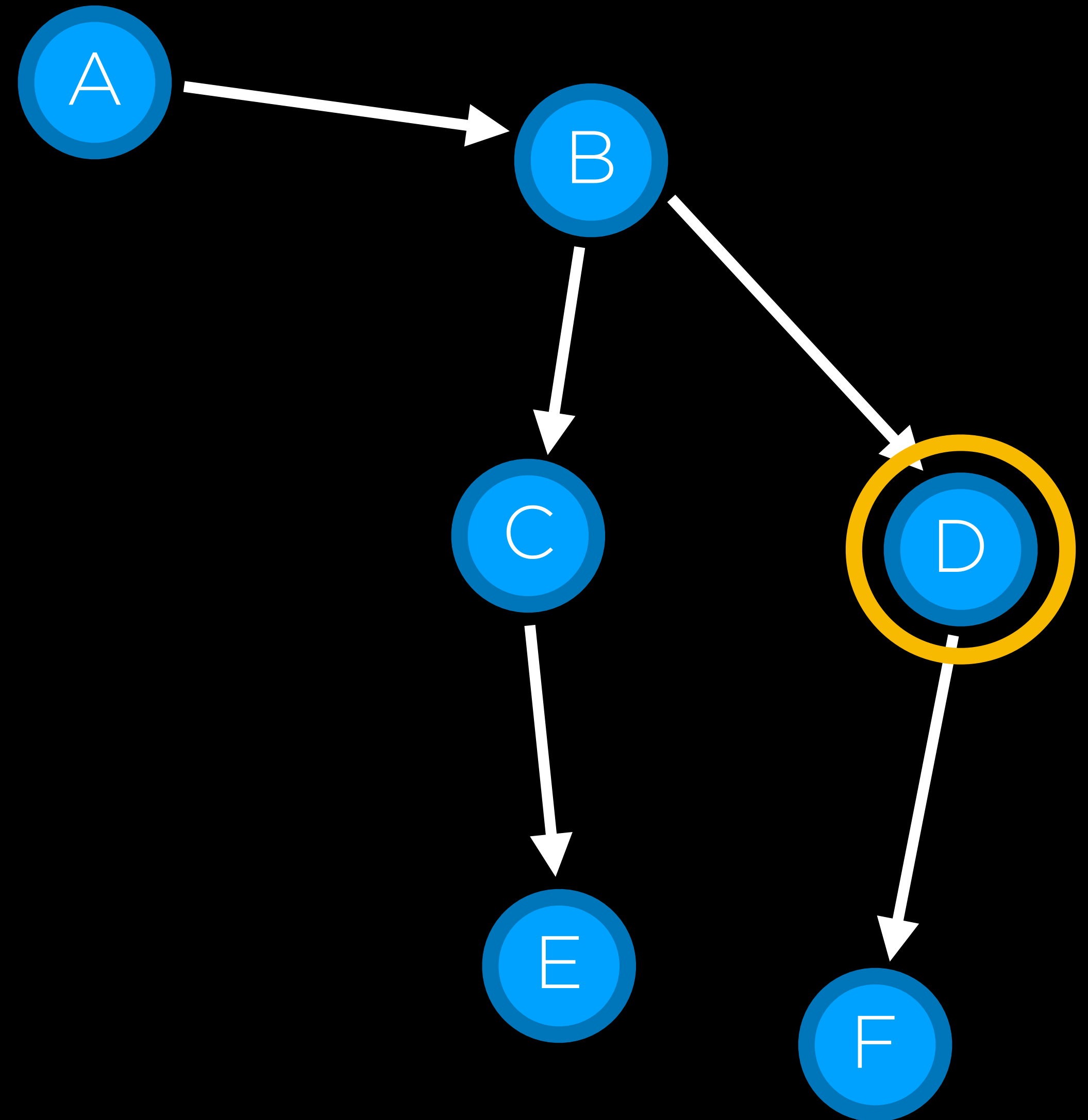
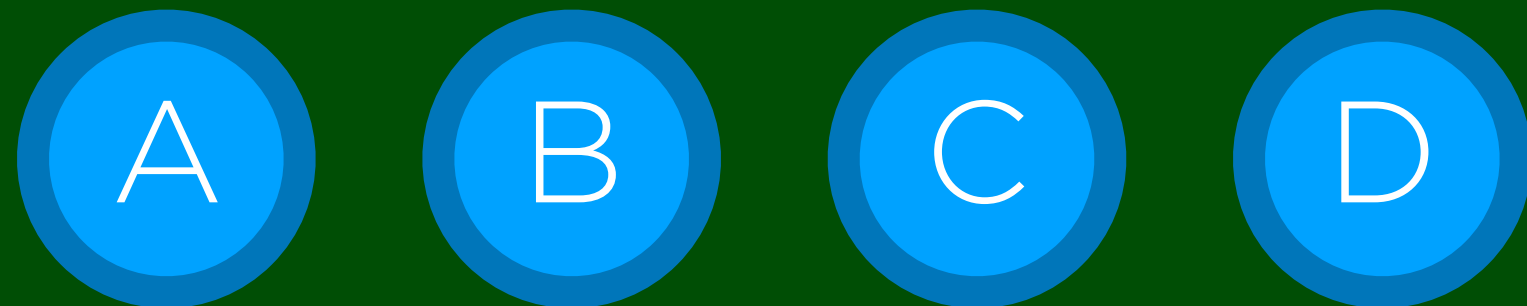


Find a path from A to E.

Frontier



Explored Set

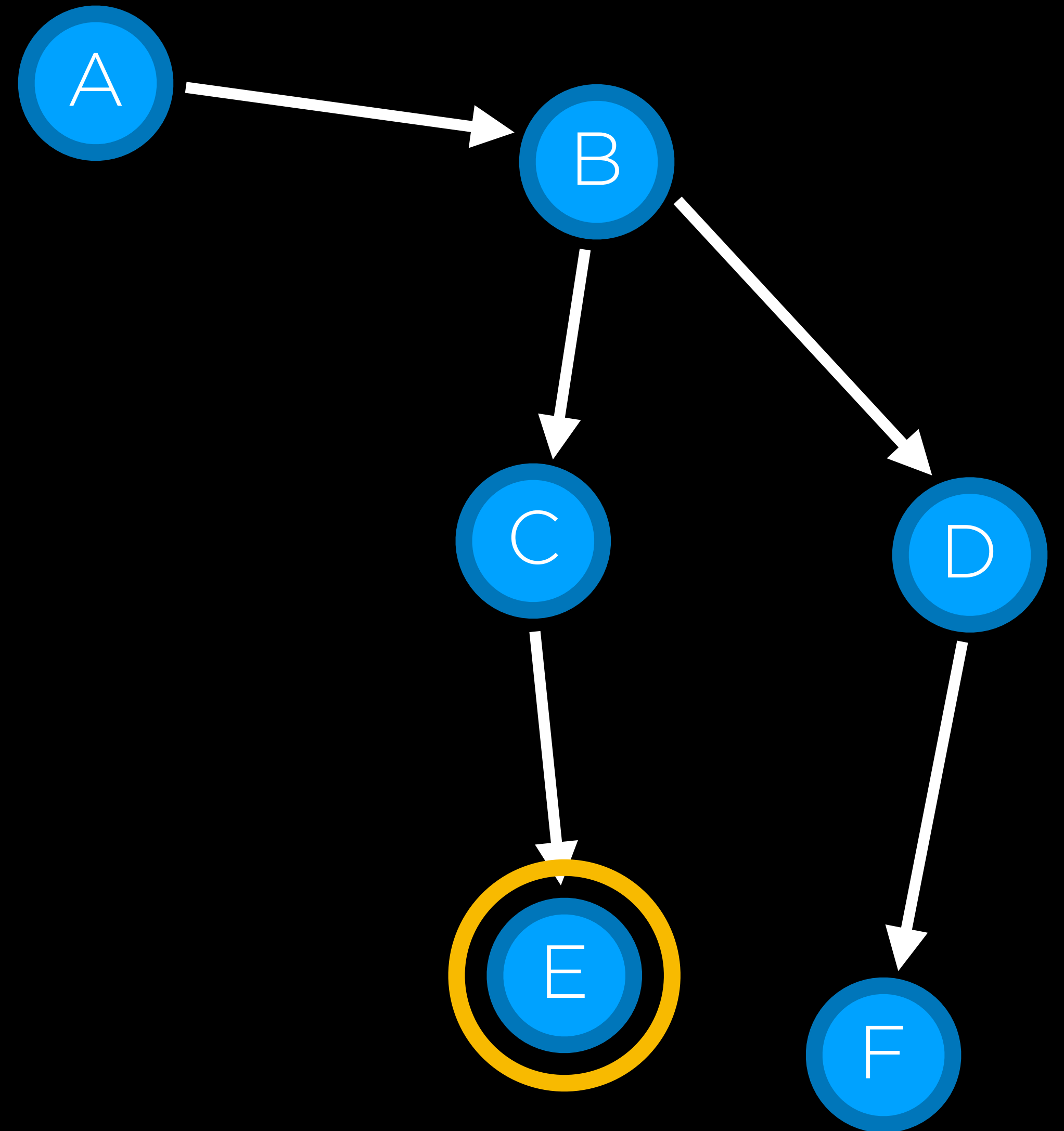
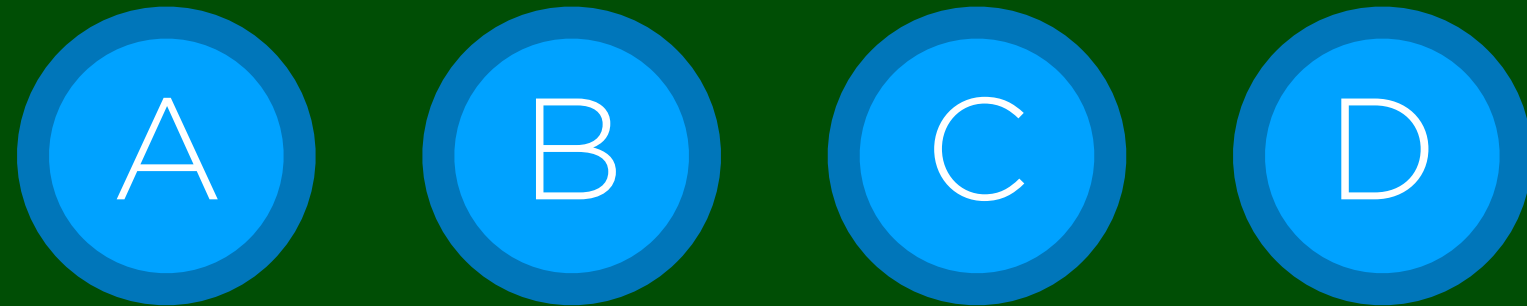


Find a path from A to E.

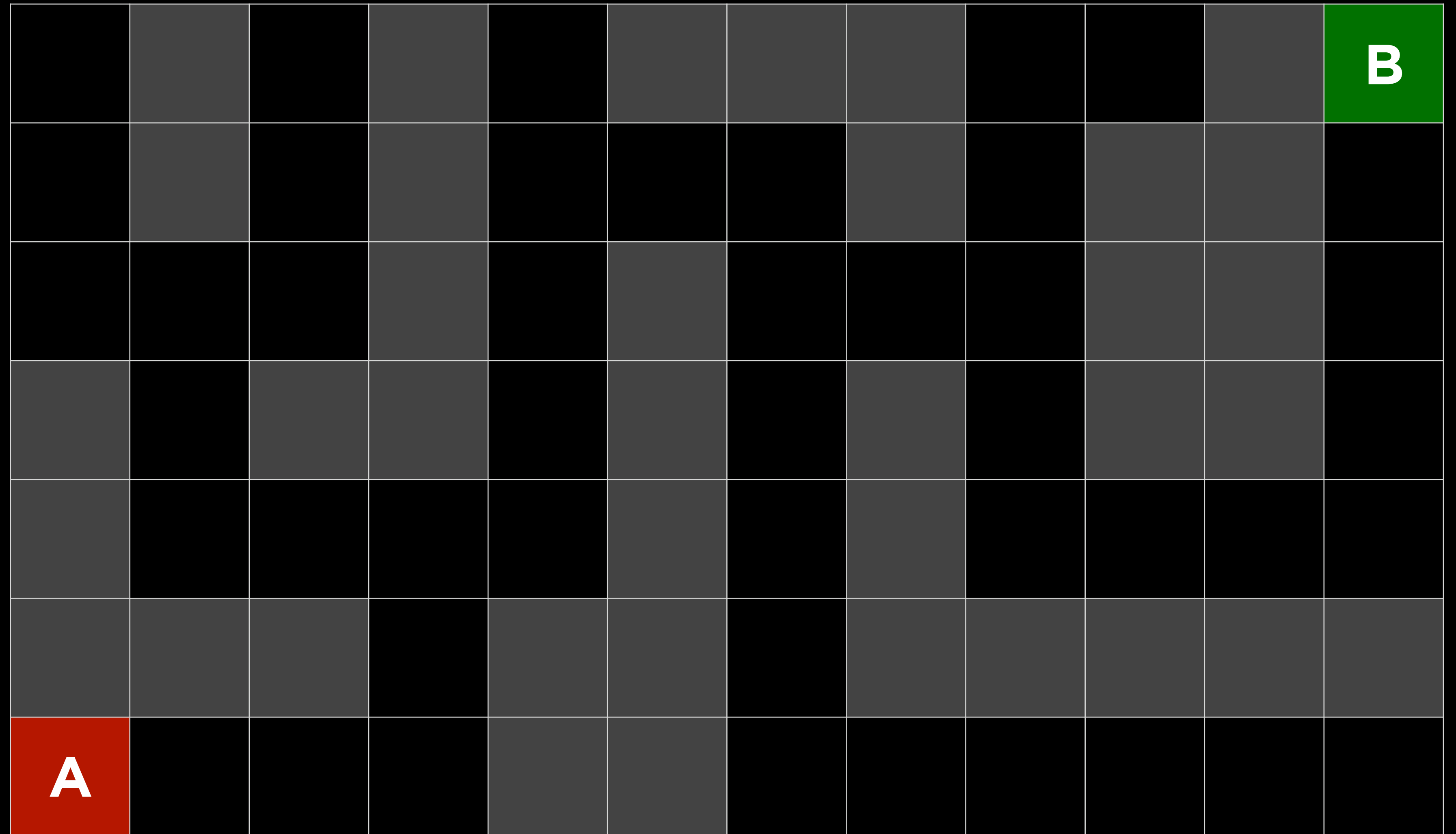
Frontier



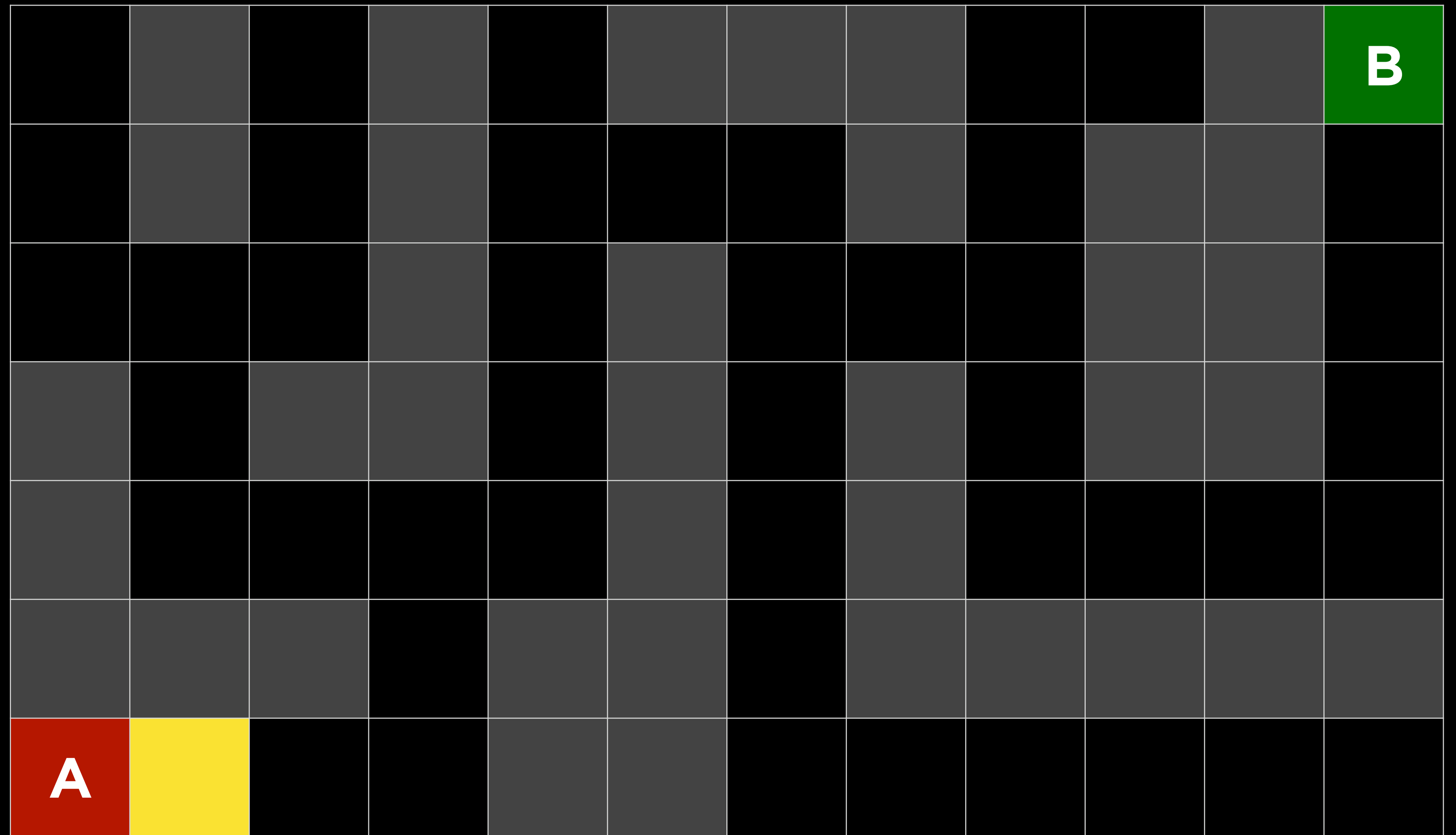
Explored Set



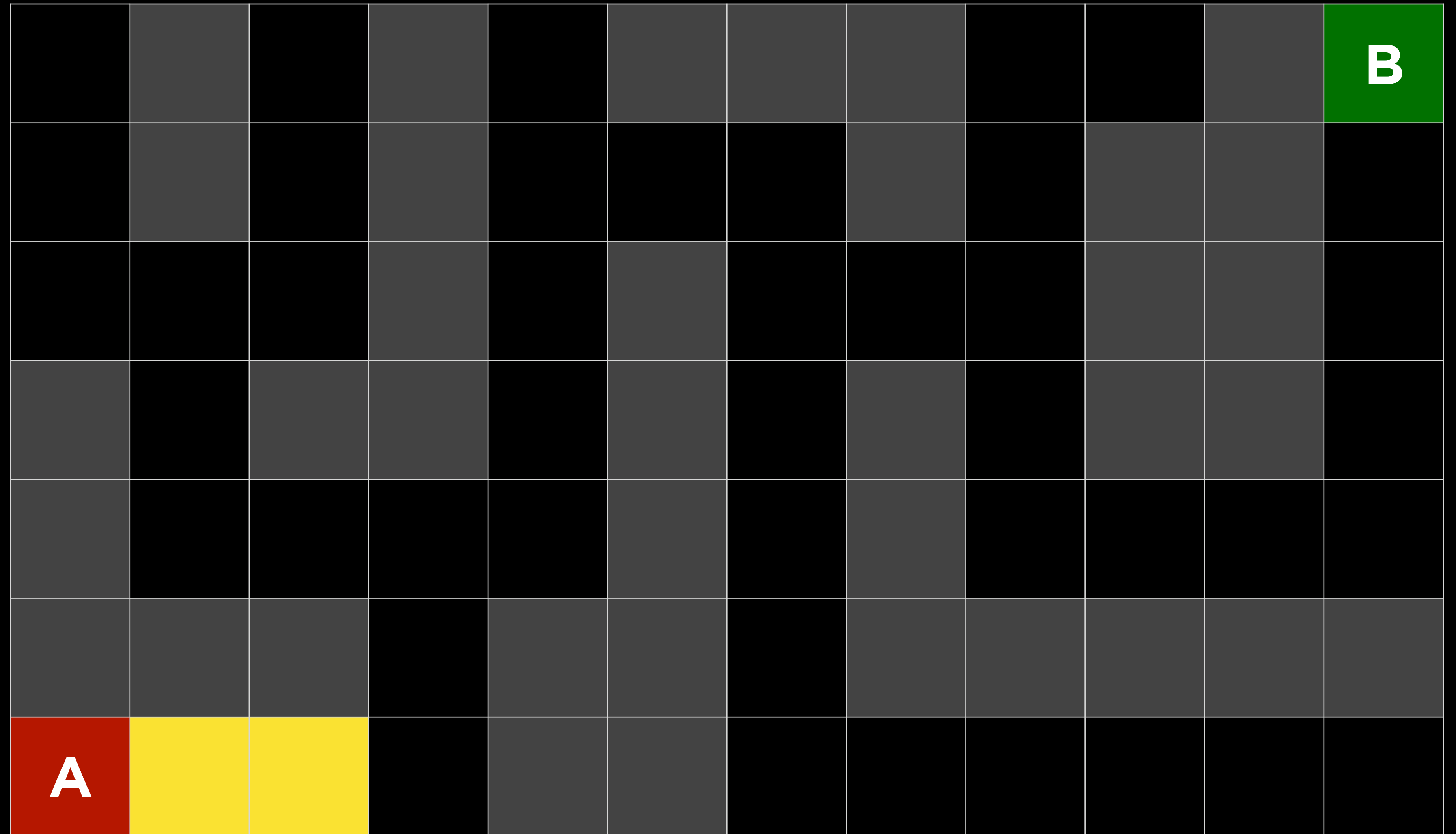
Depth-First Search



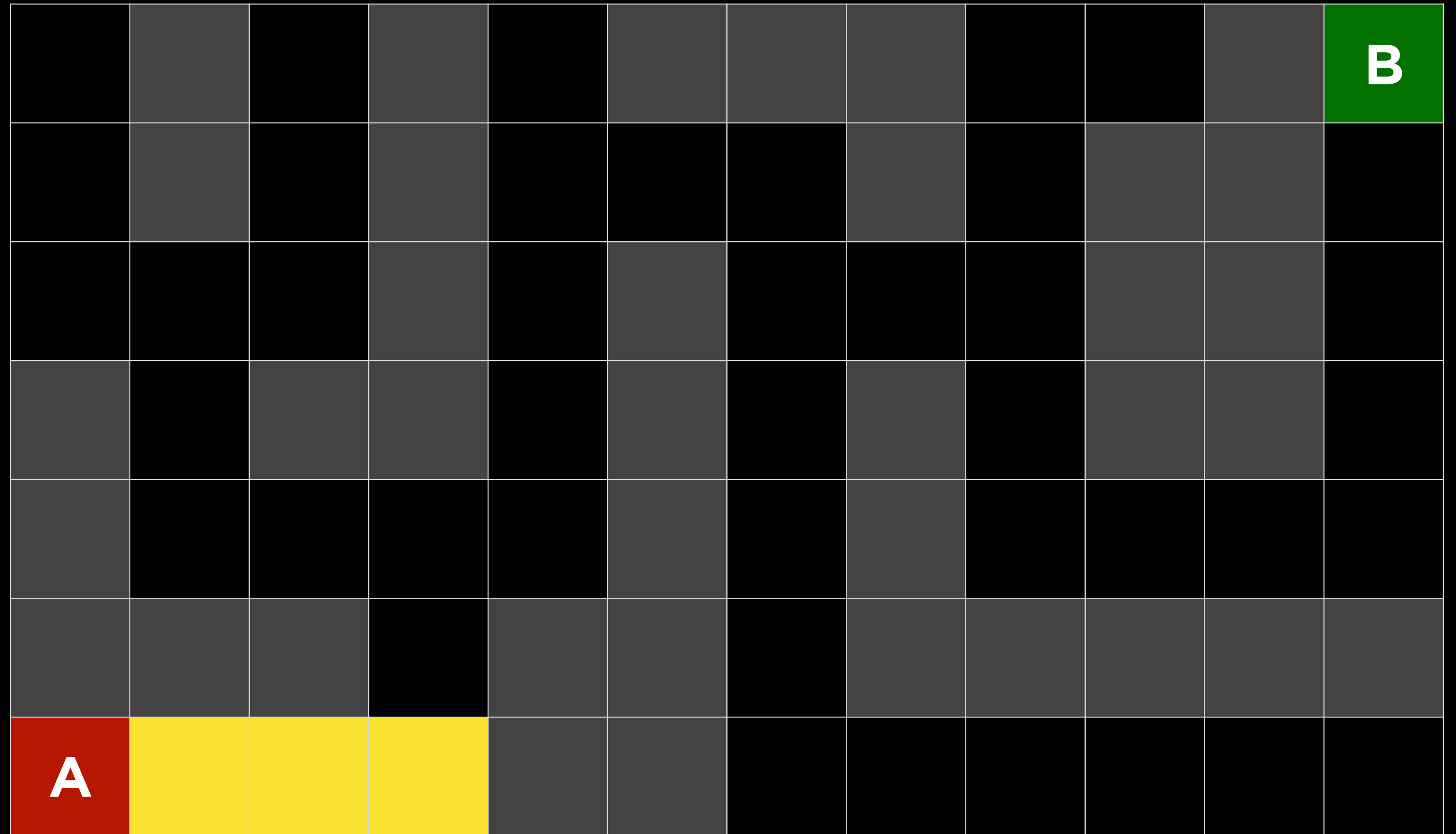
Depth-First Search



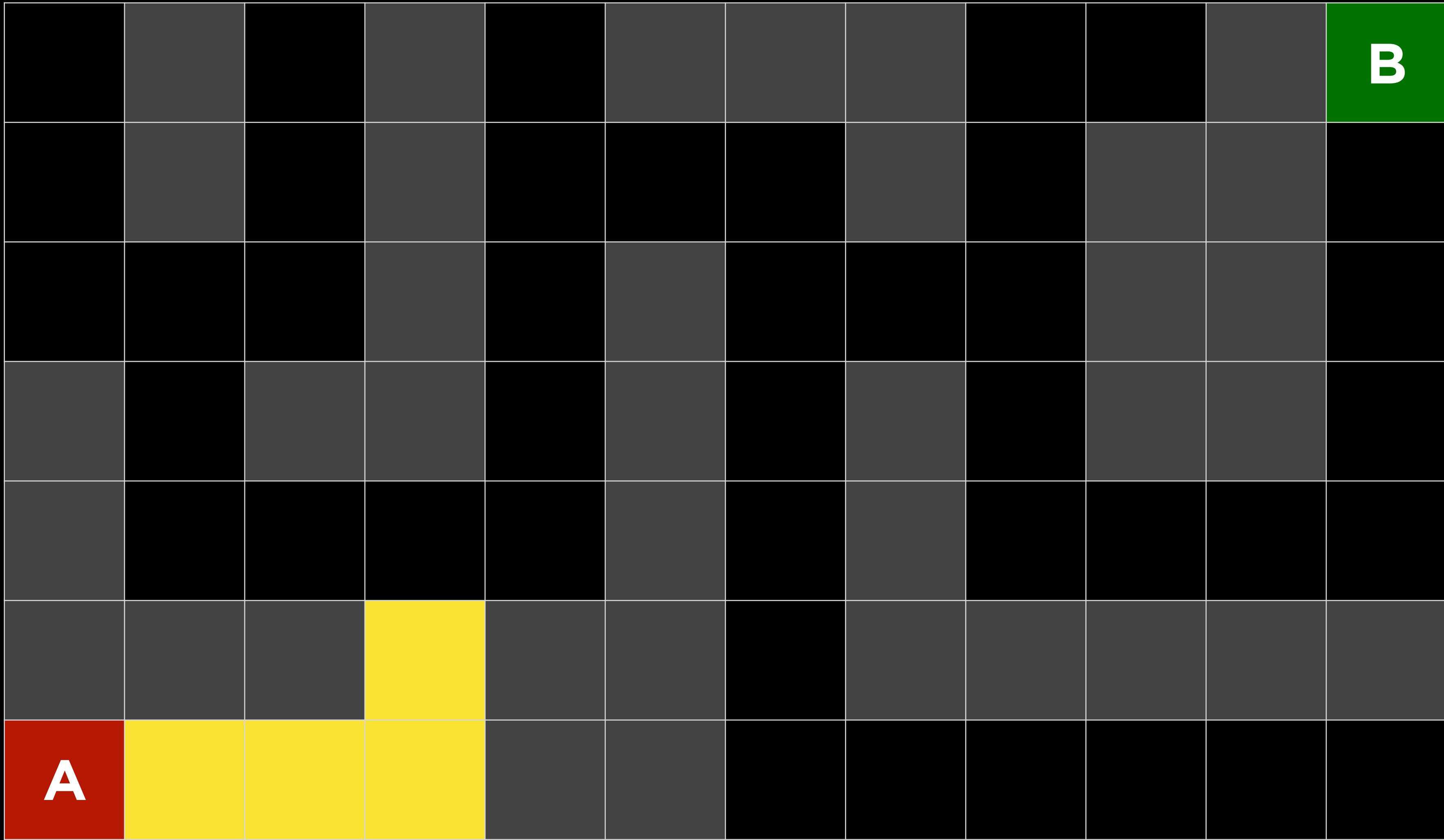
Depth-First Search



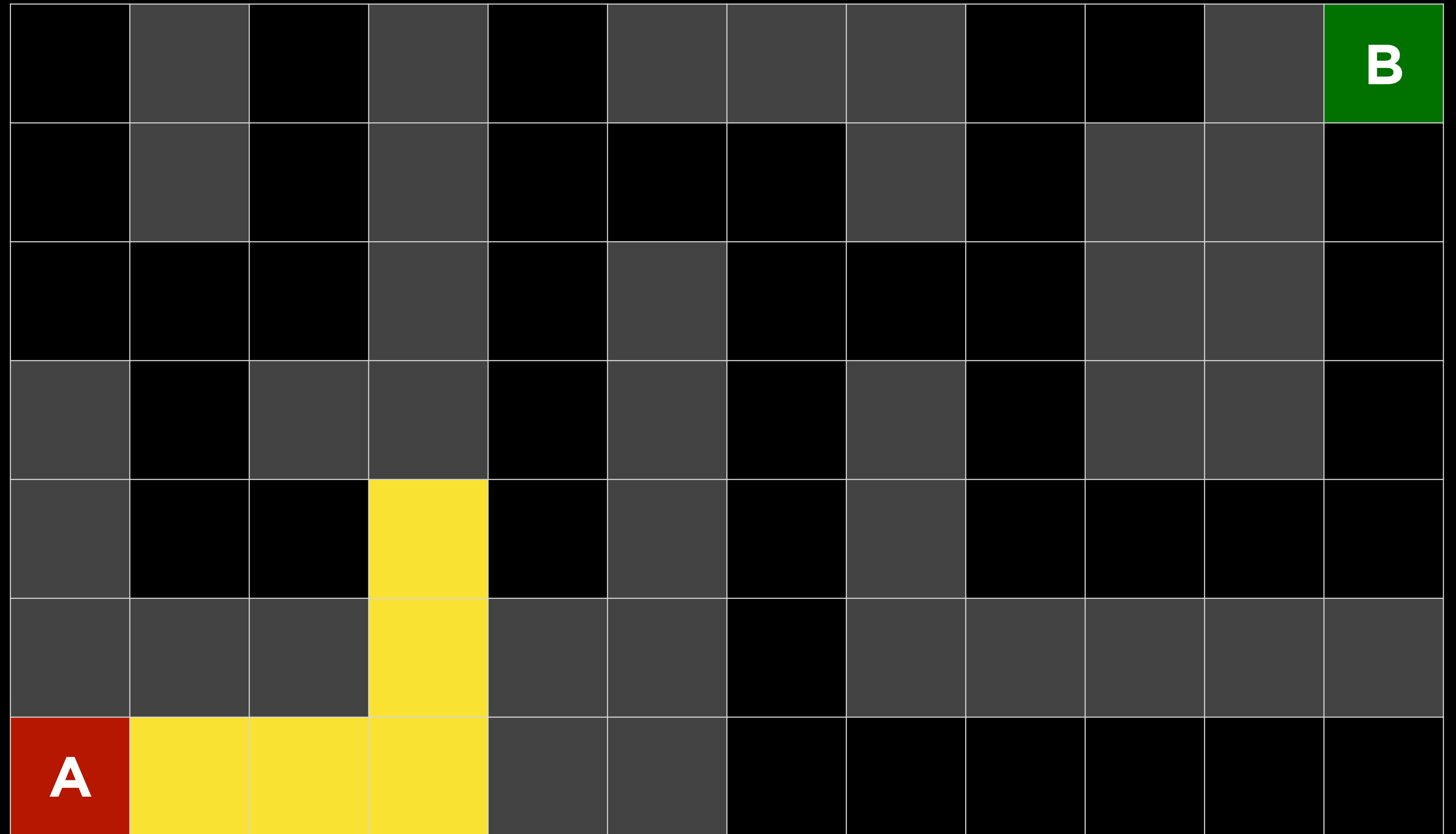
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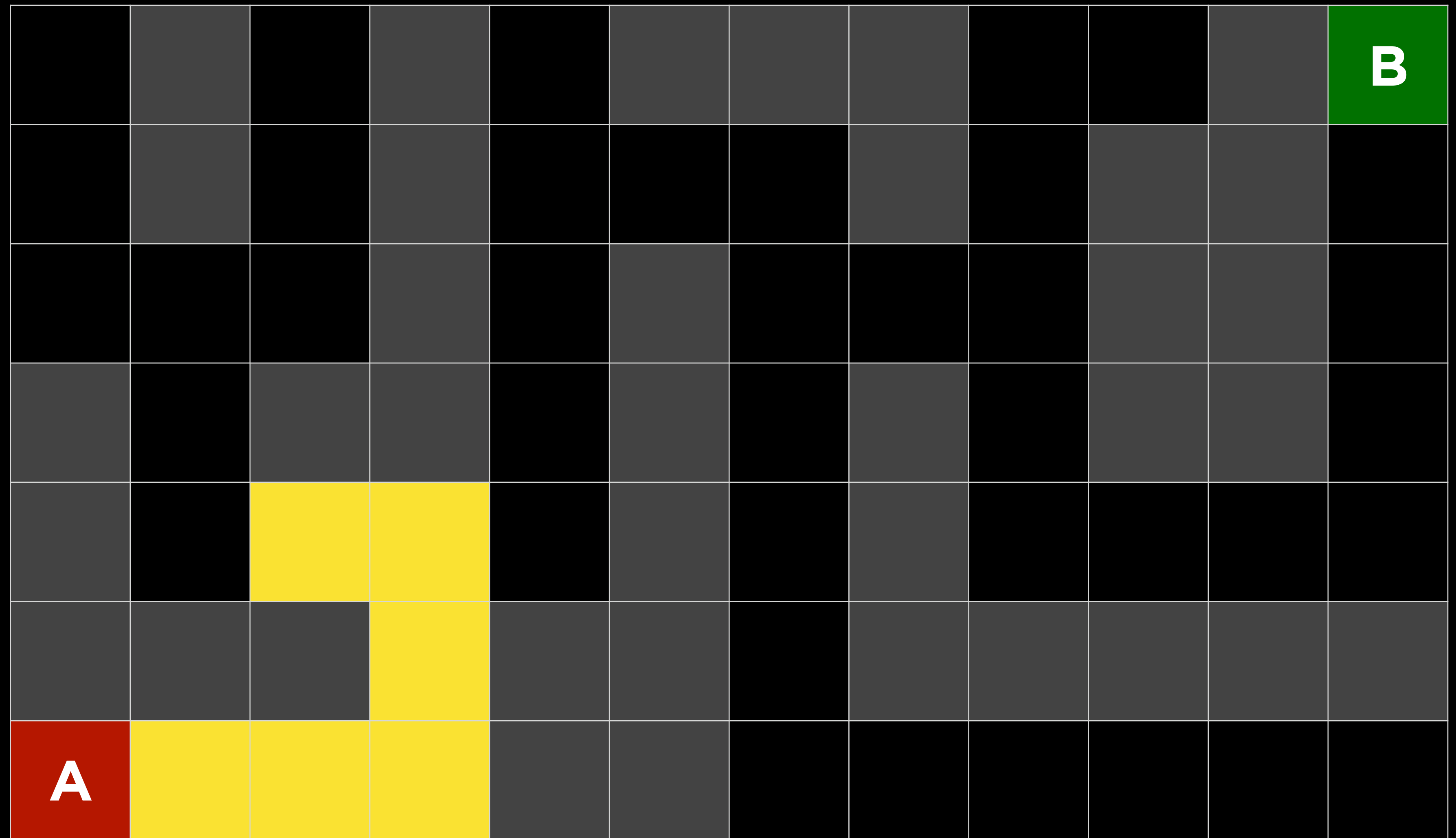
Depth-First Search



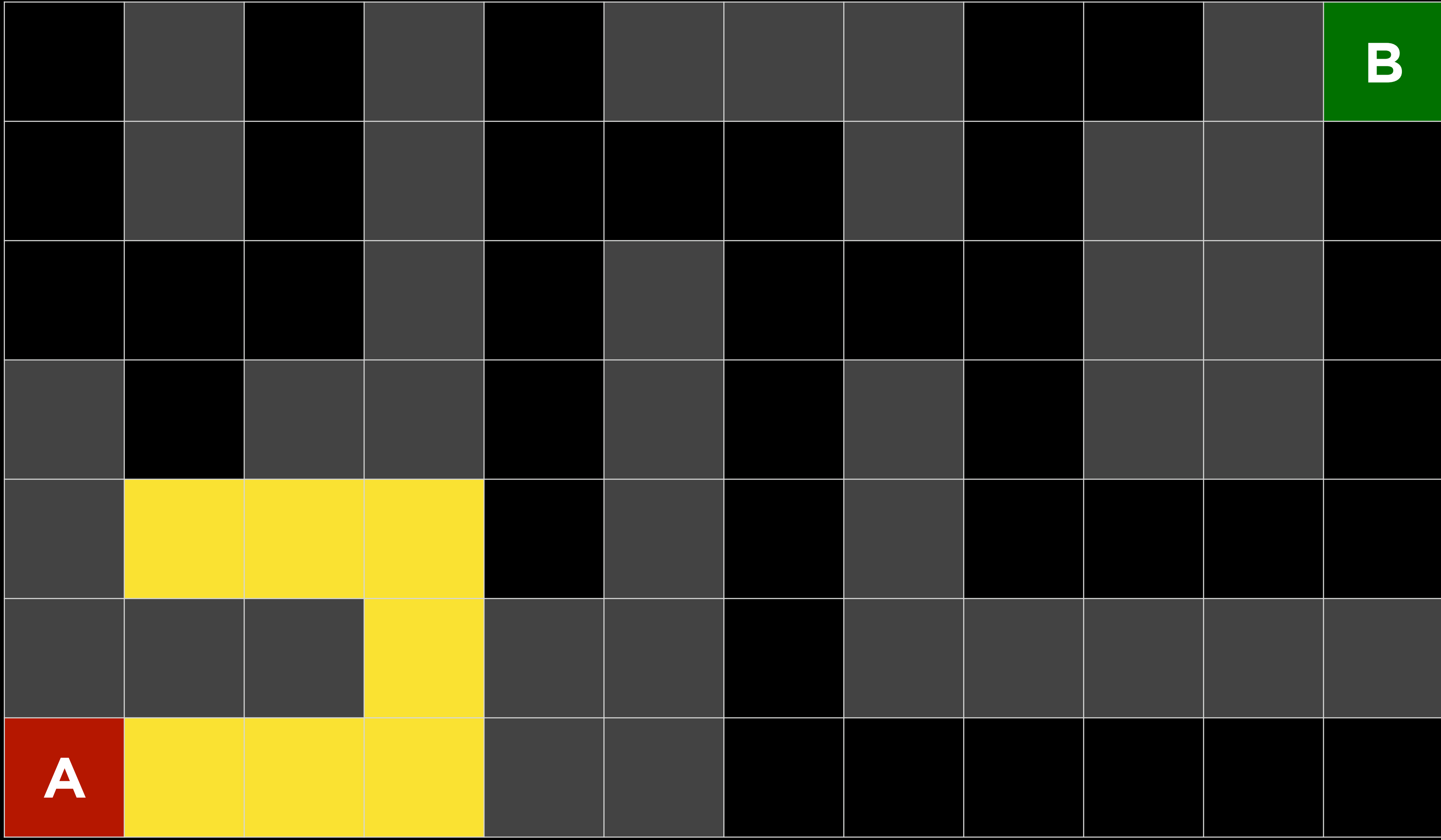
Depth-First Search



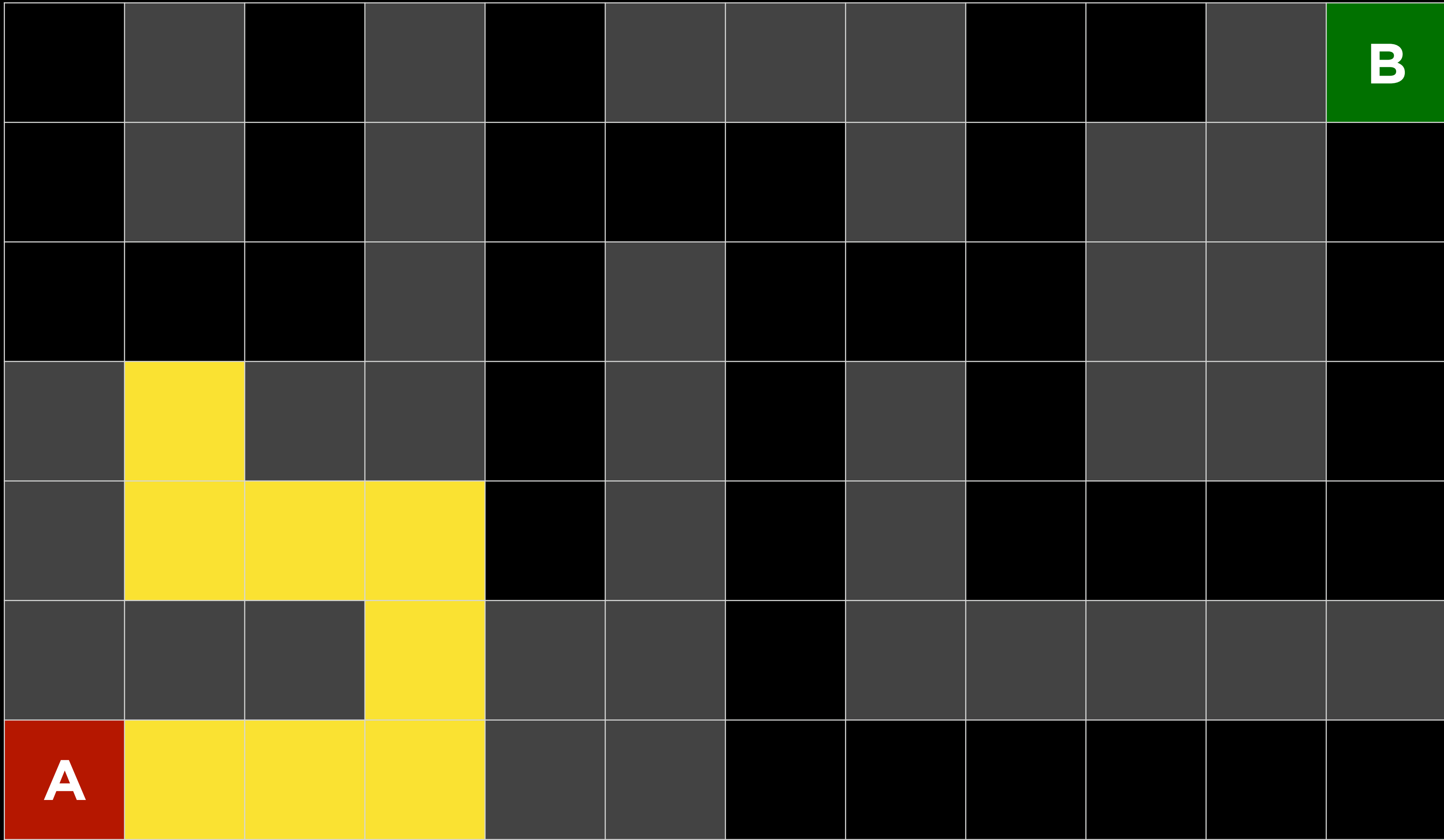
Depth-First Search



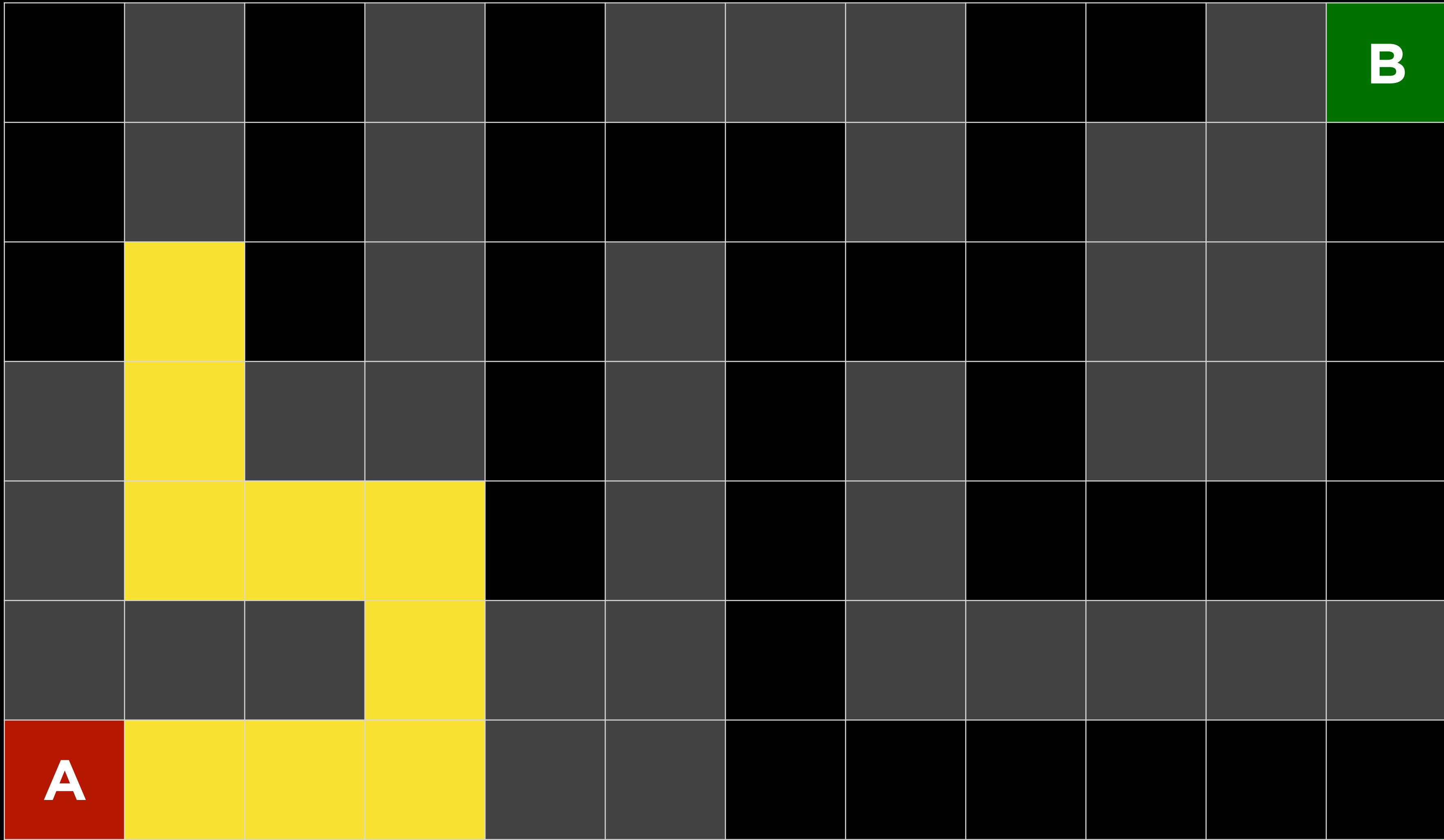
Depth-First Search



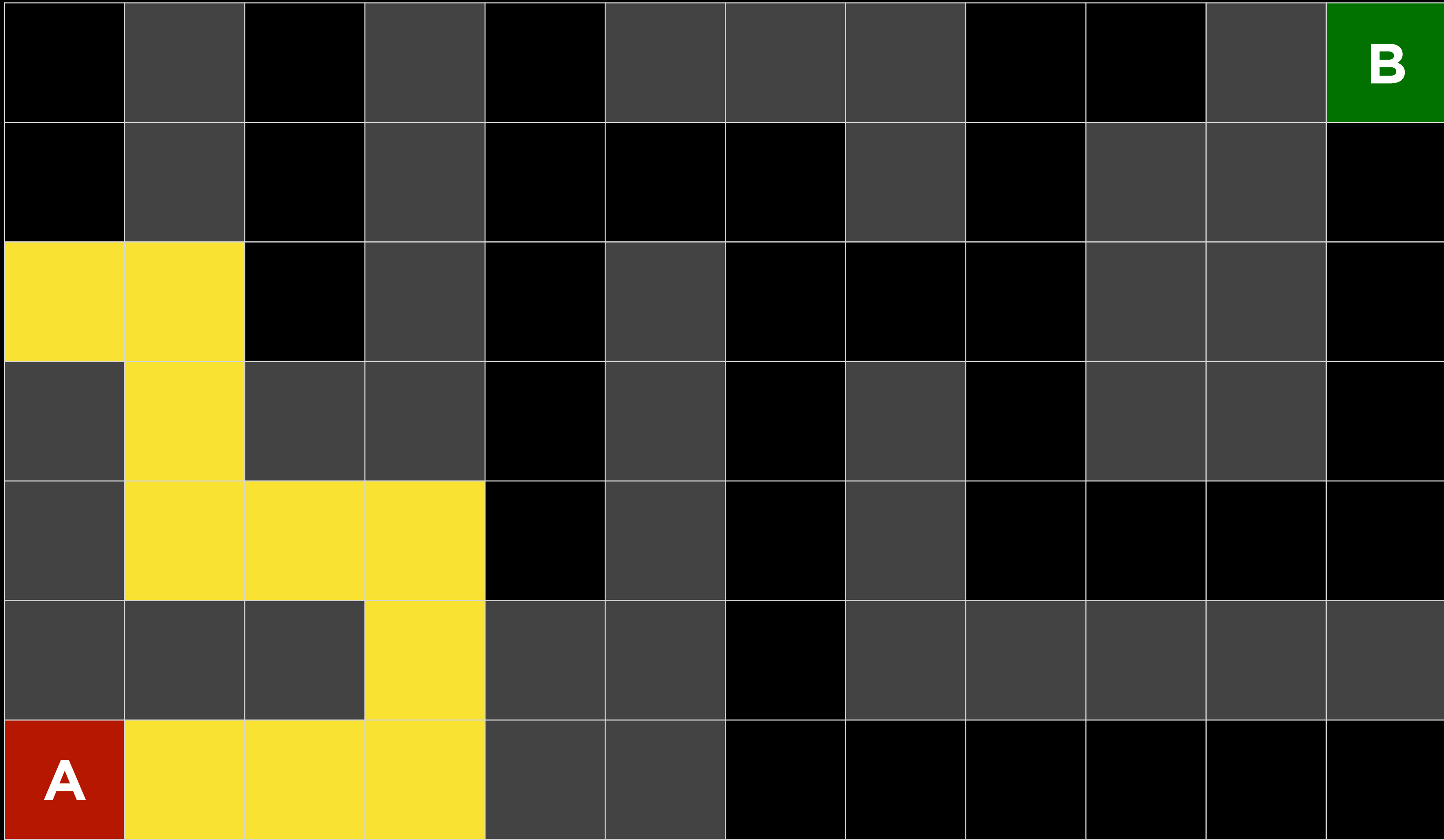
Depth-First Search



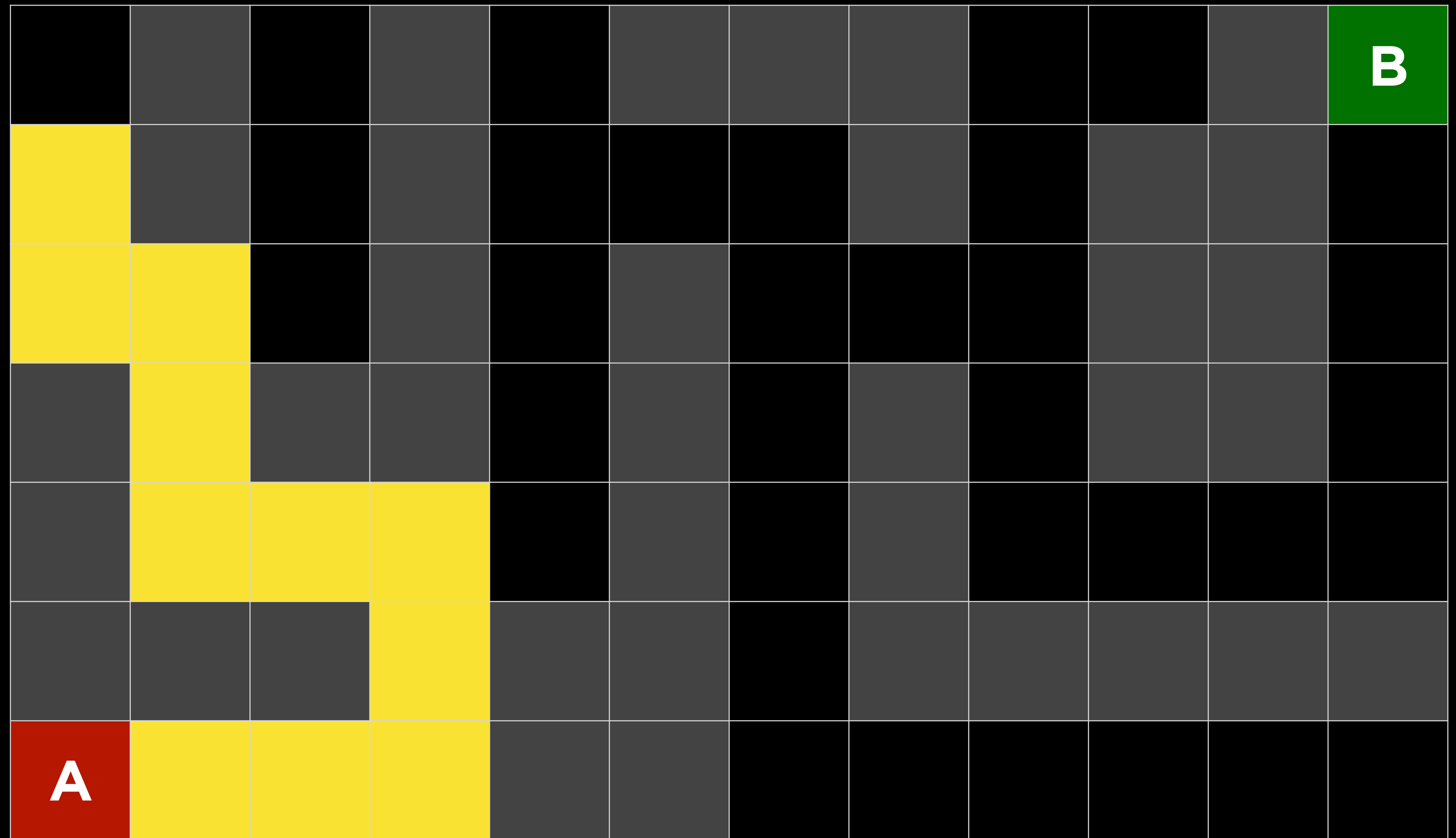
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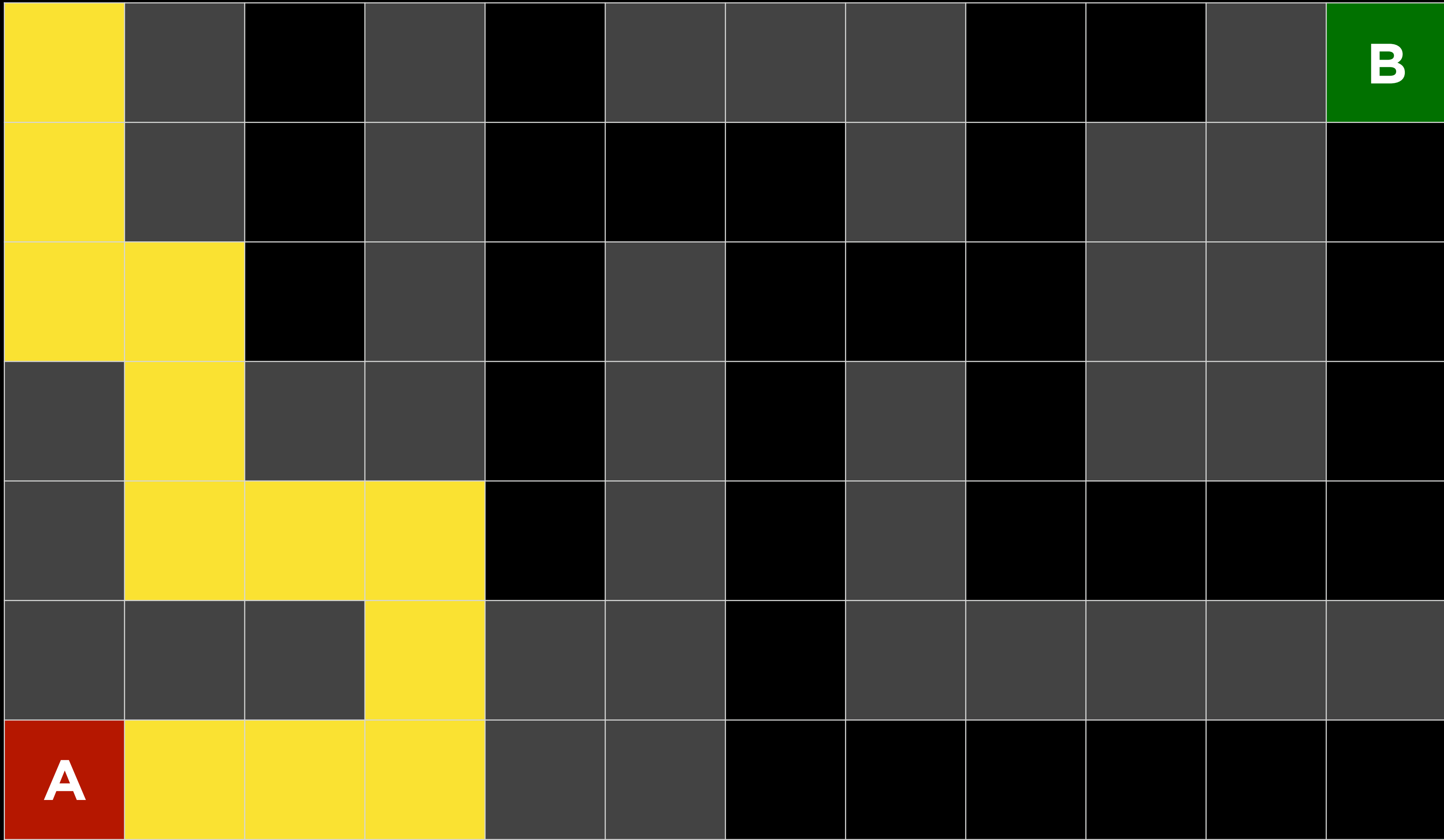
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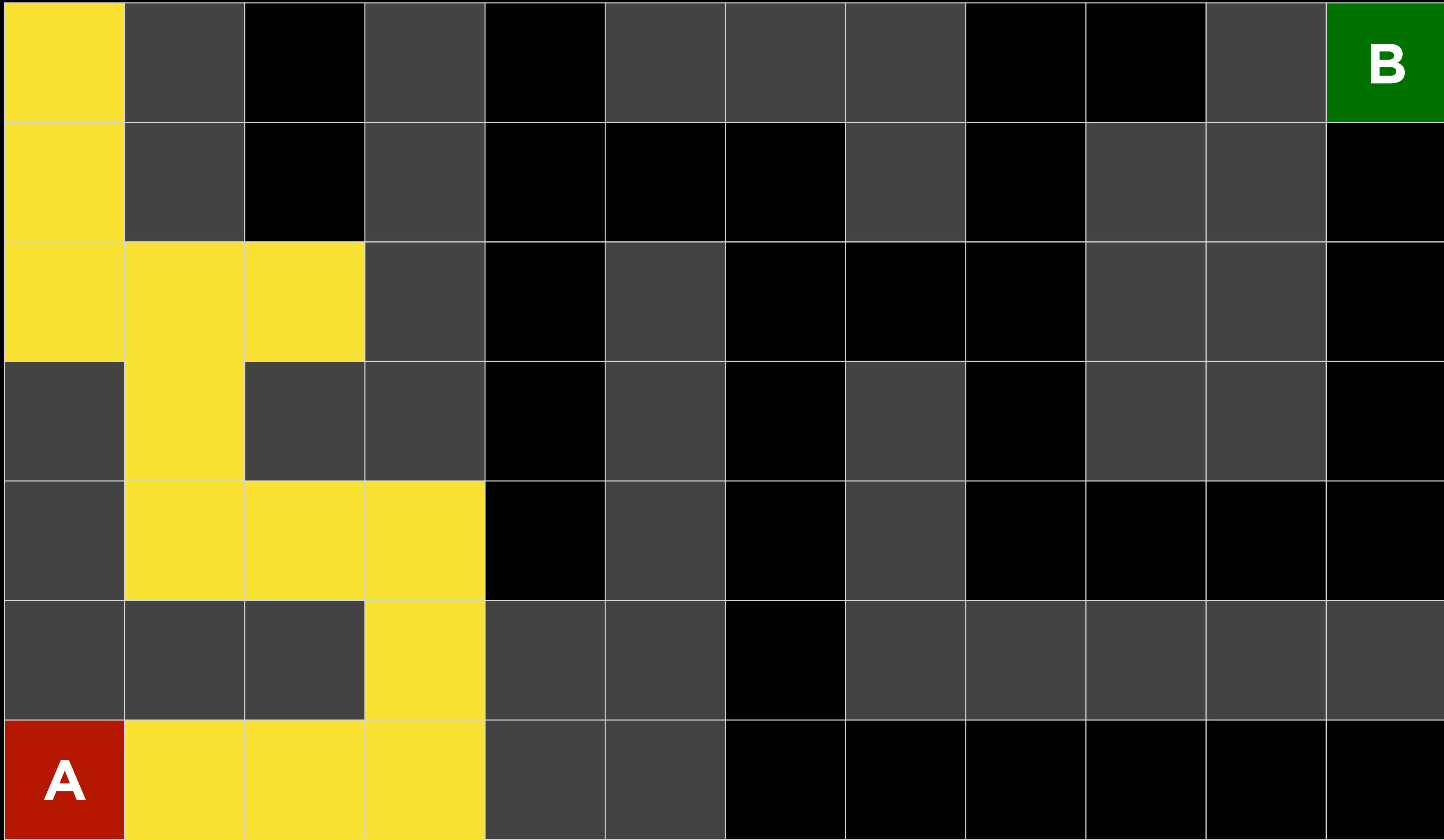
Depth-First Search



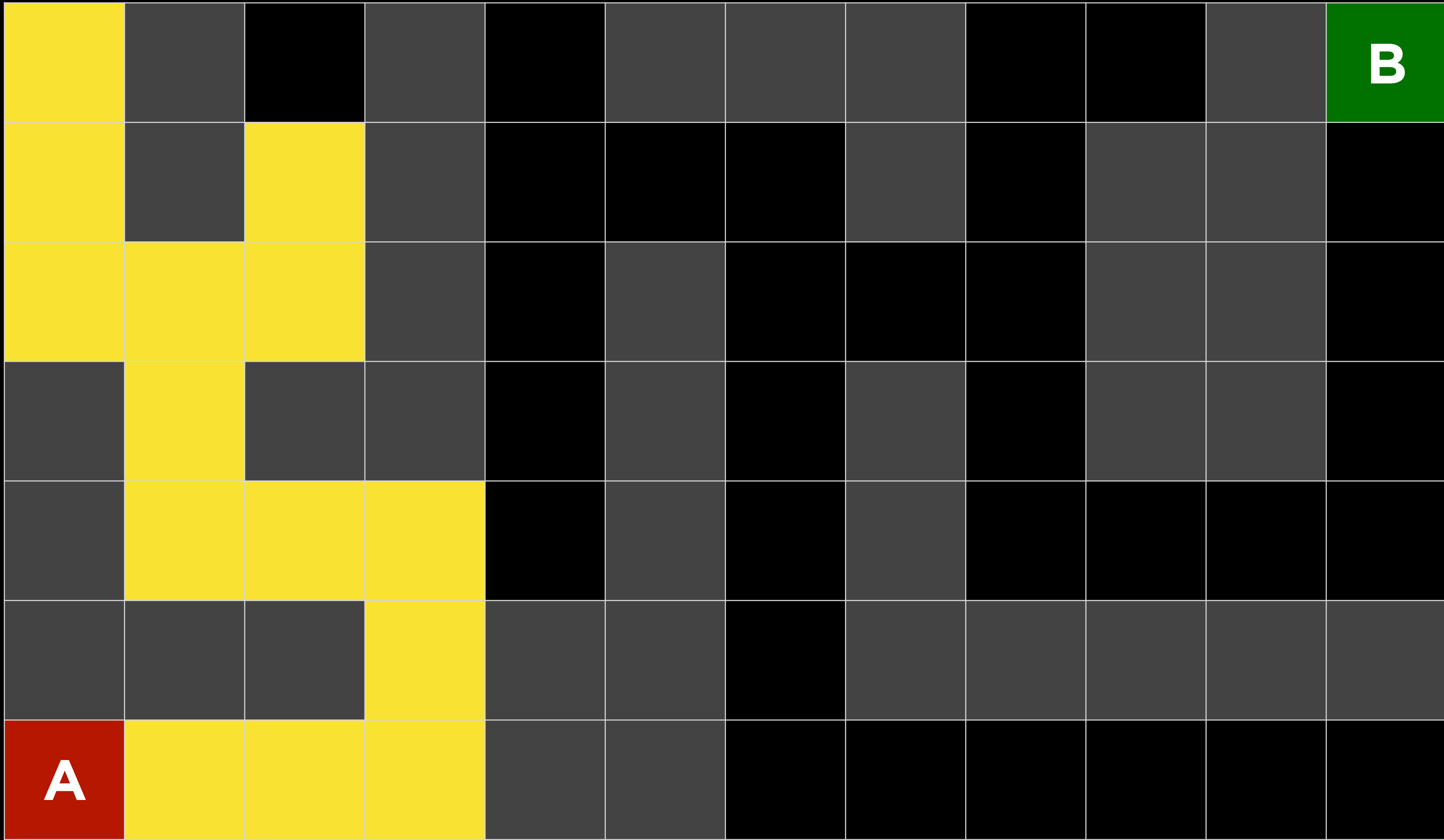
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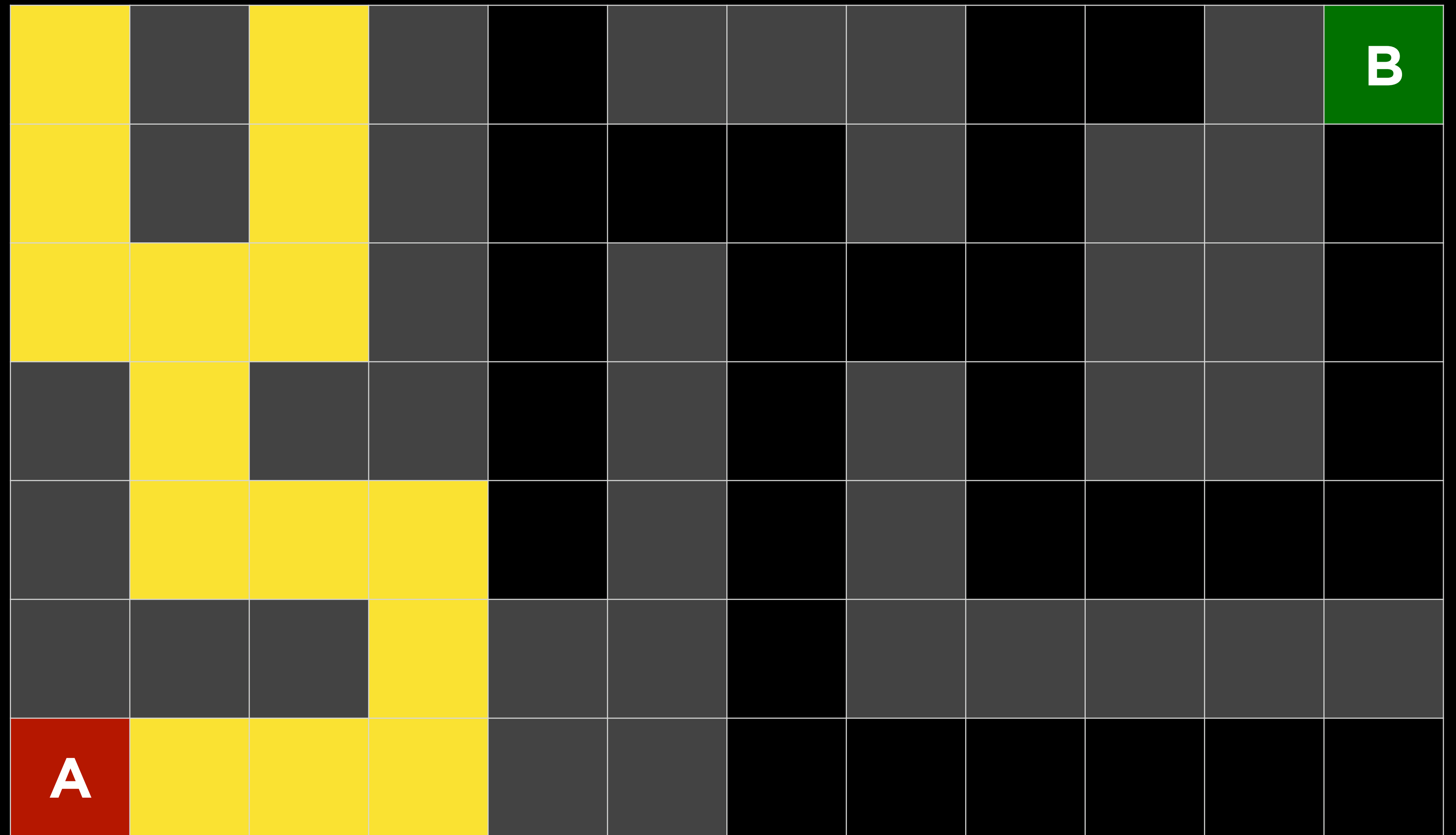
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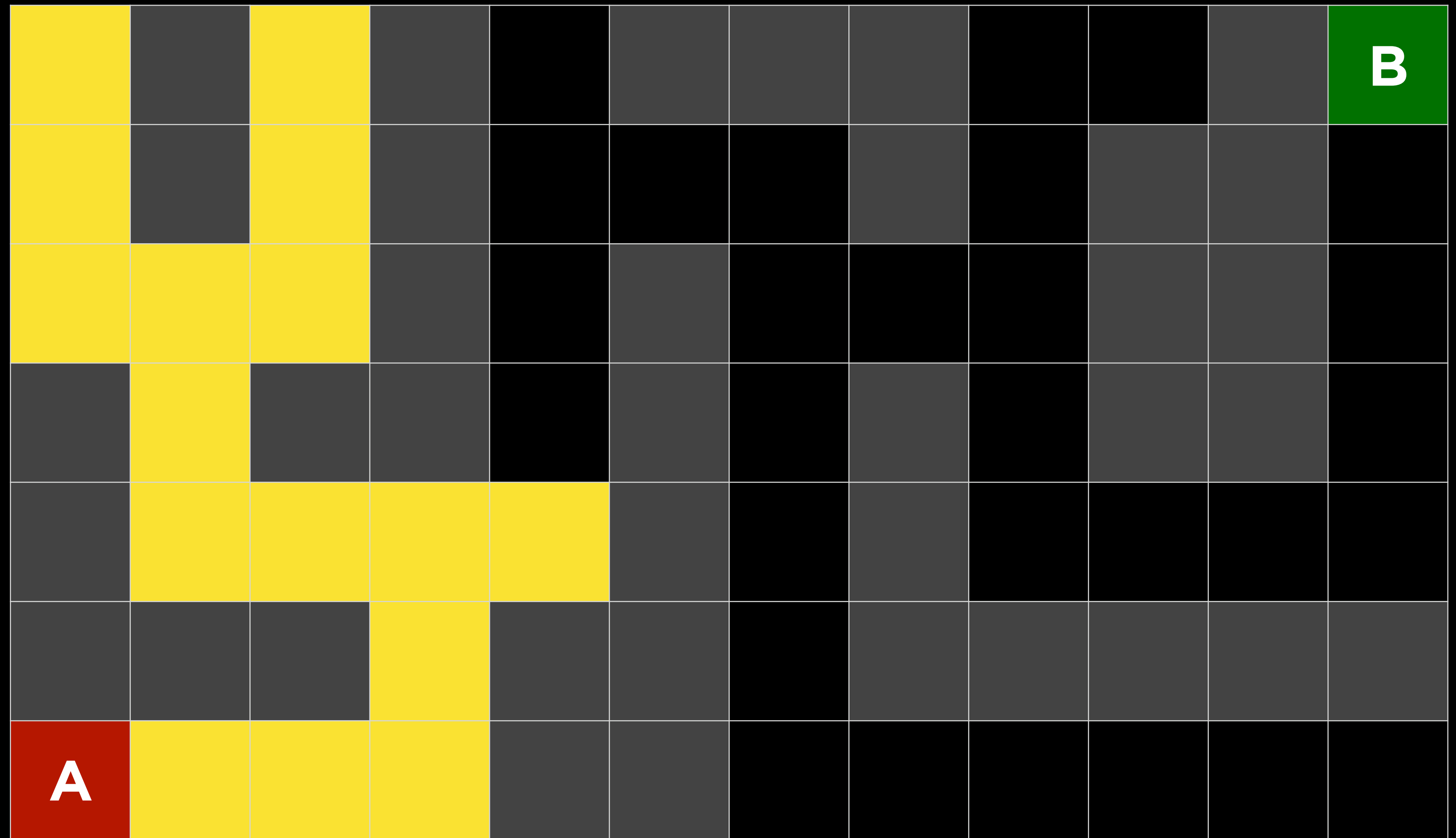
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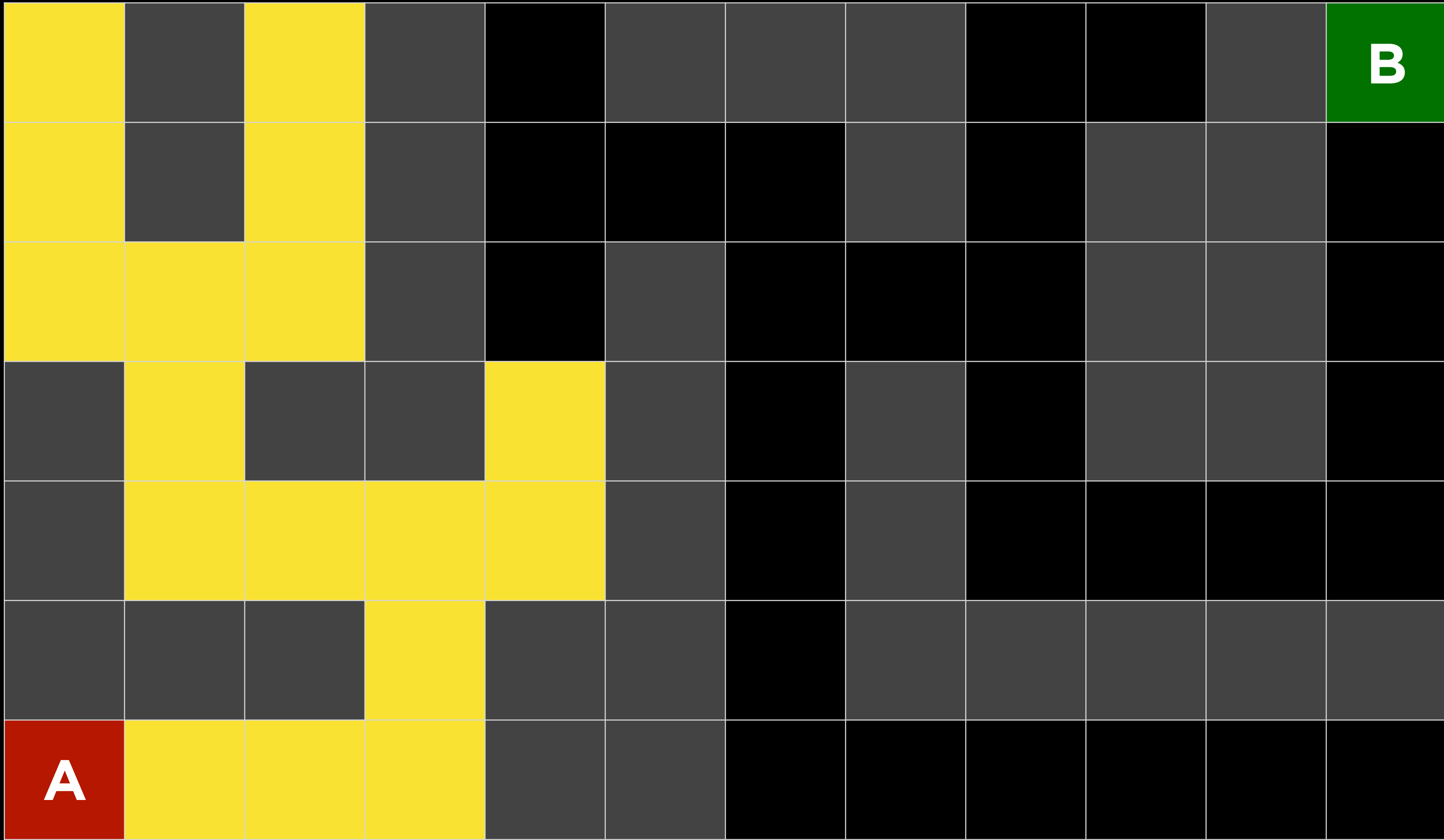
Depth-First Search



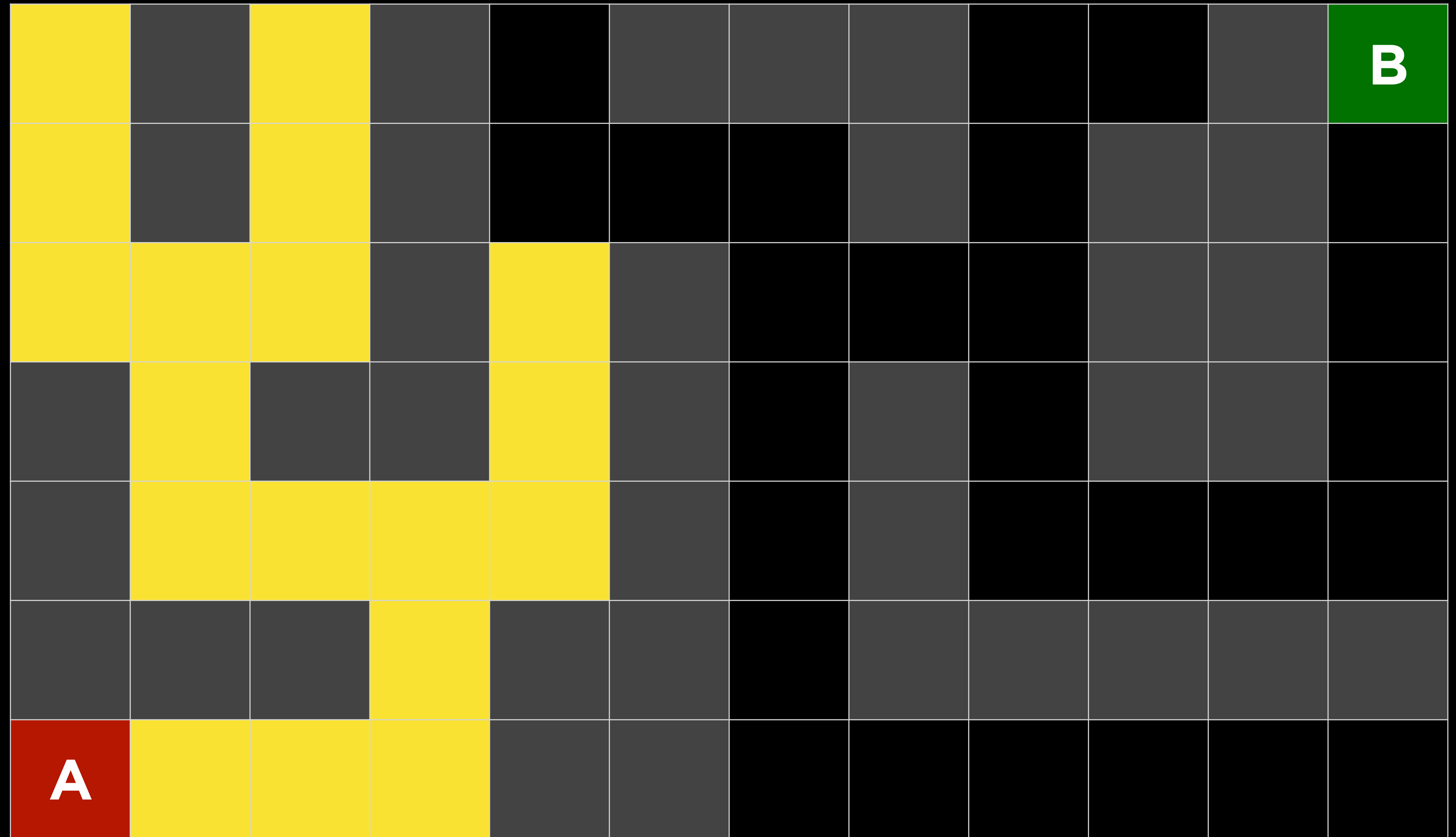
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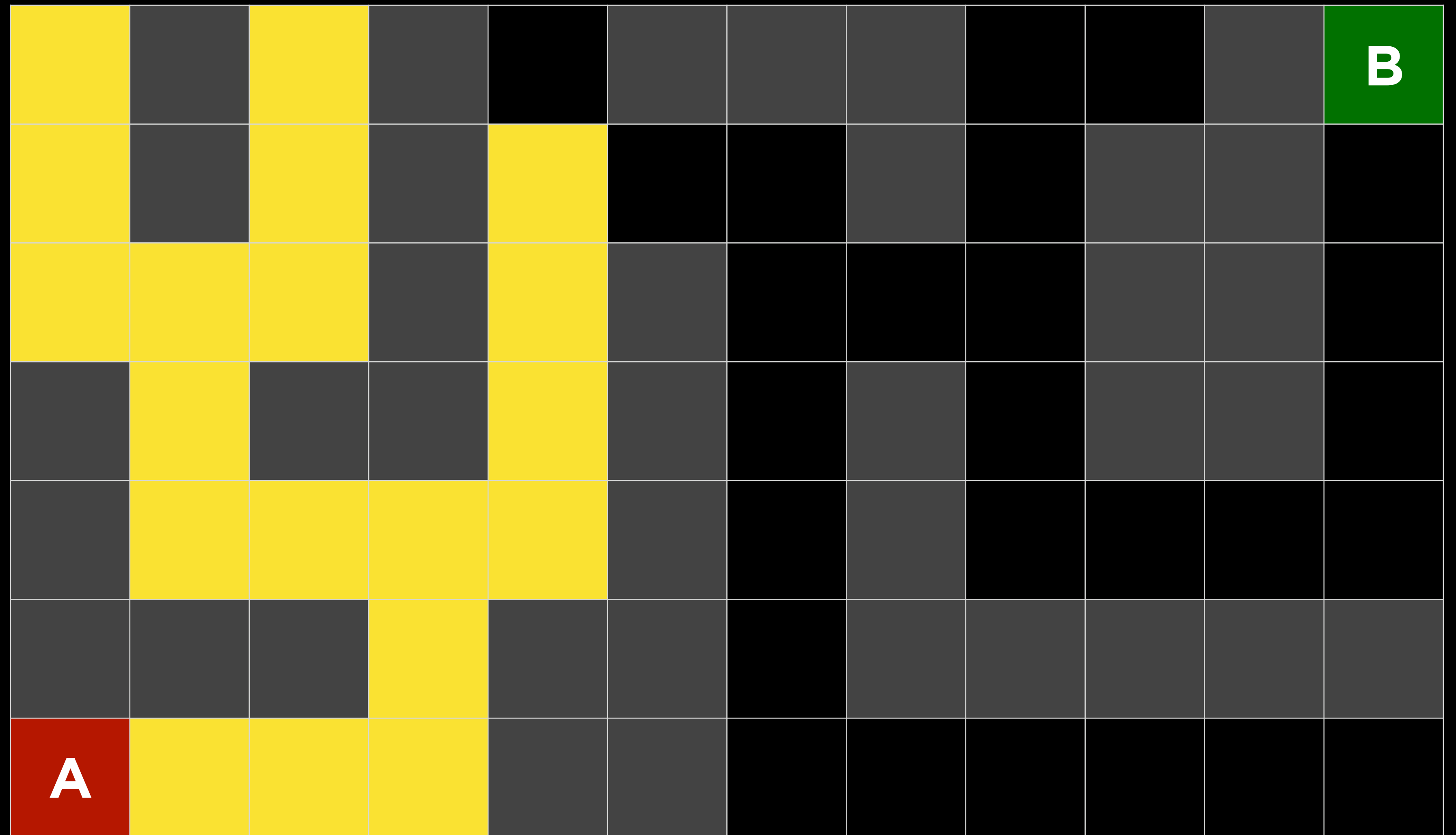
Depth-First Search



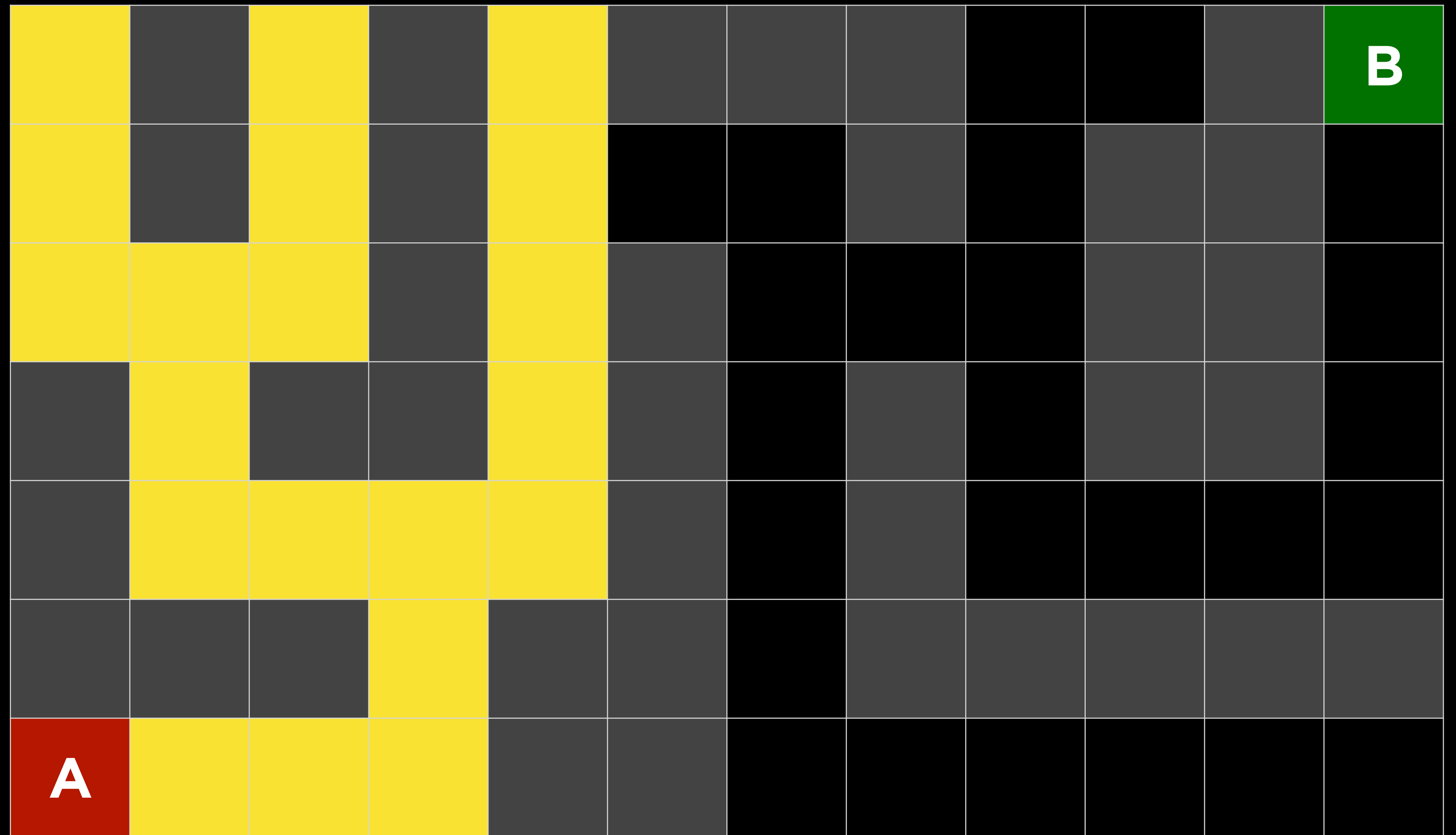
Depth-First Search



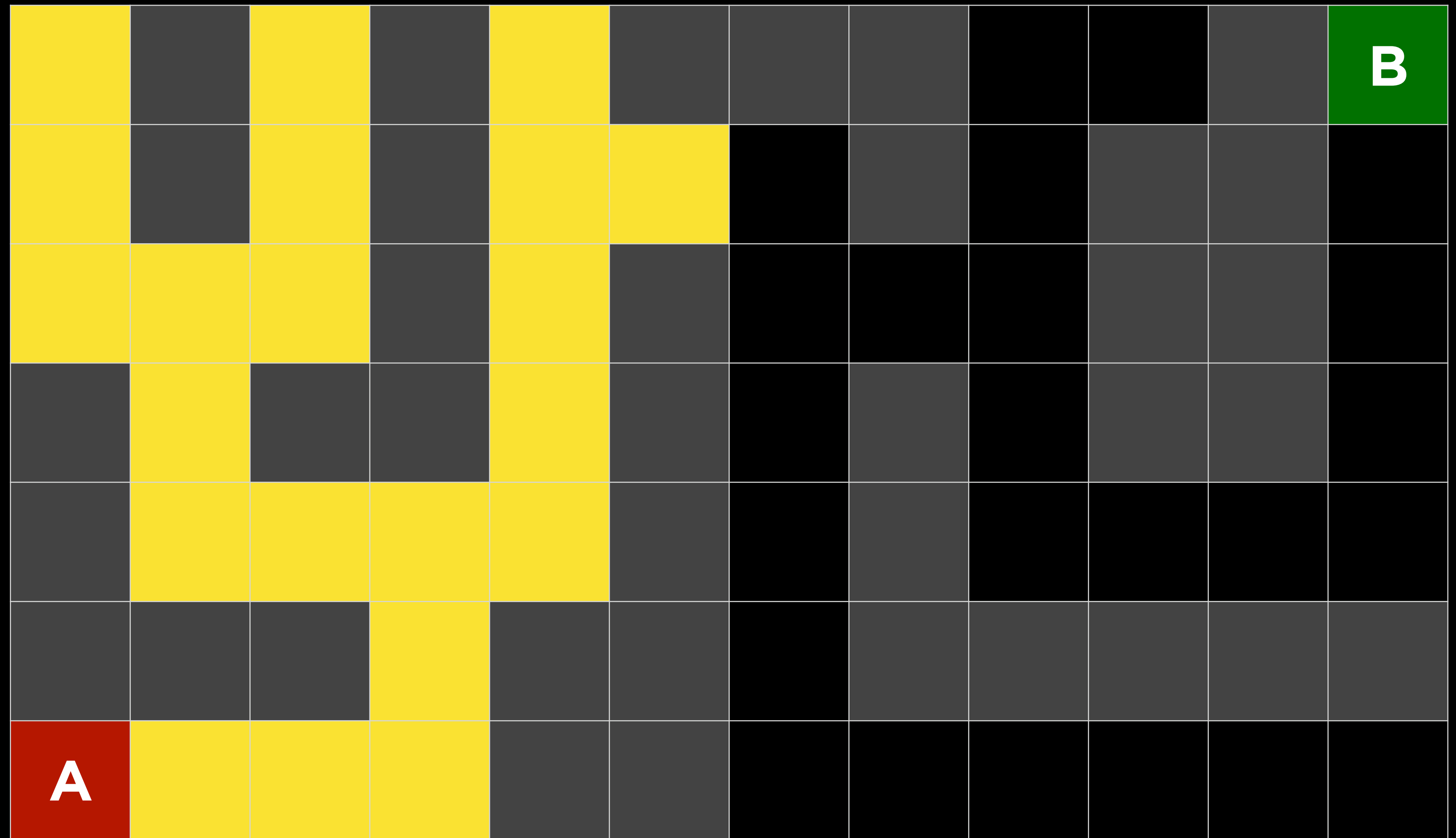
Depth-First Search



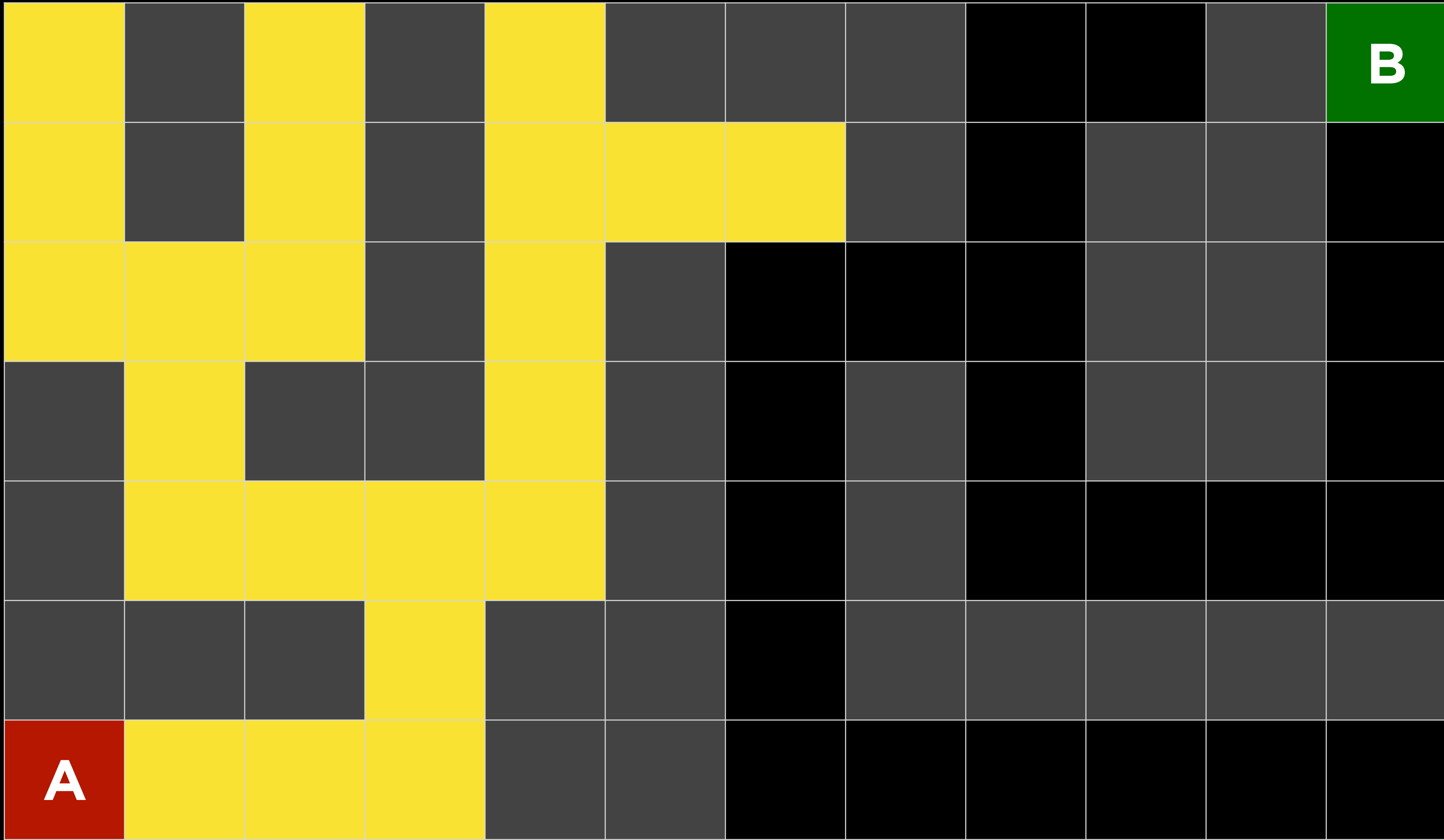
Depth-First Search



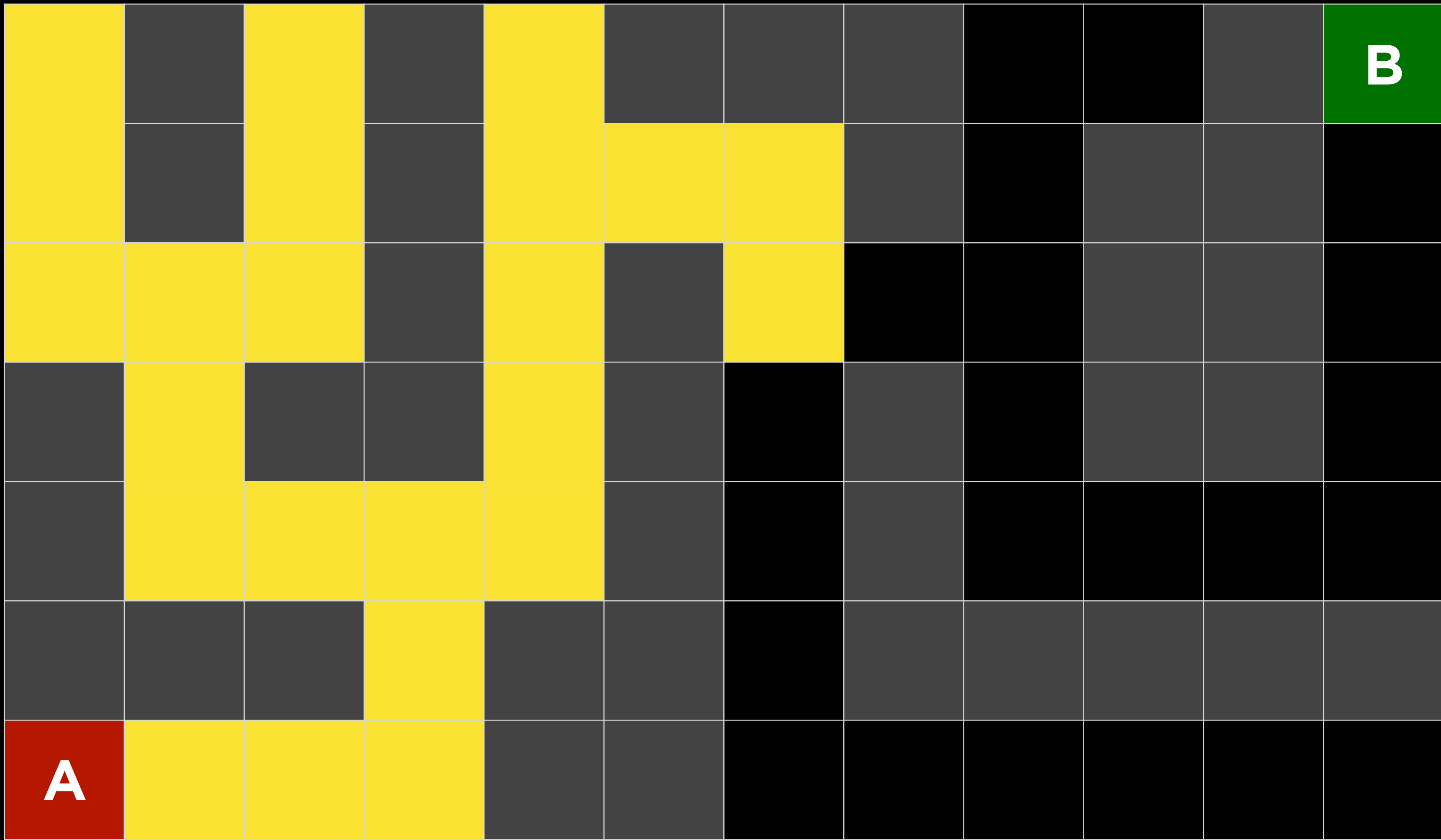
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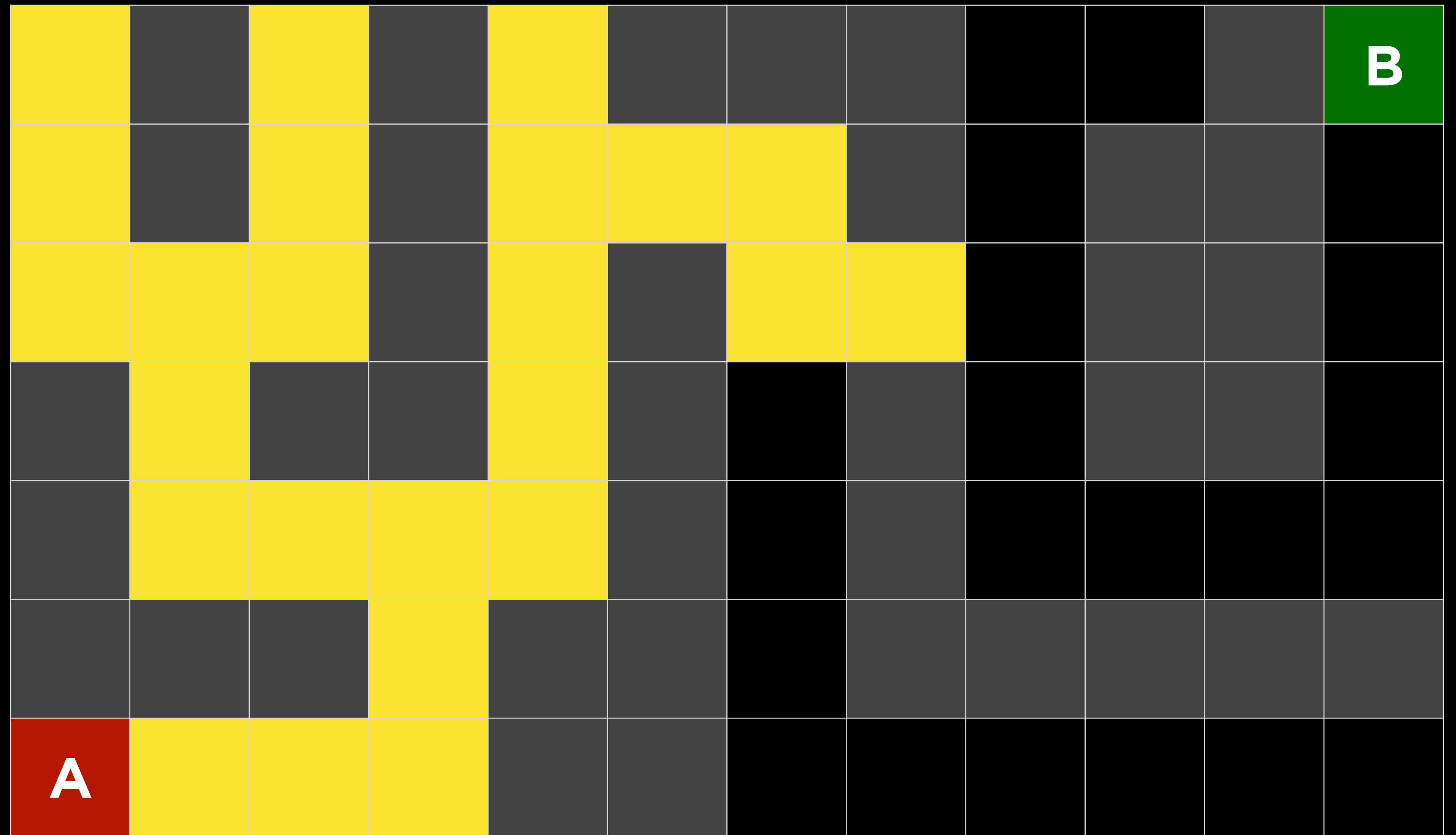
Depth-First Search



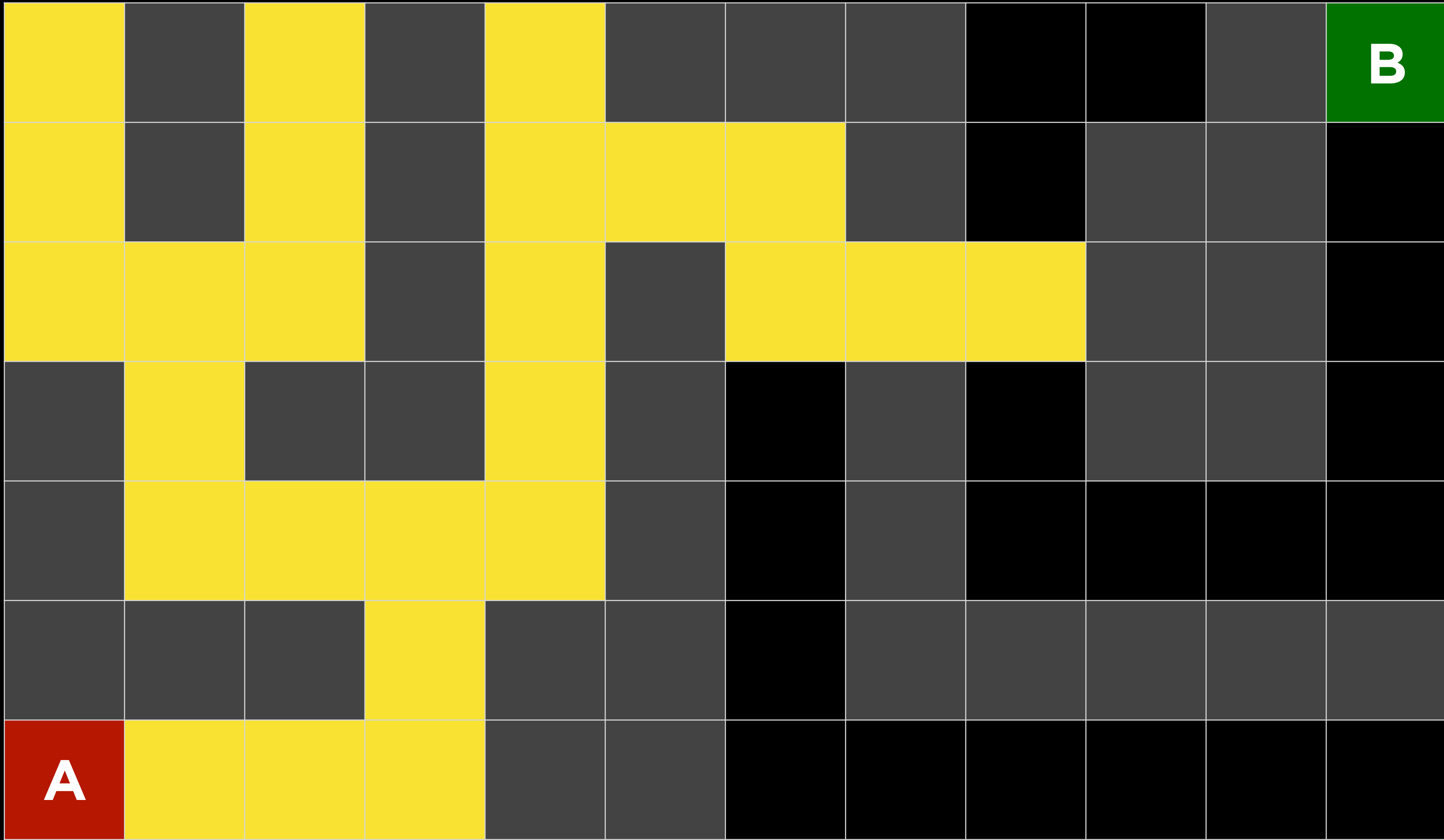
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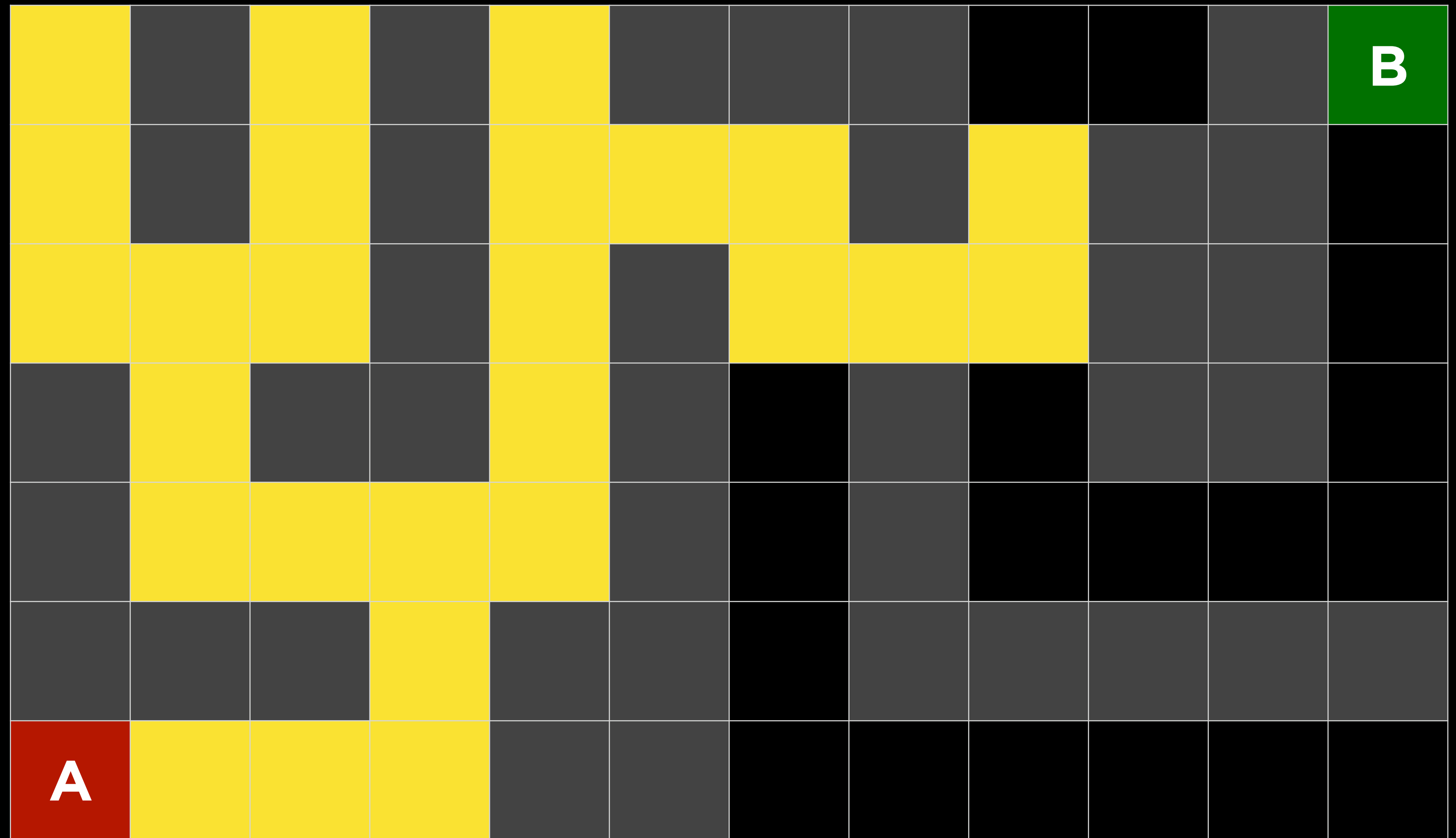
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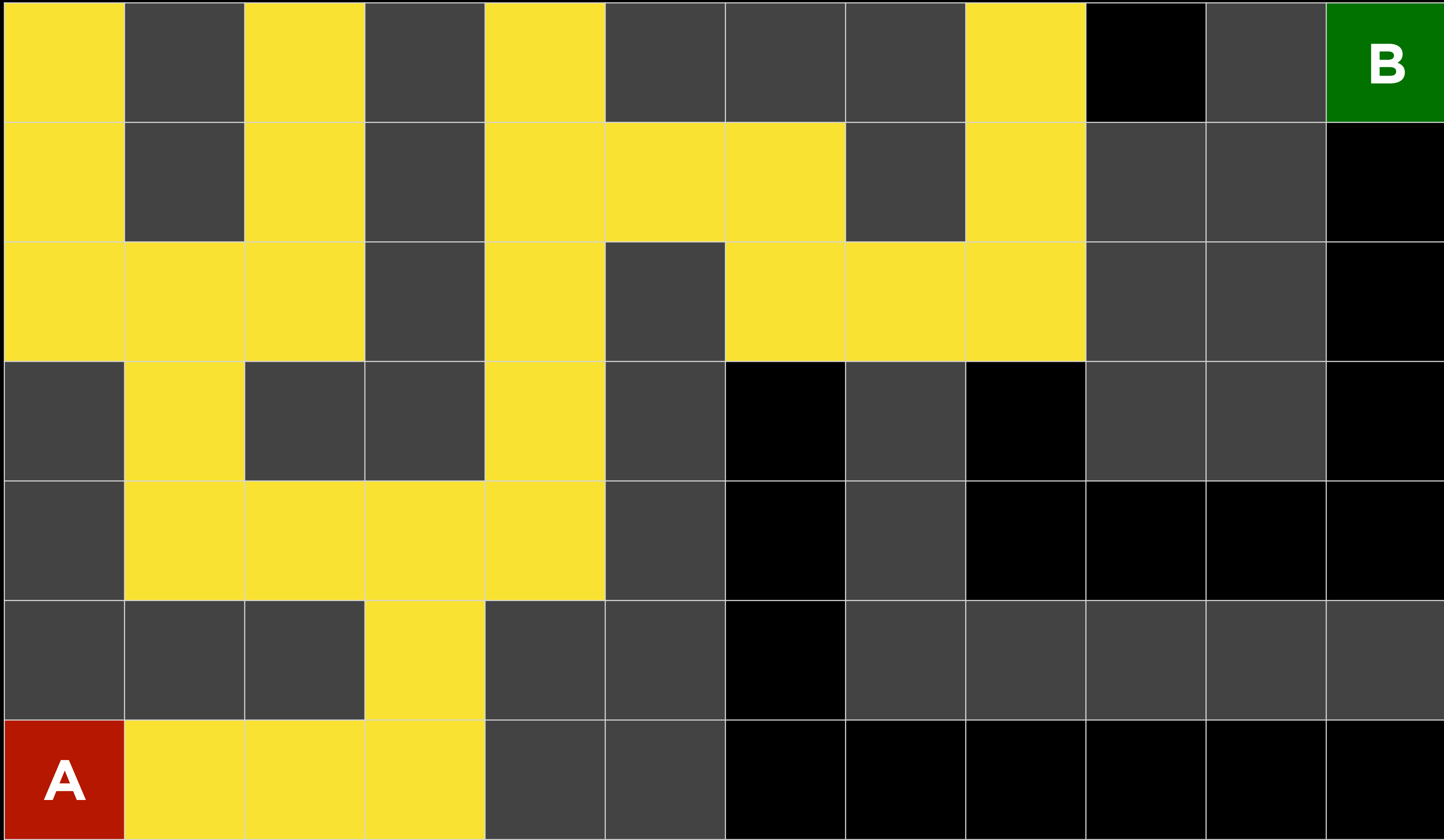
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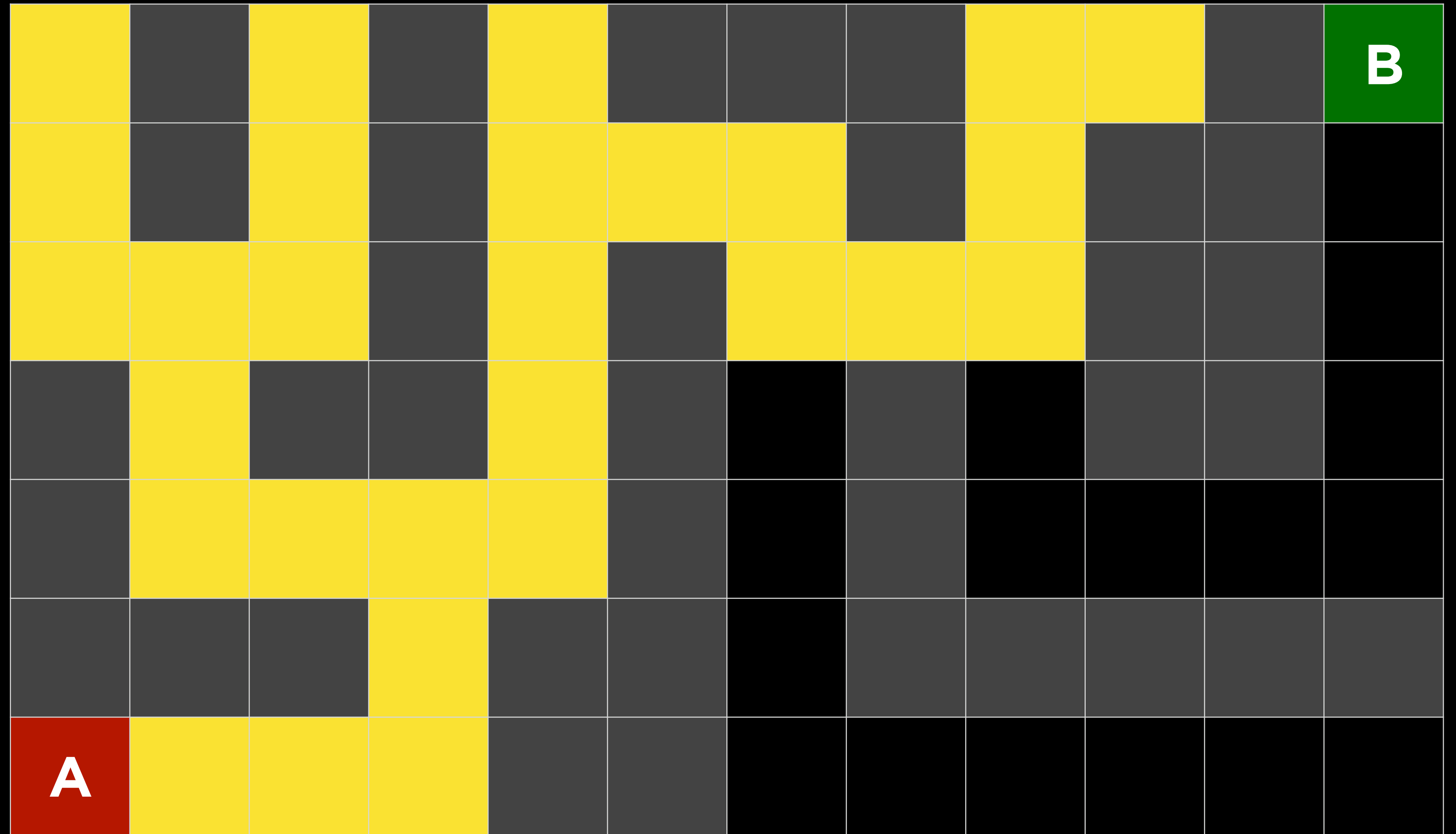
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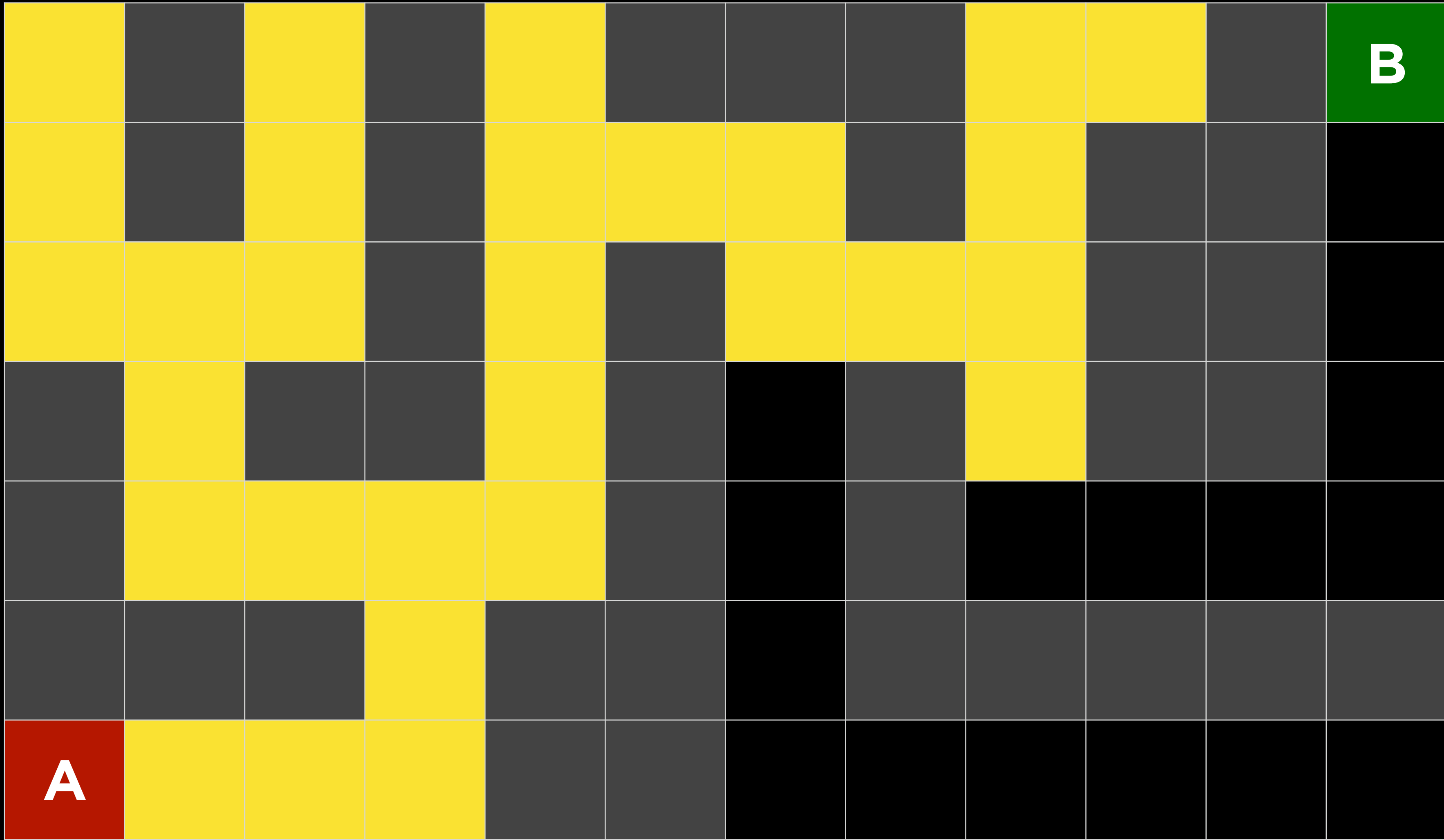
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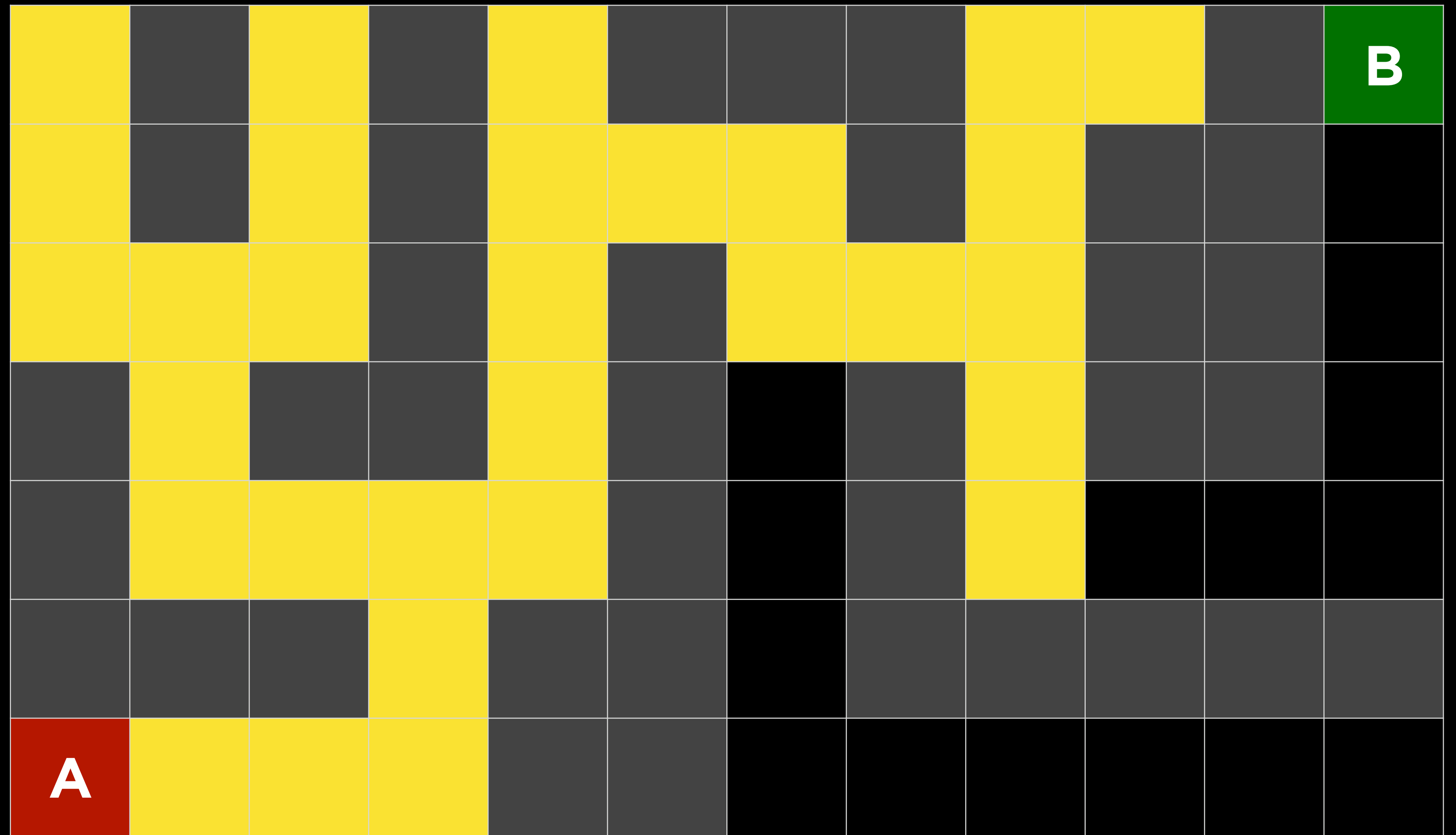
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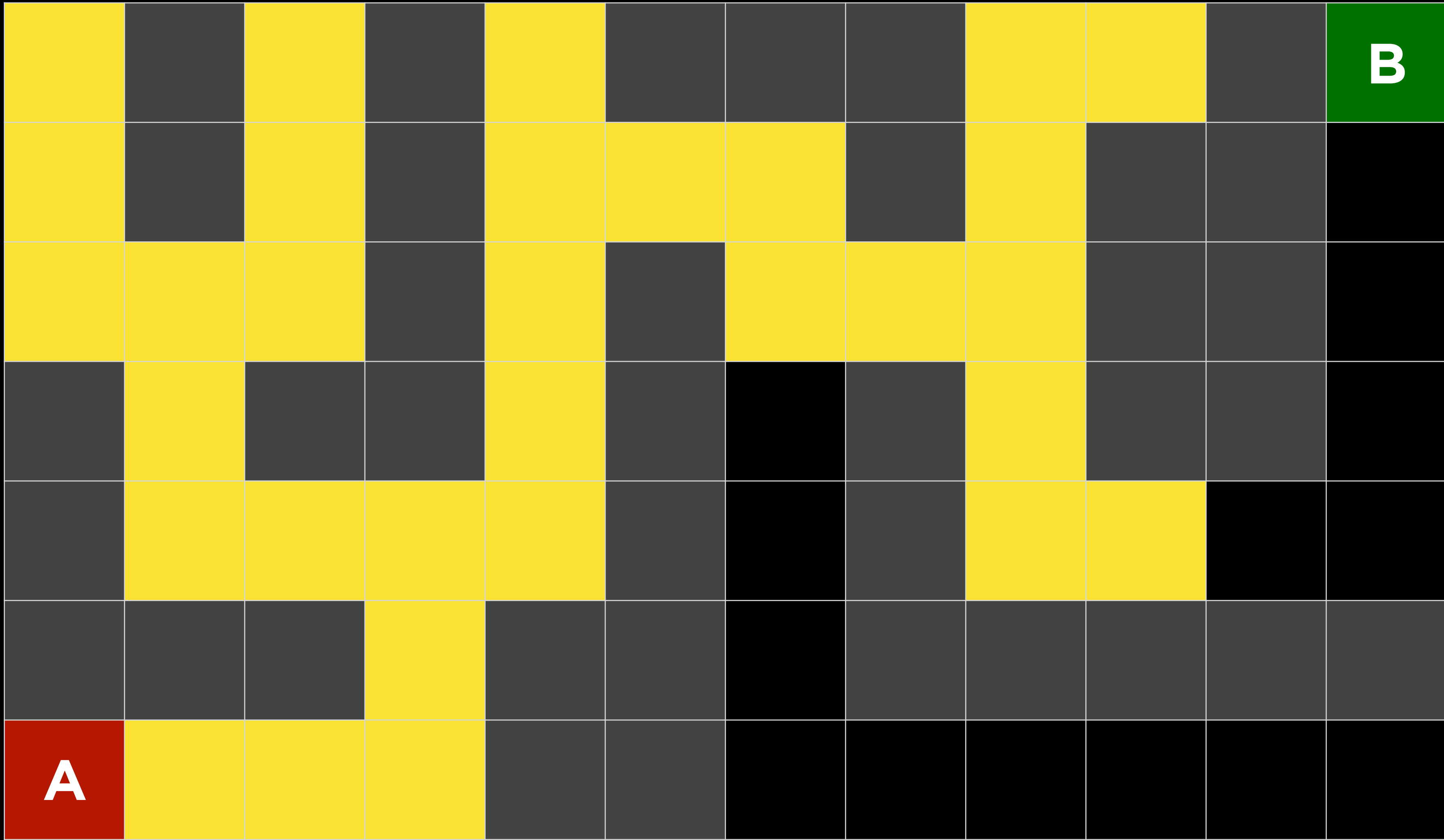
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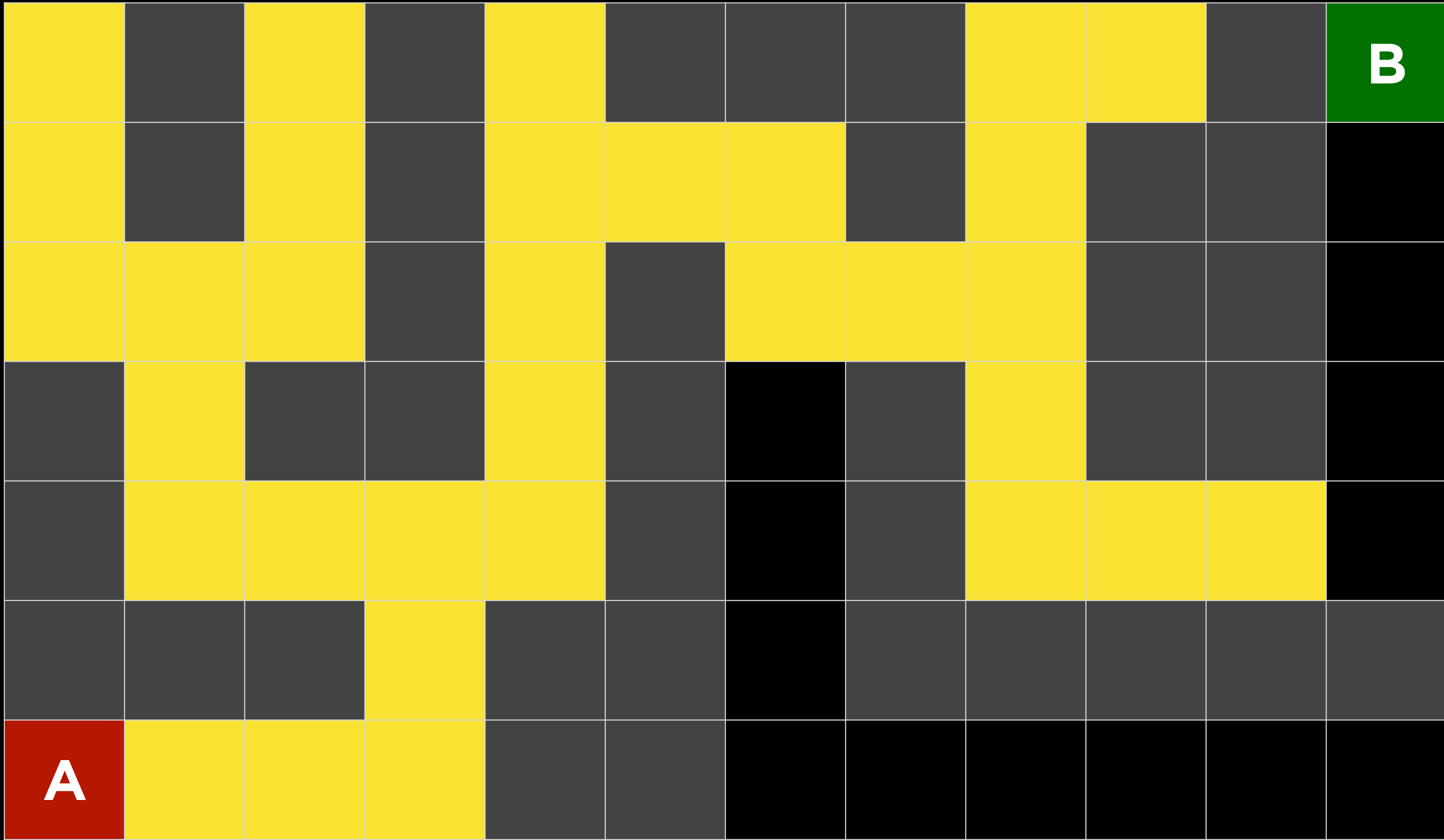
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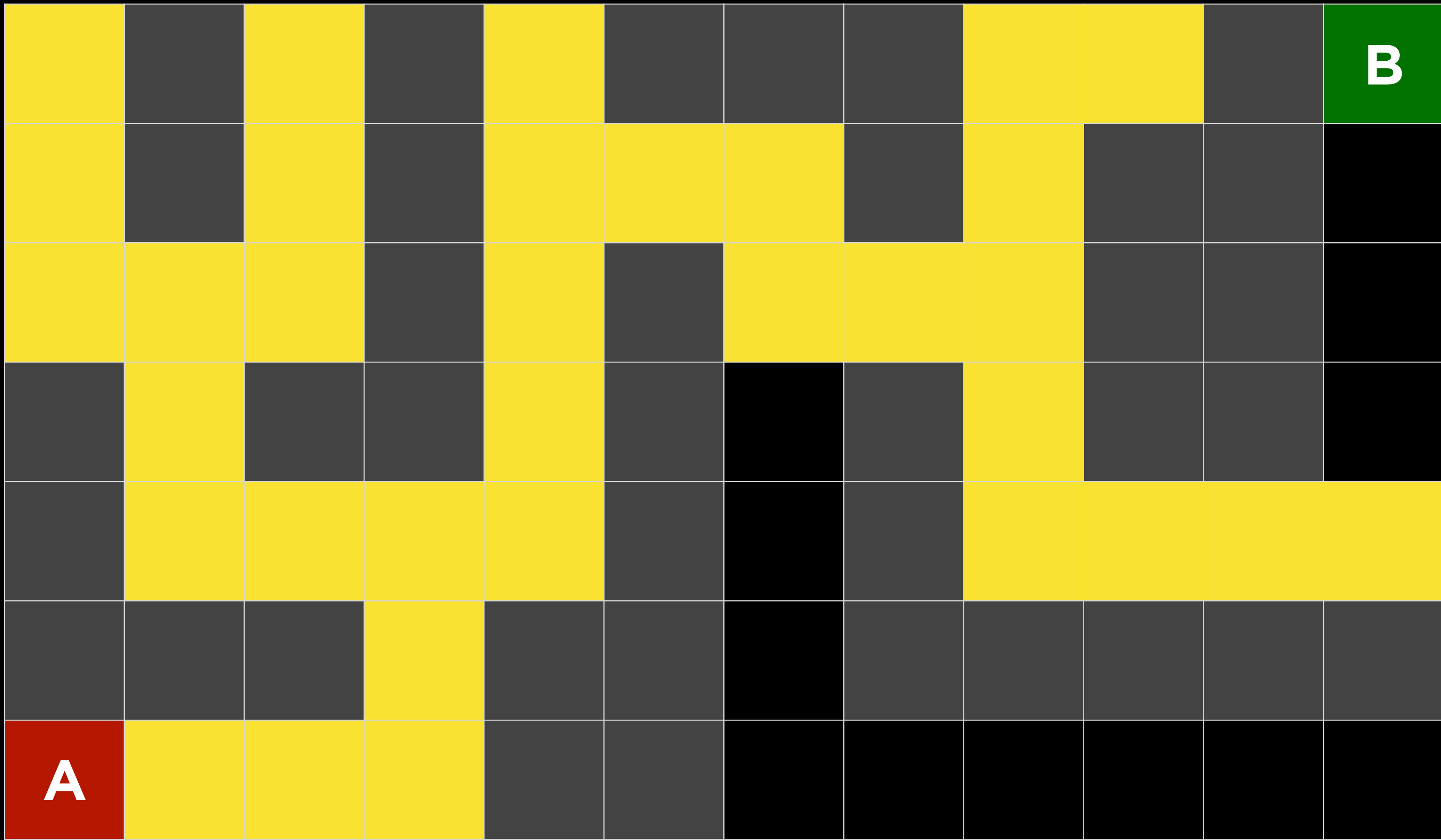
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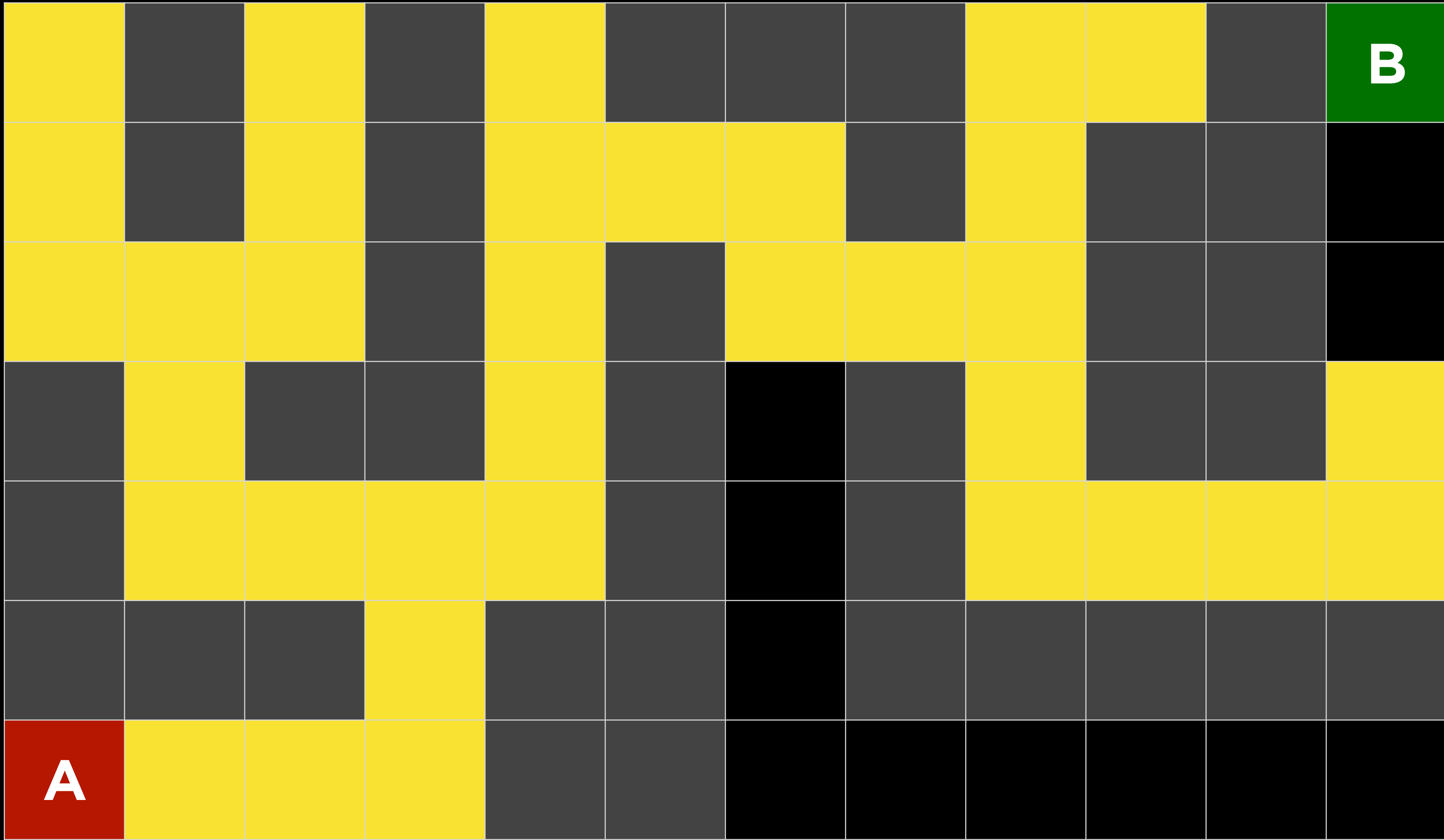
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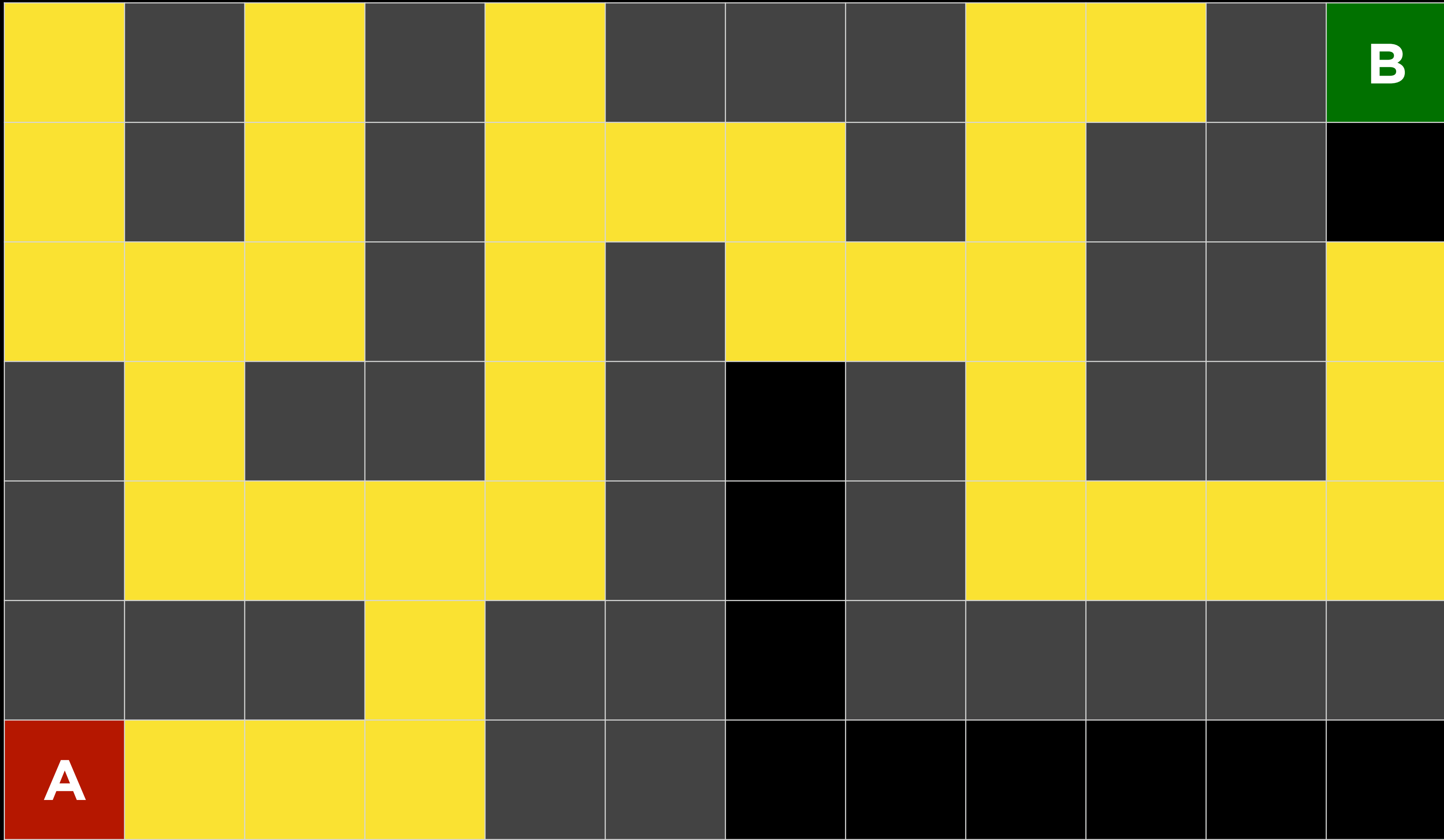
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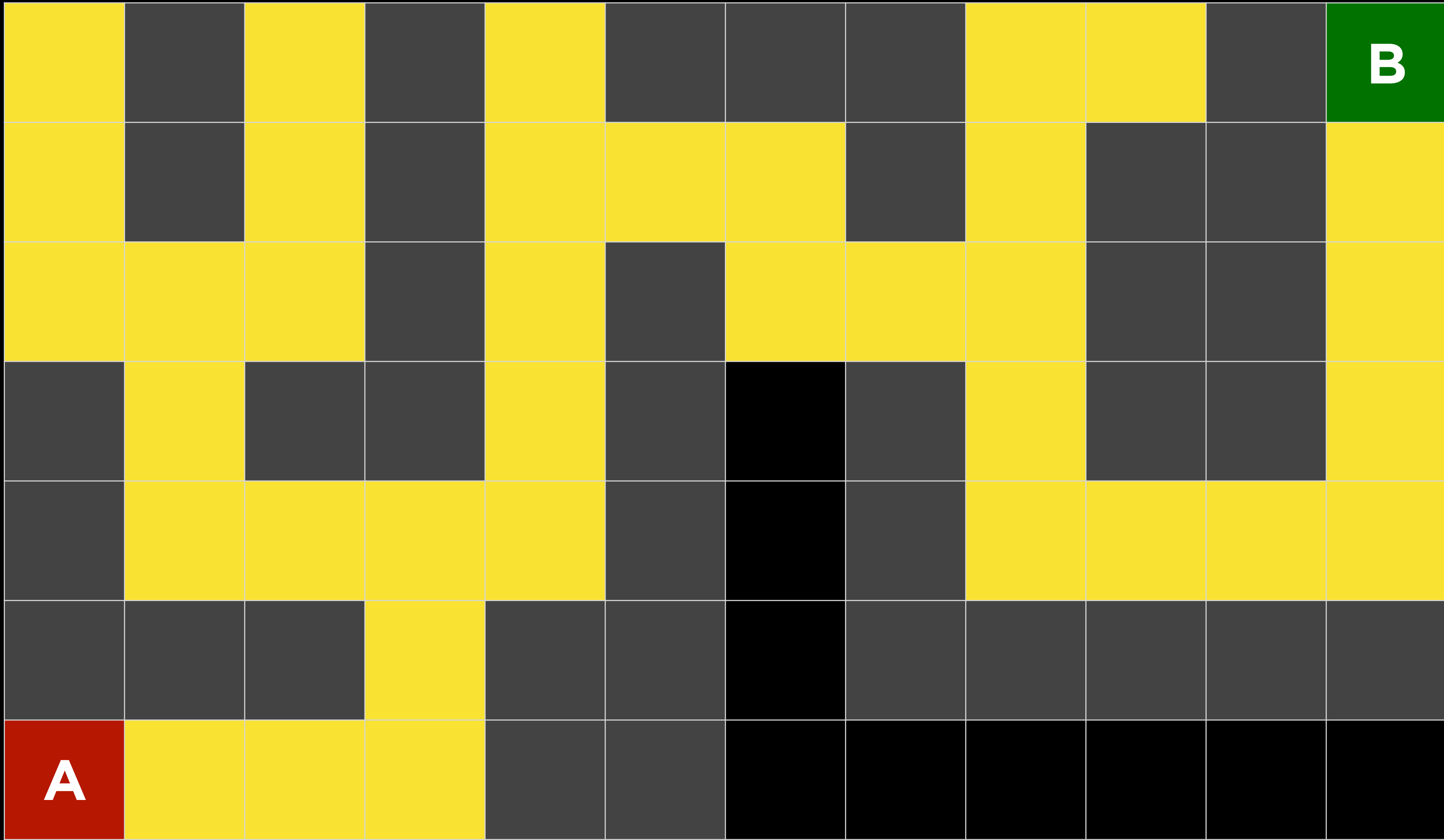
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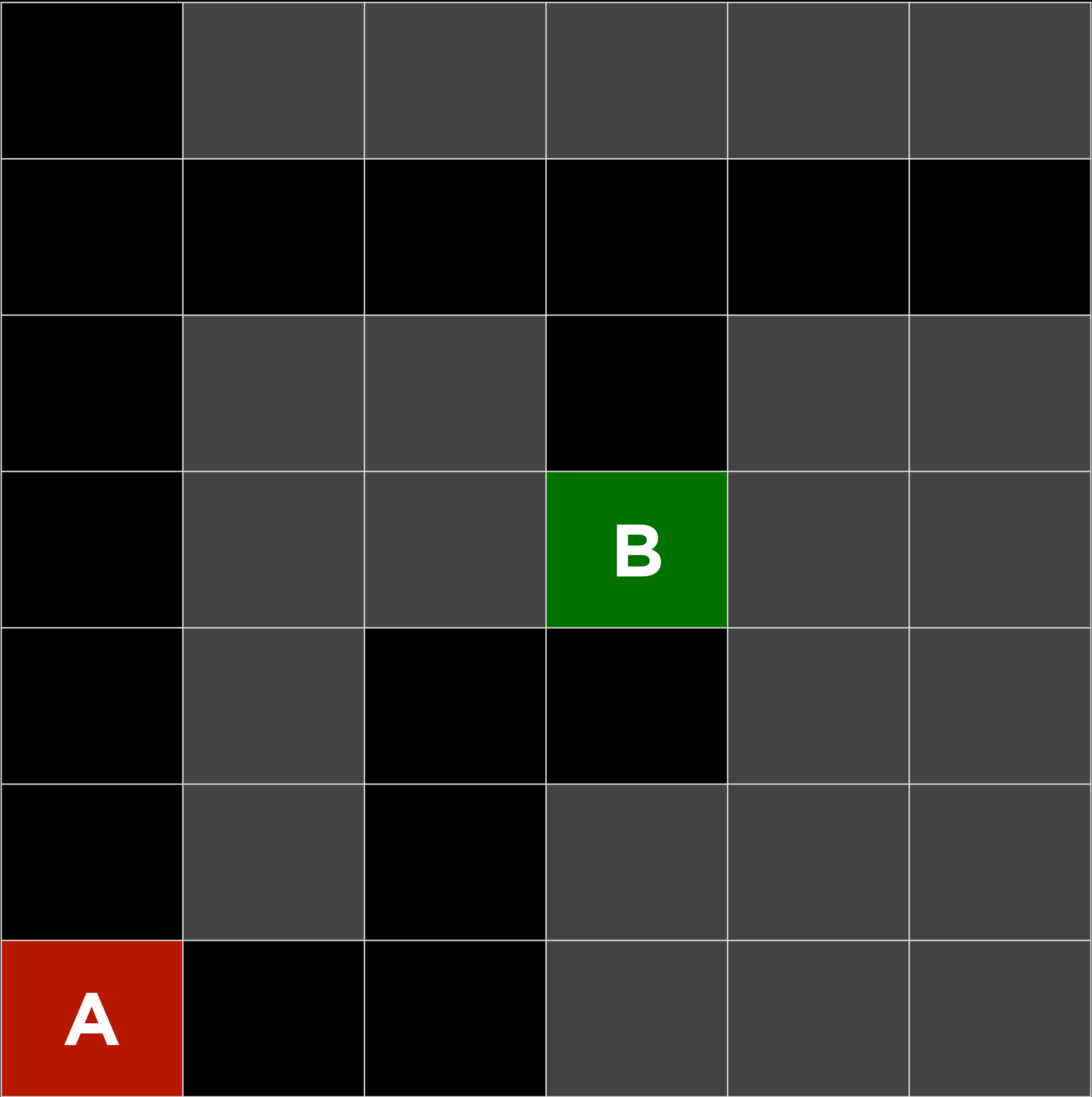
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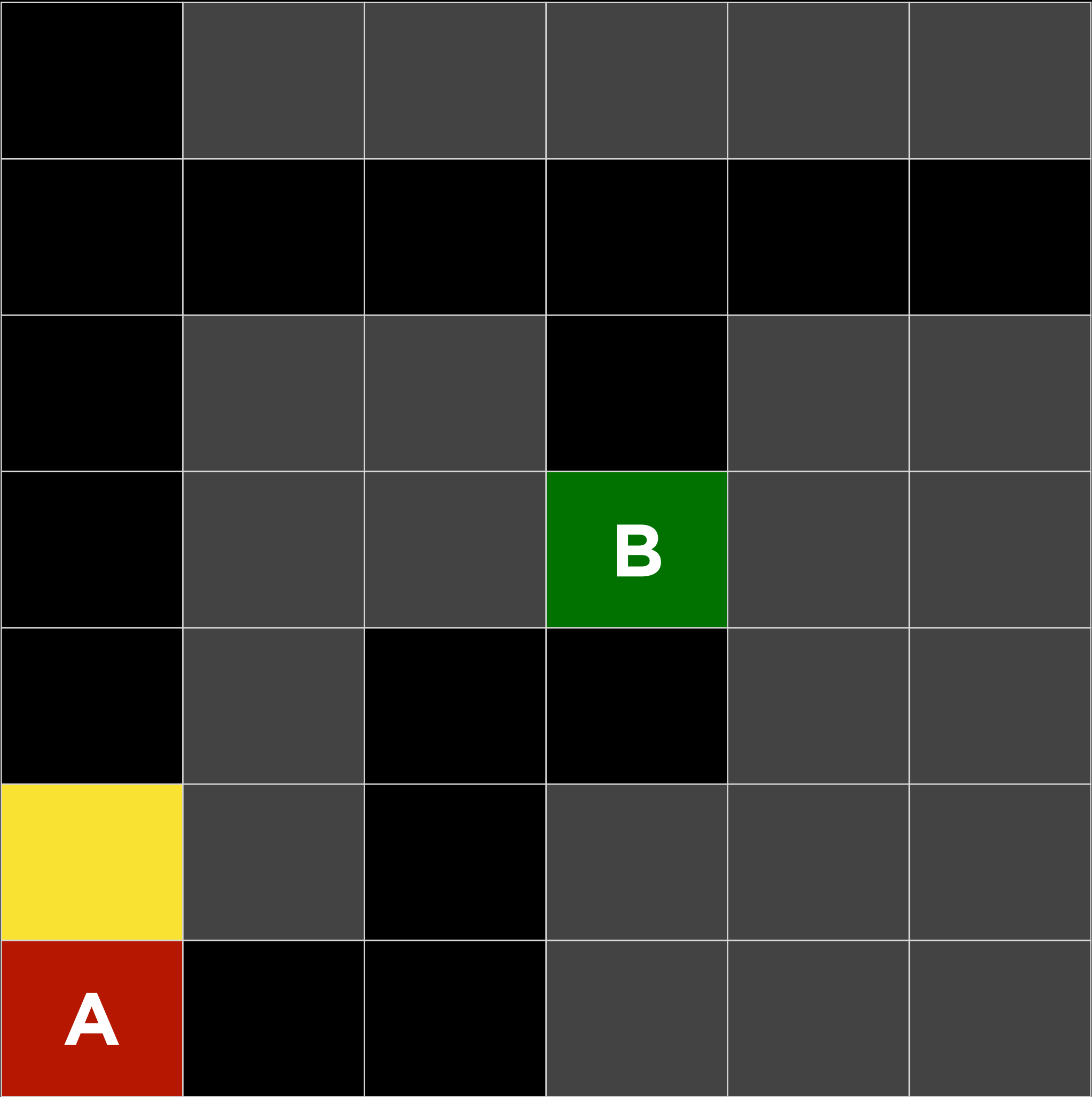
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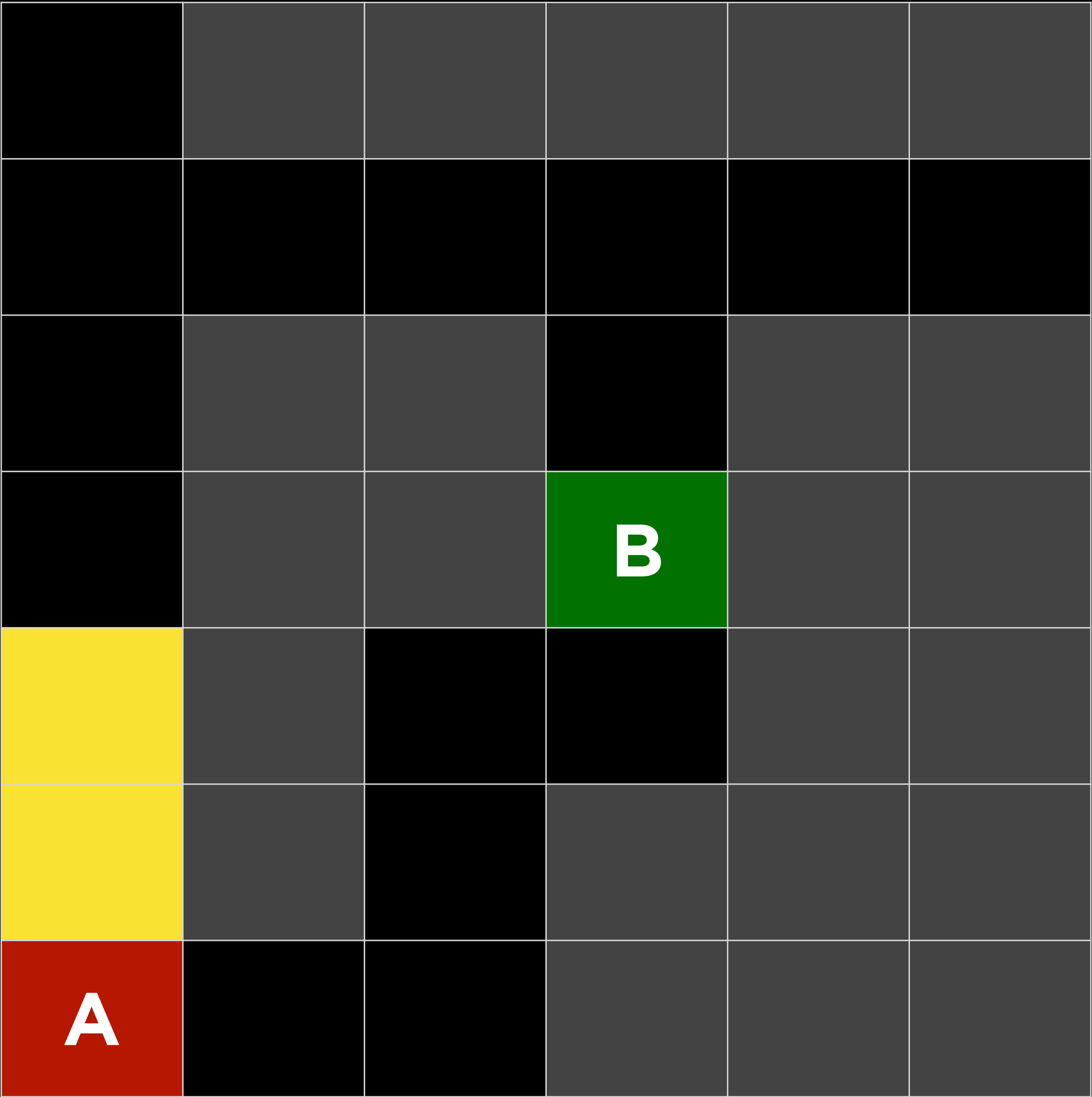
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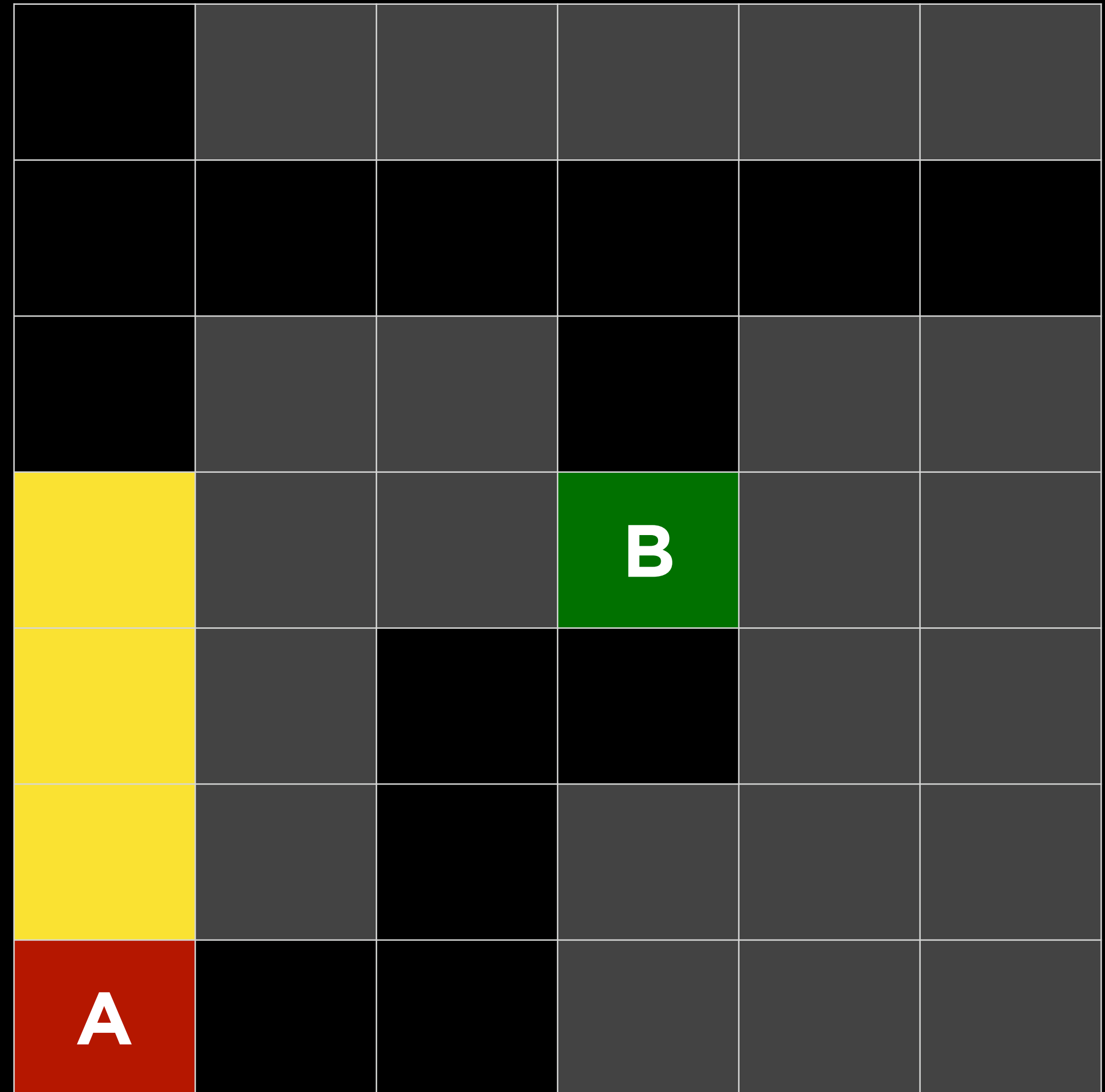
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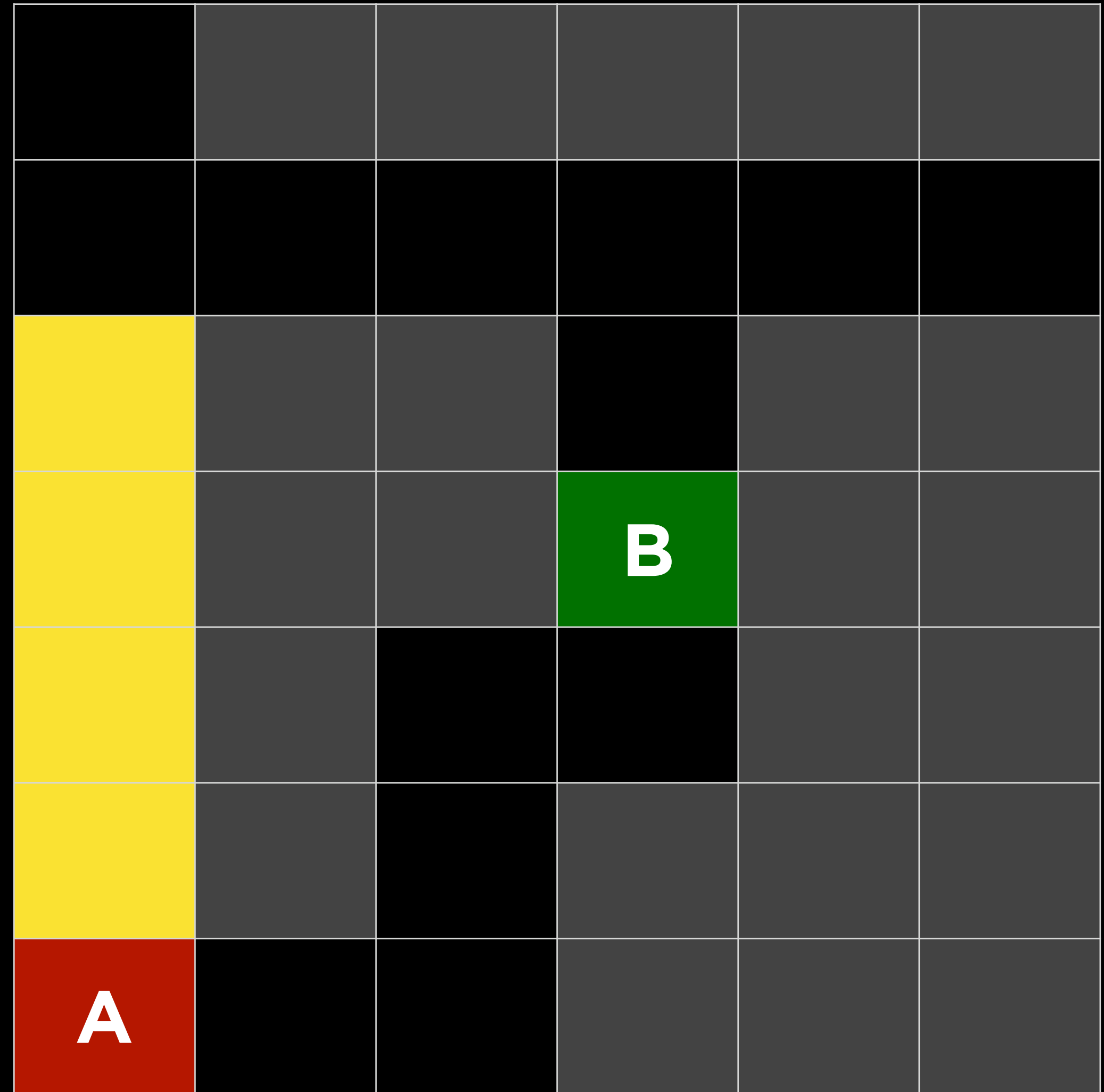
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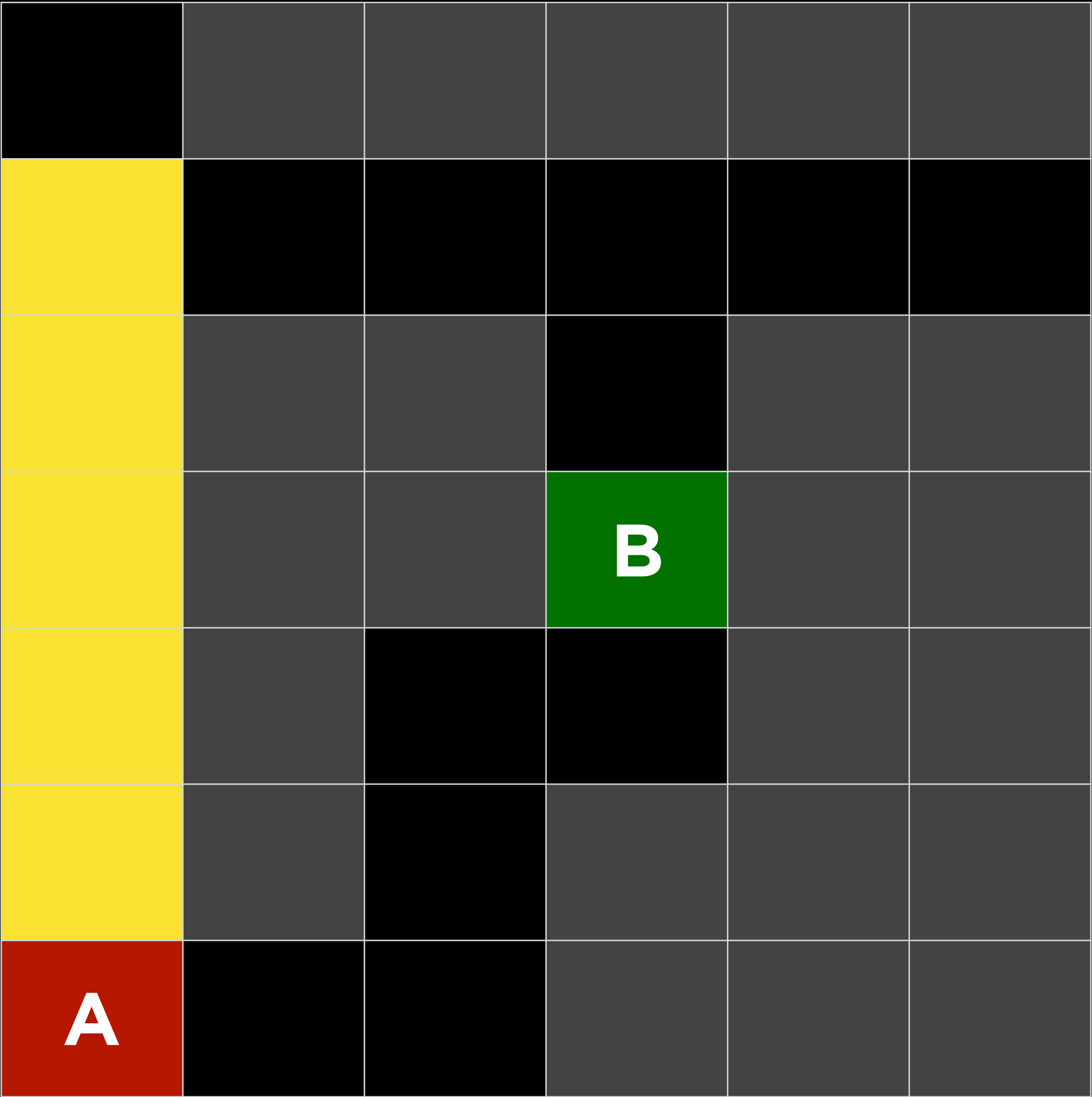
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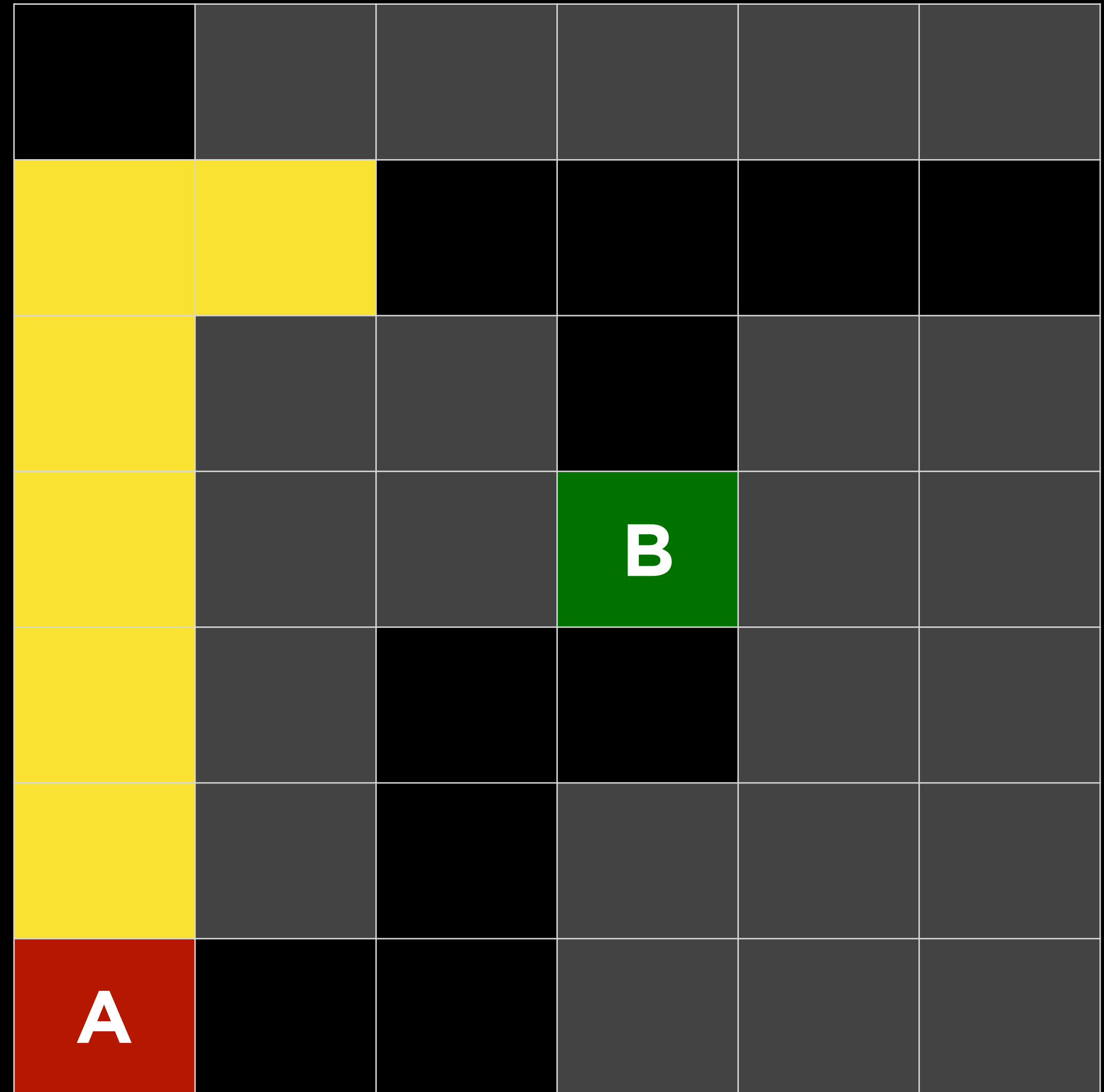
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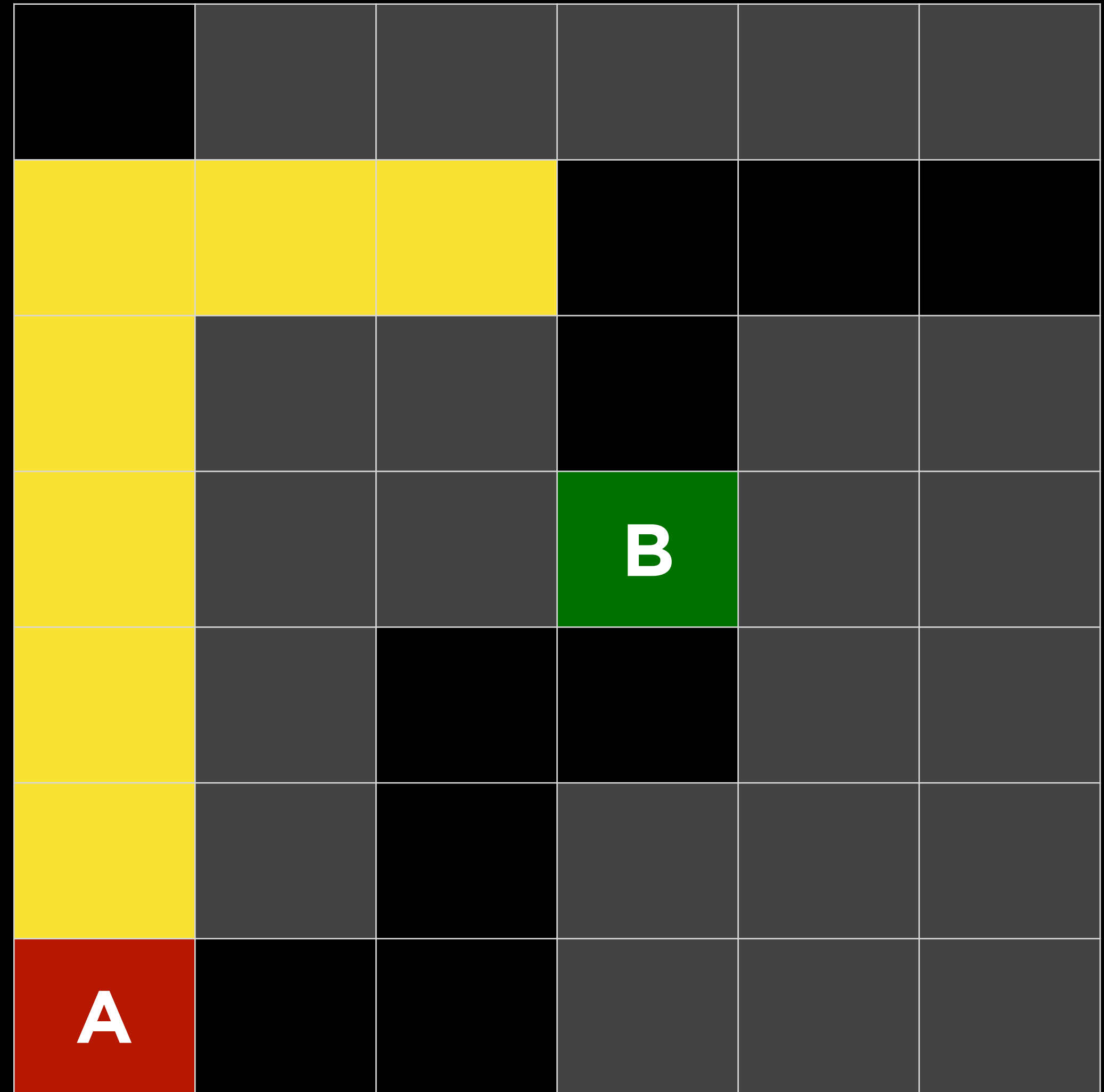
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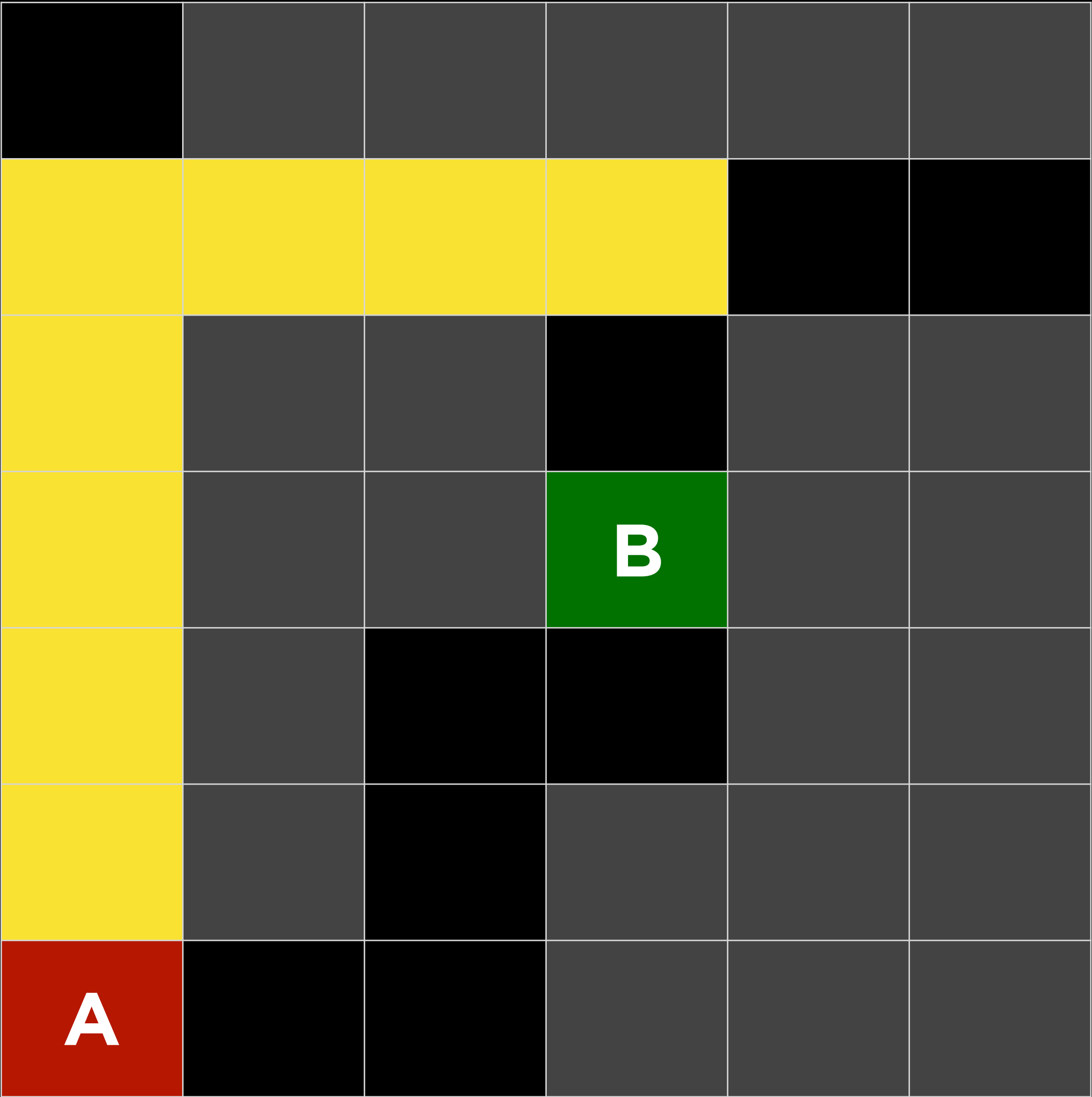
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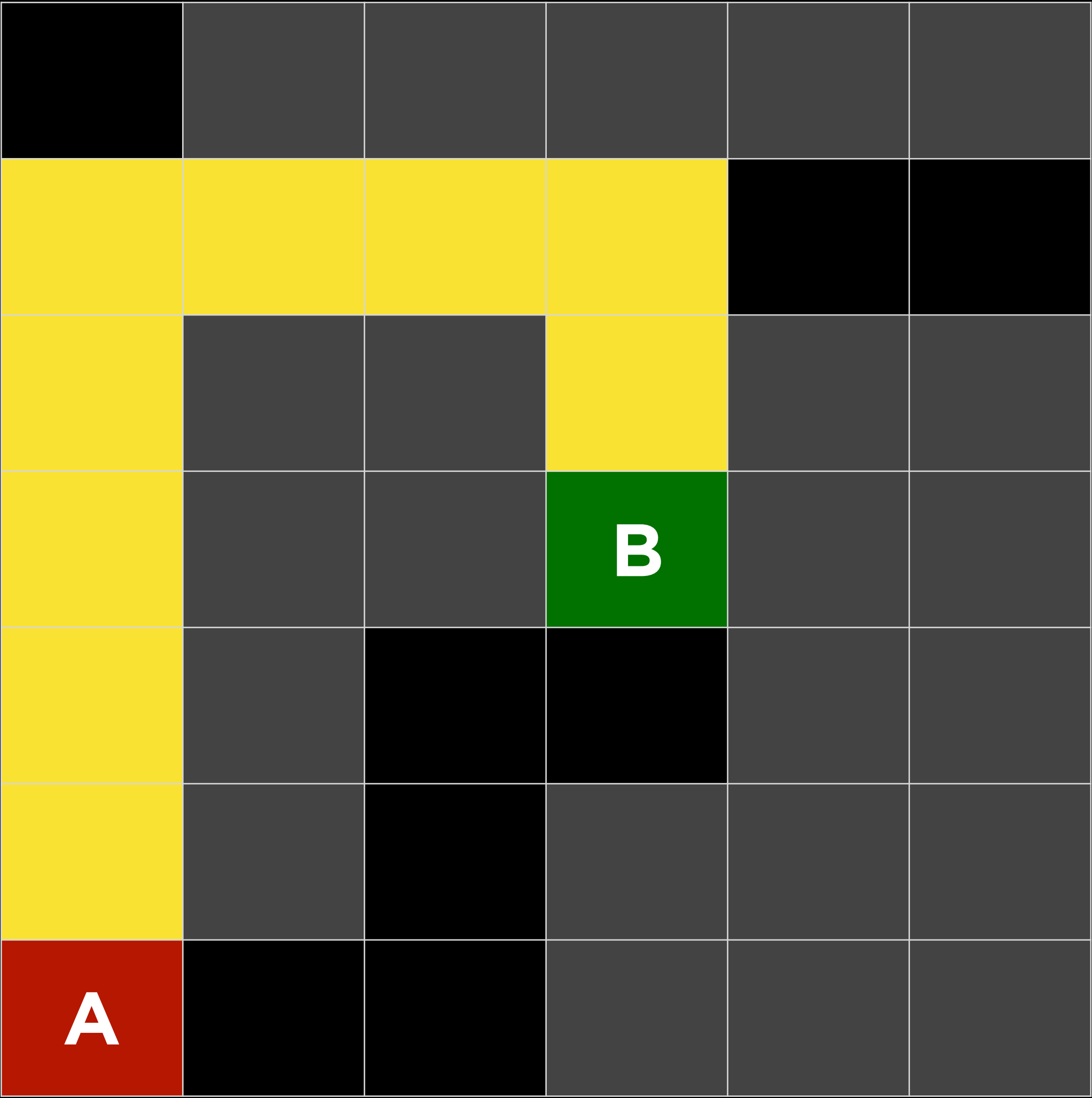
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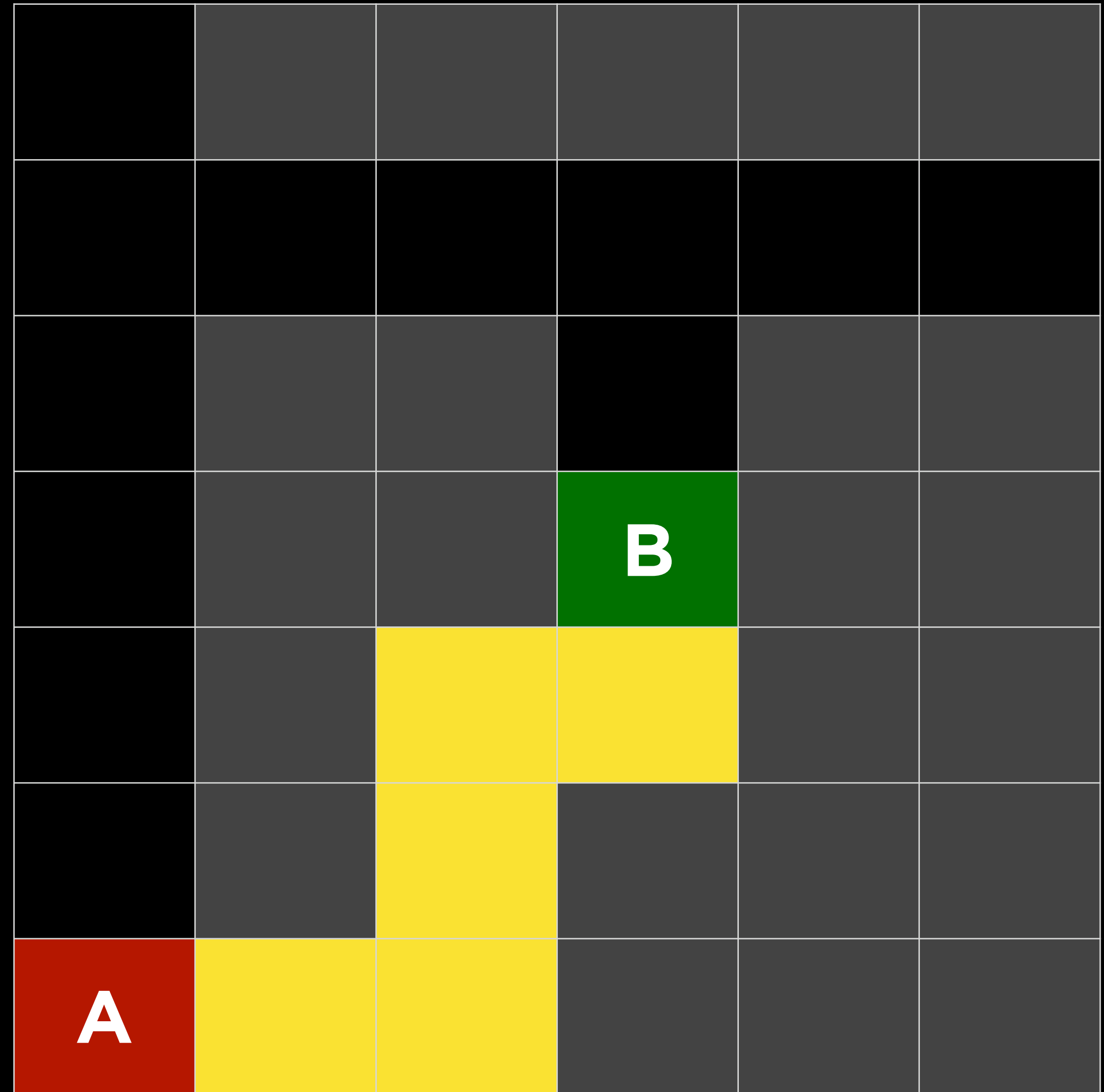
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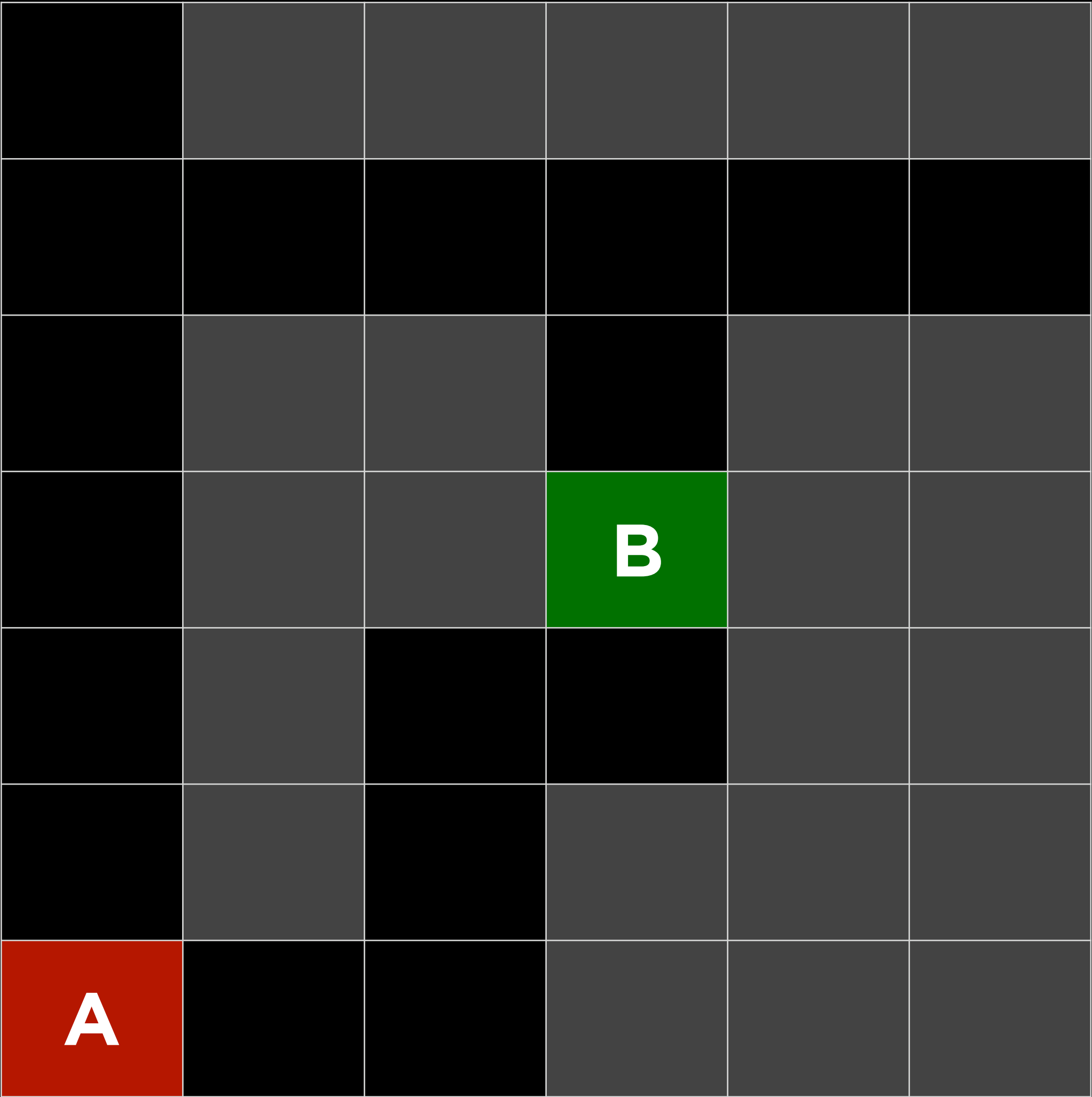
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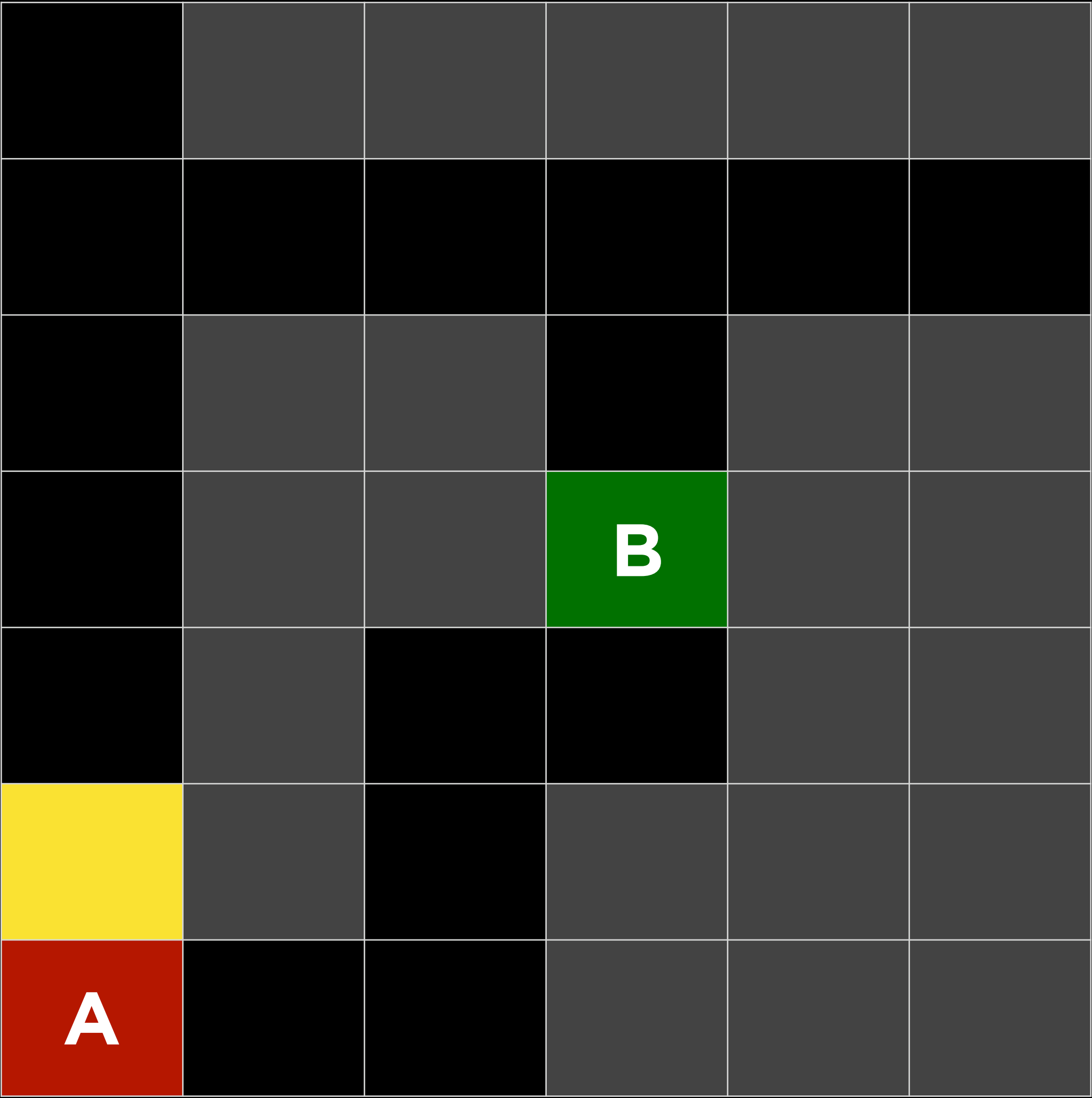
Depth-First Search



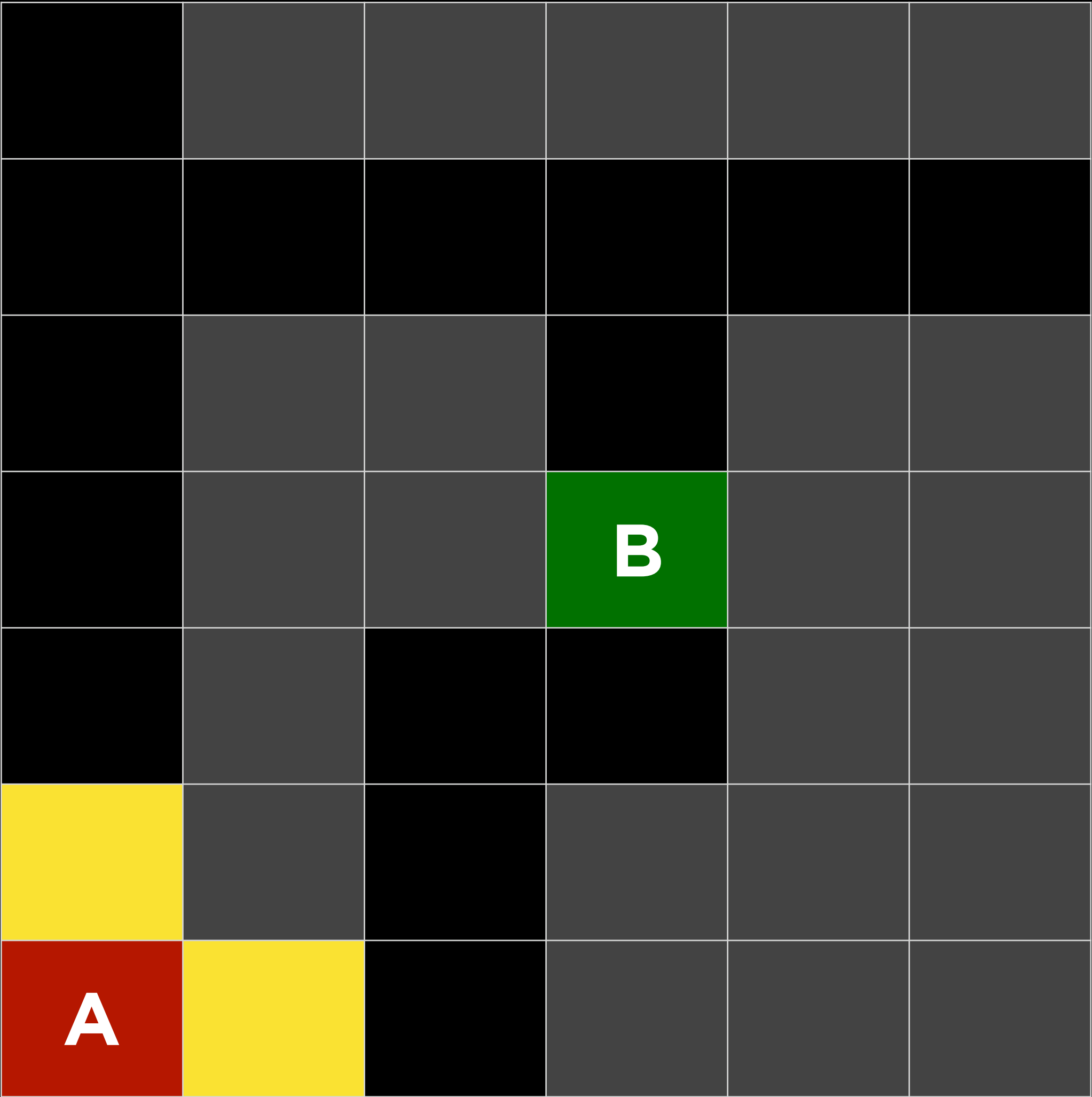
Breadth-First Search



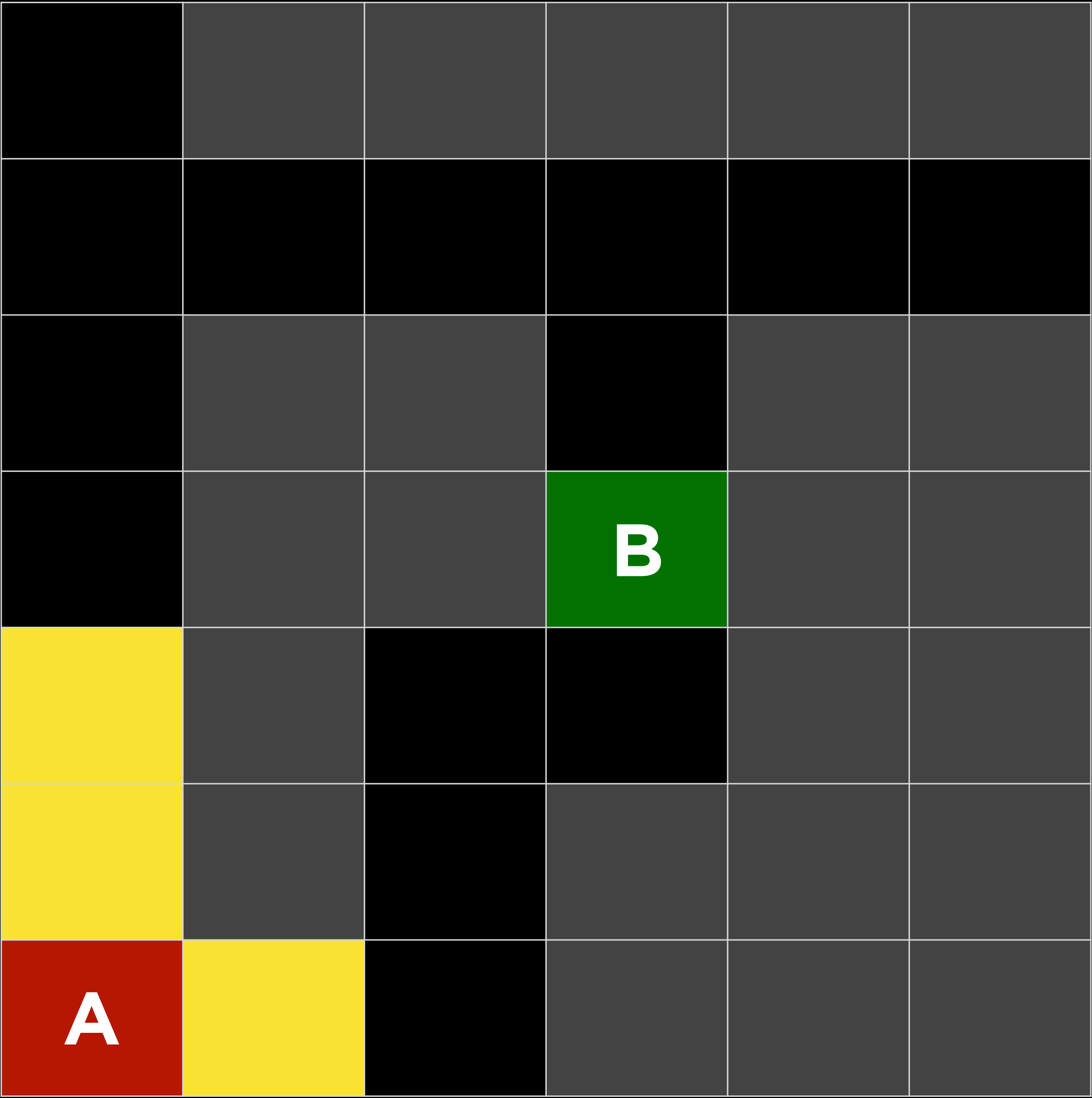
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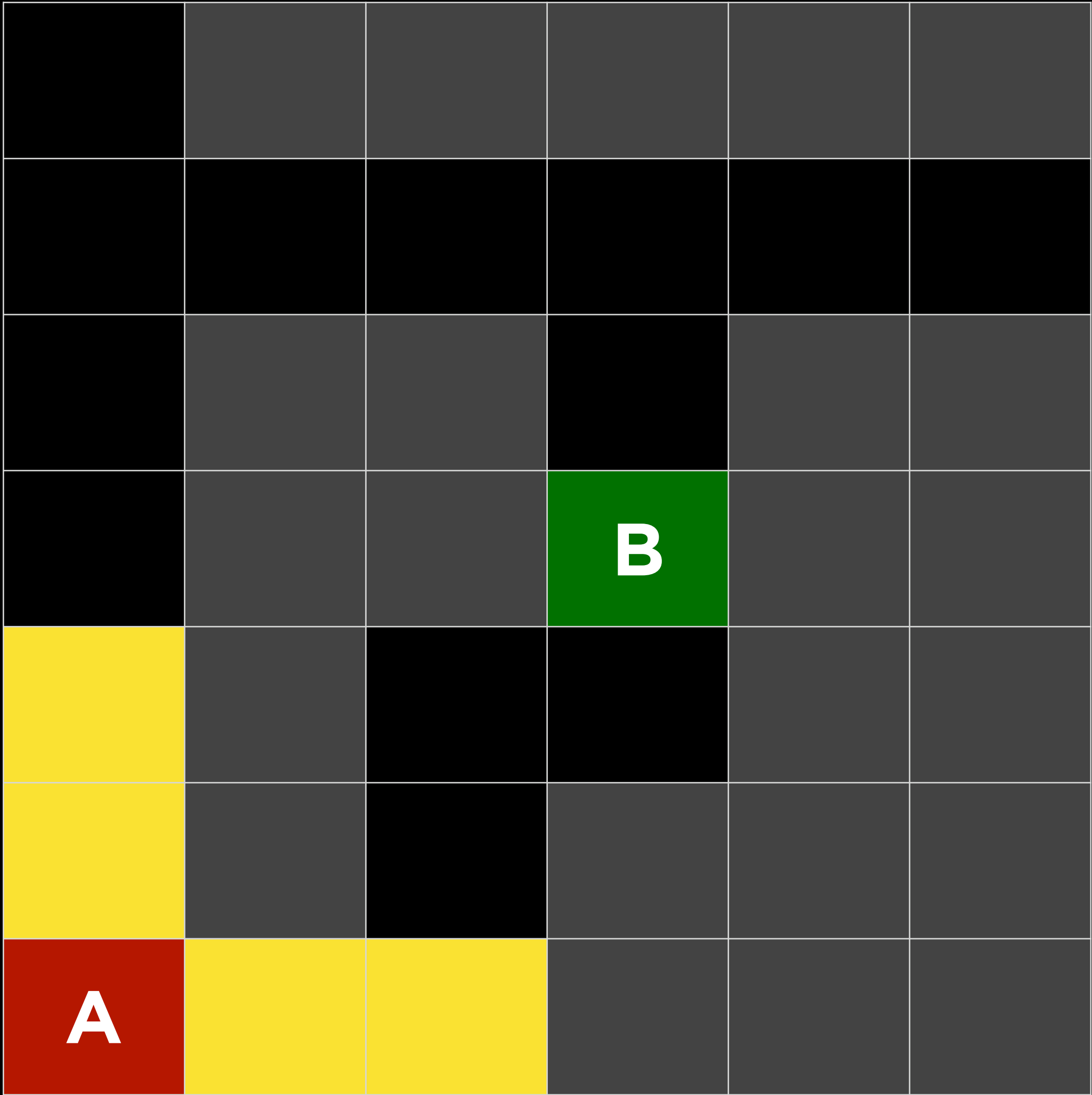
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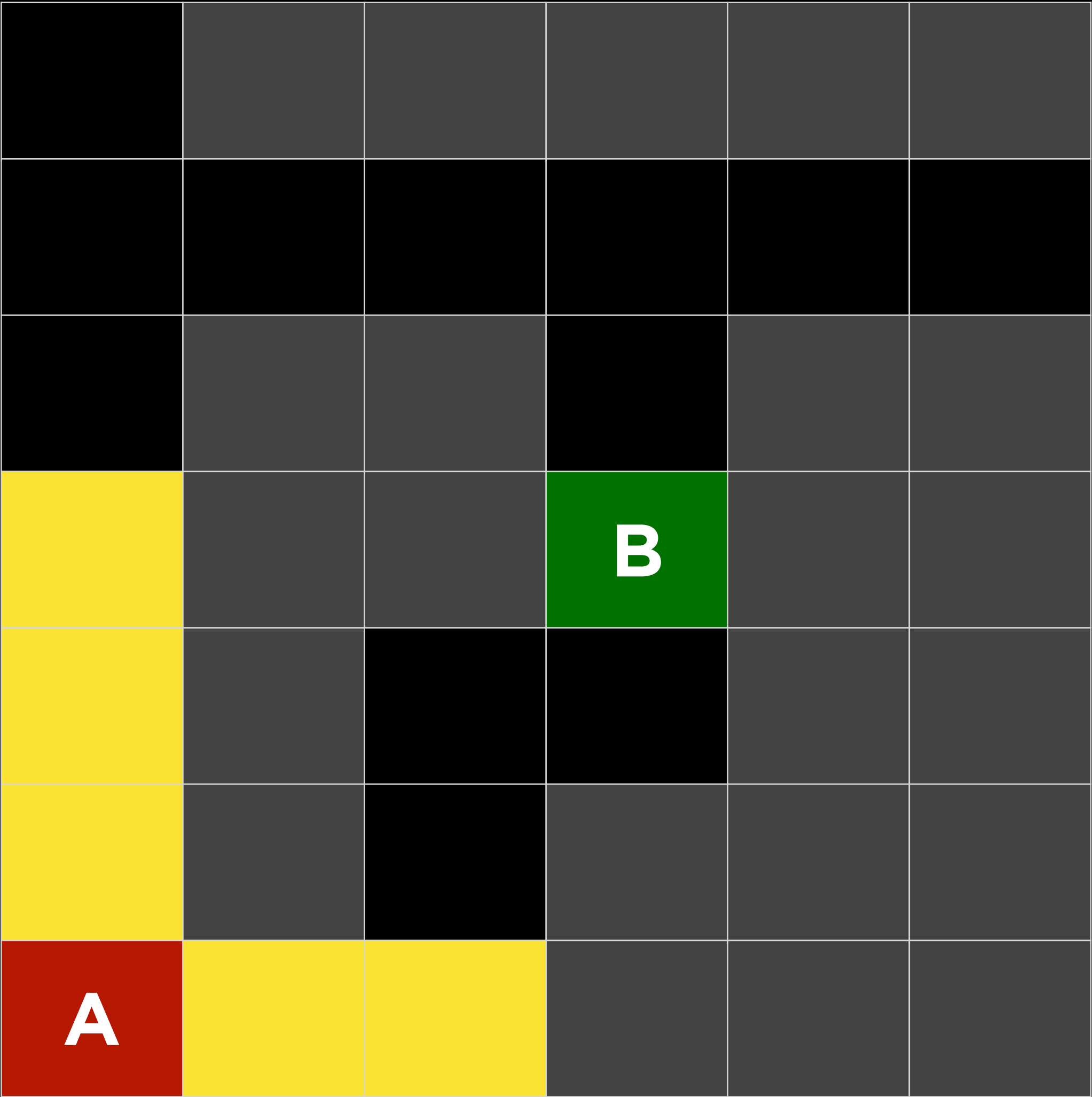
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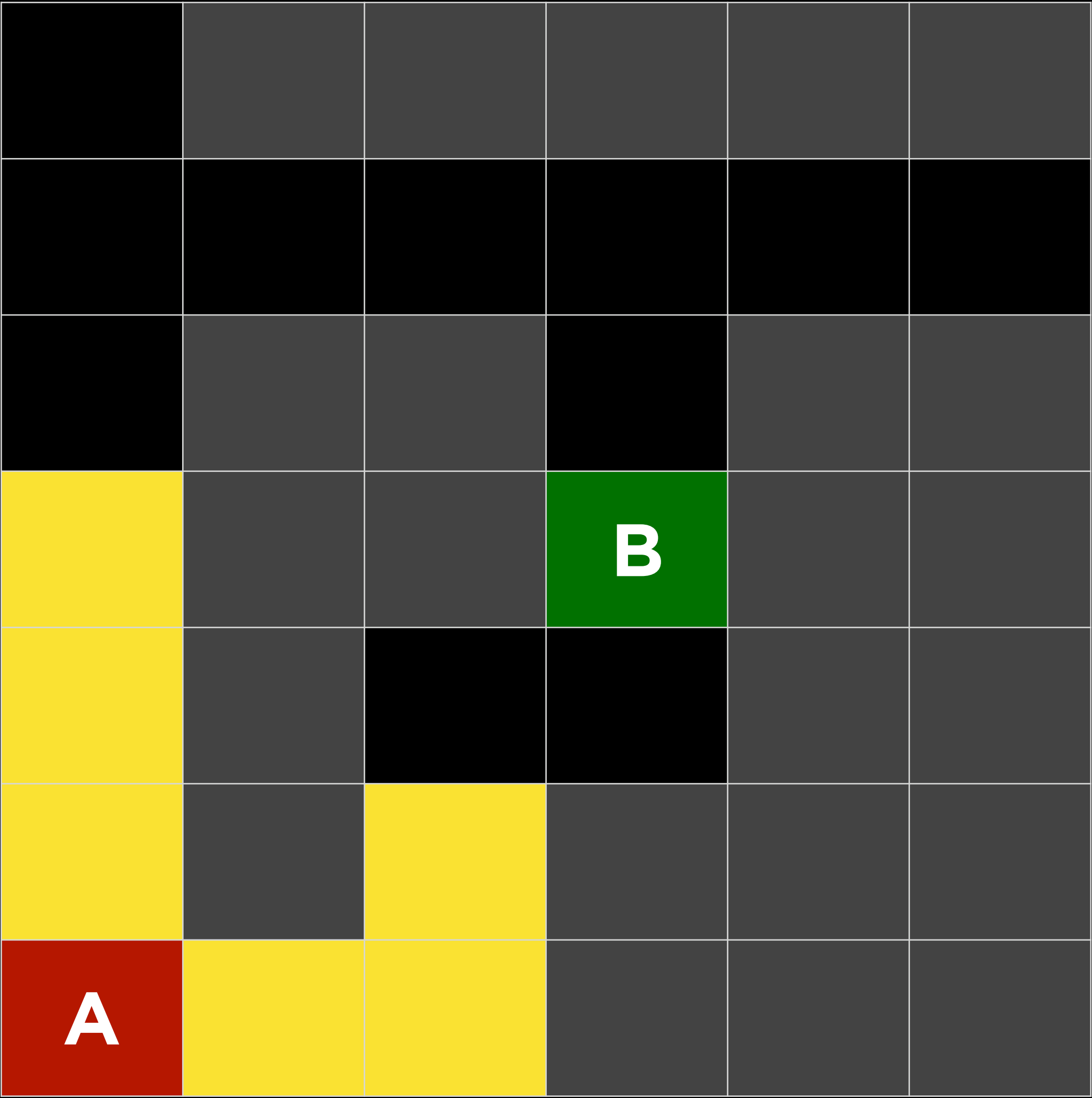
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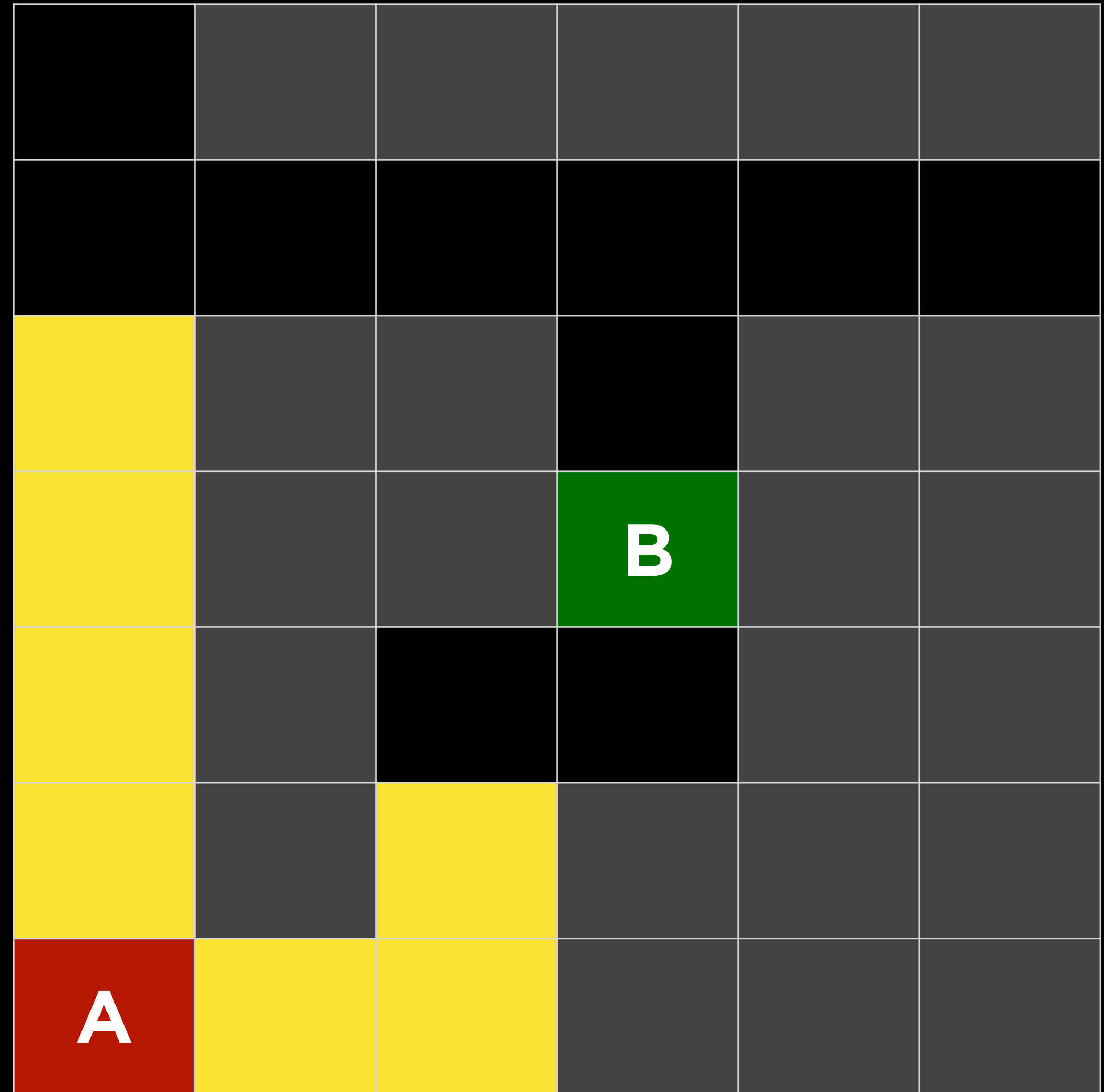
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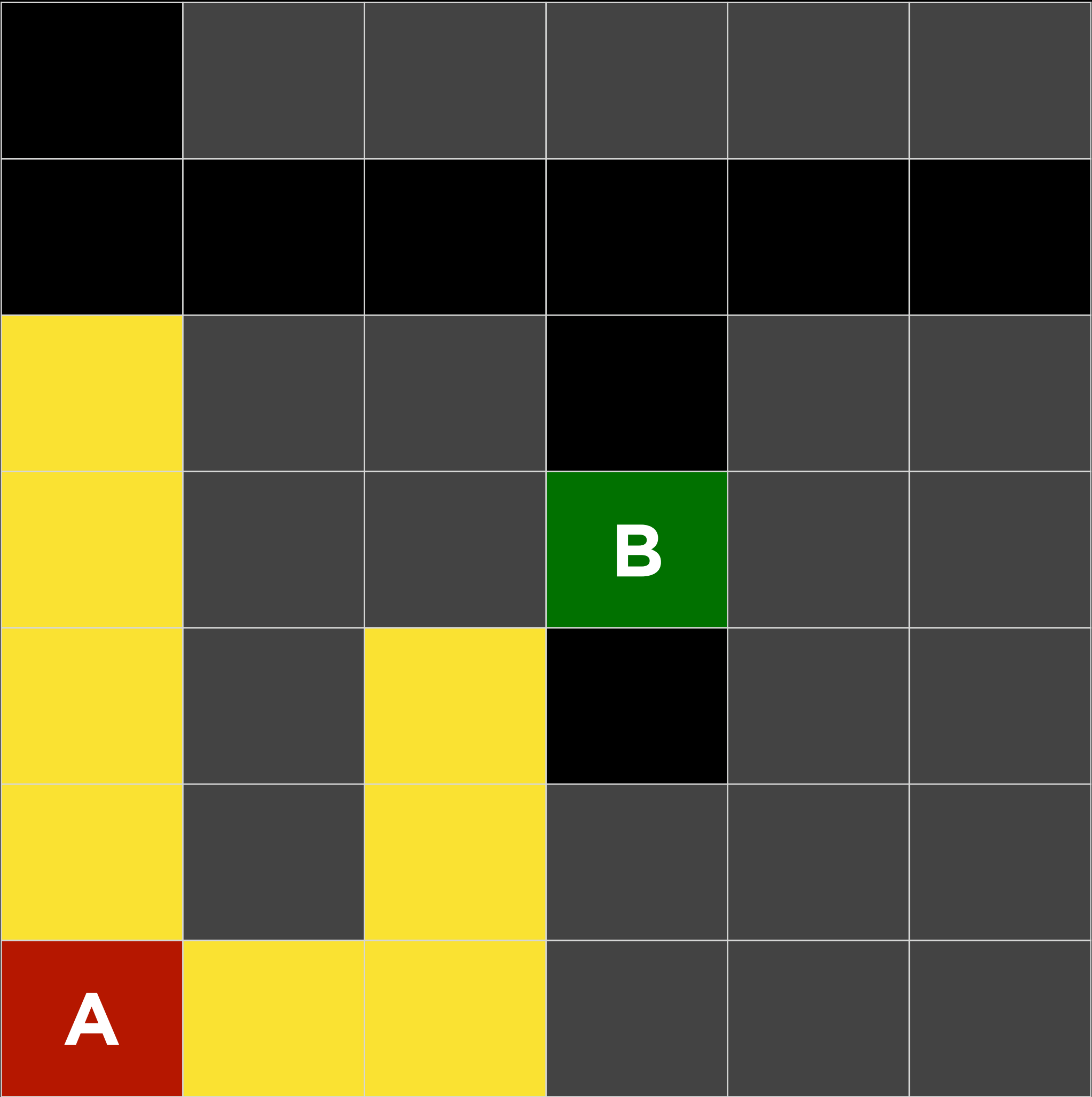
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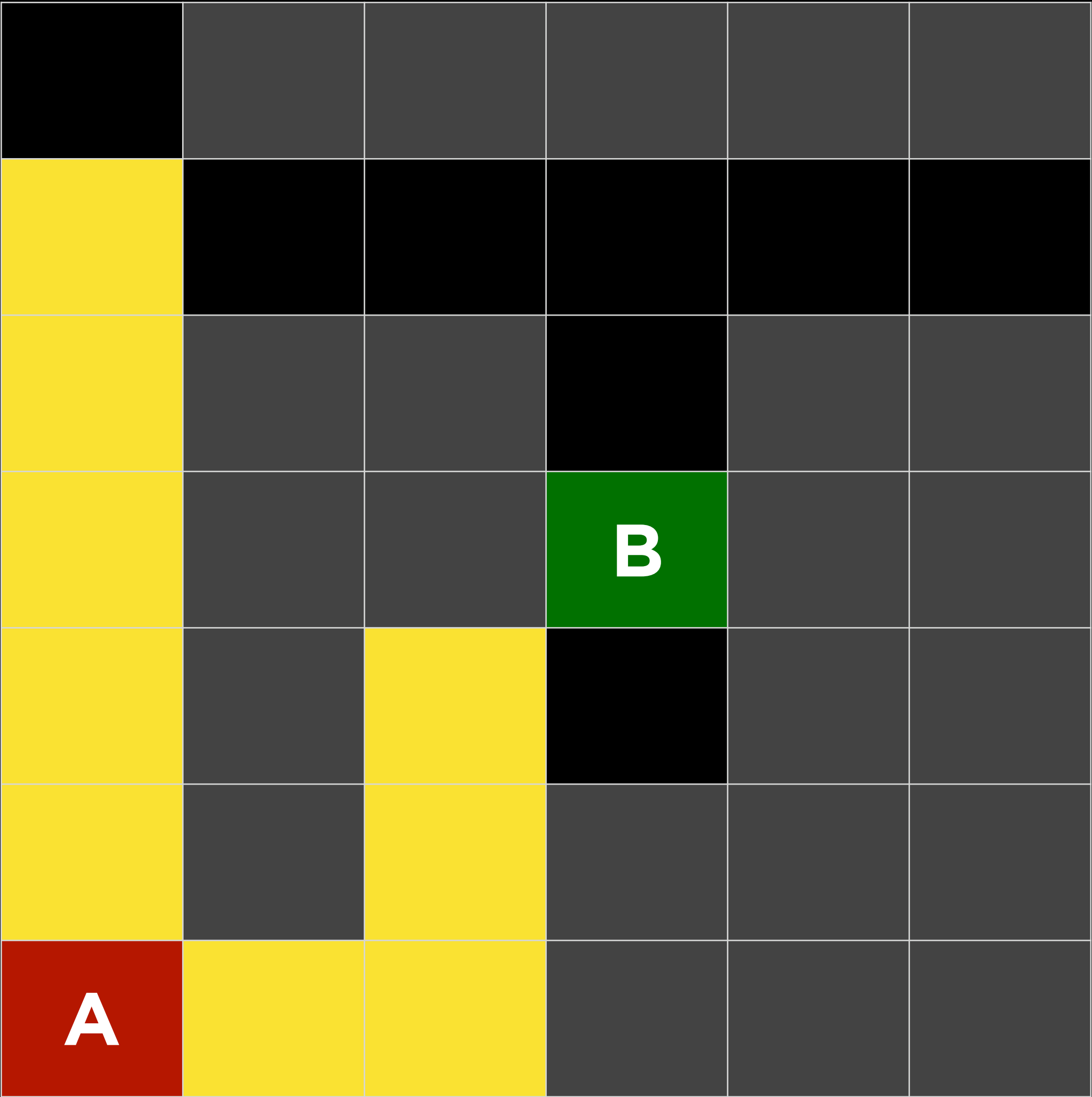
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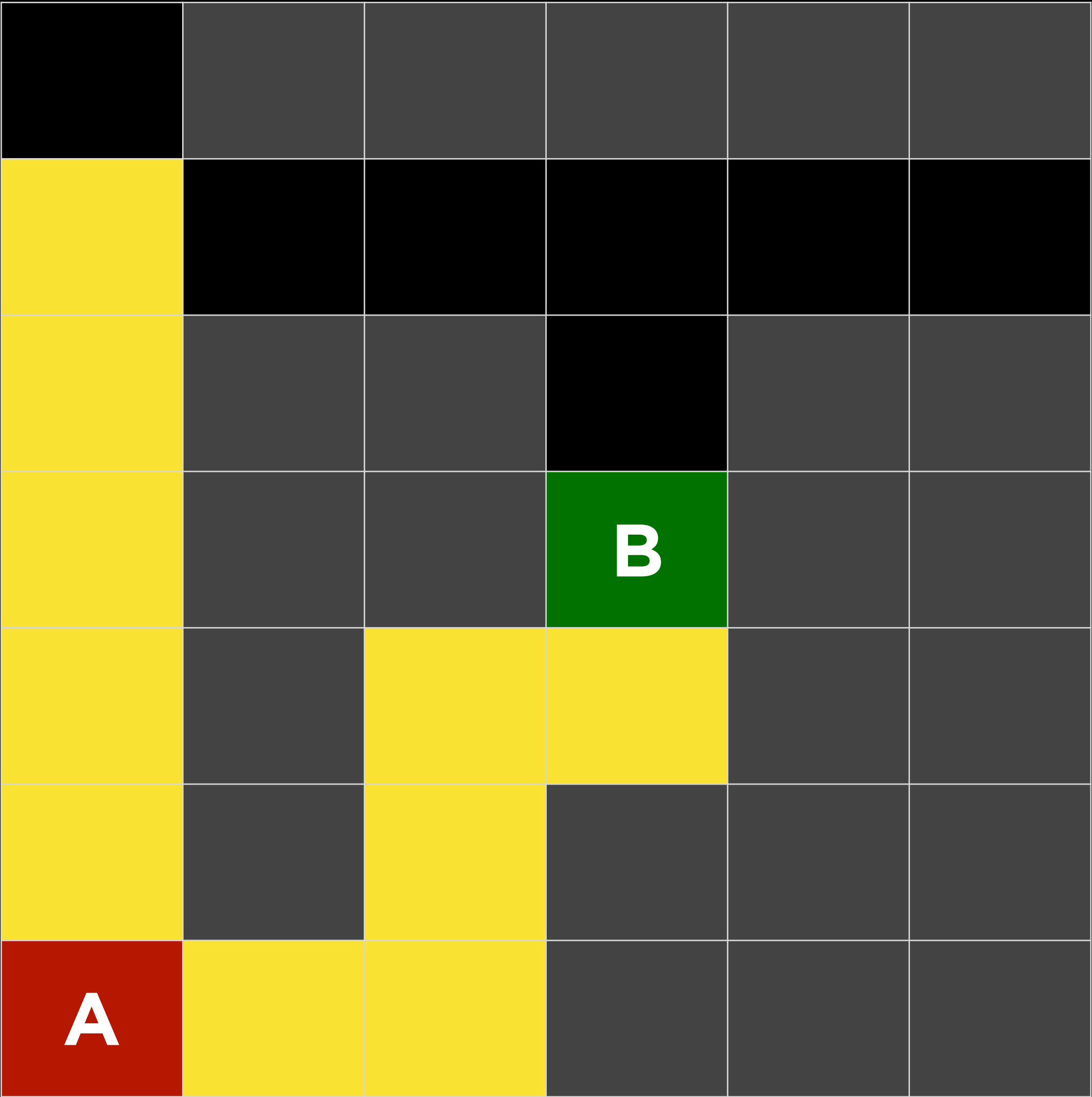
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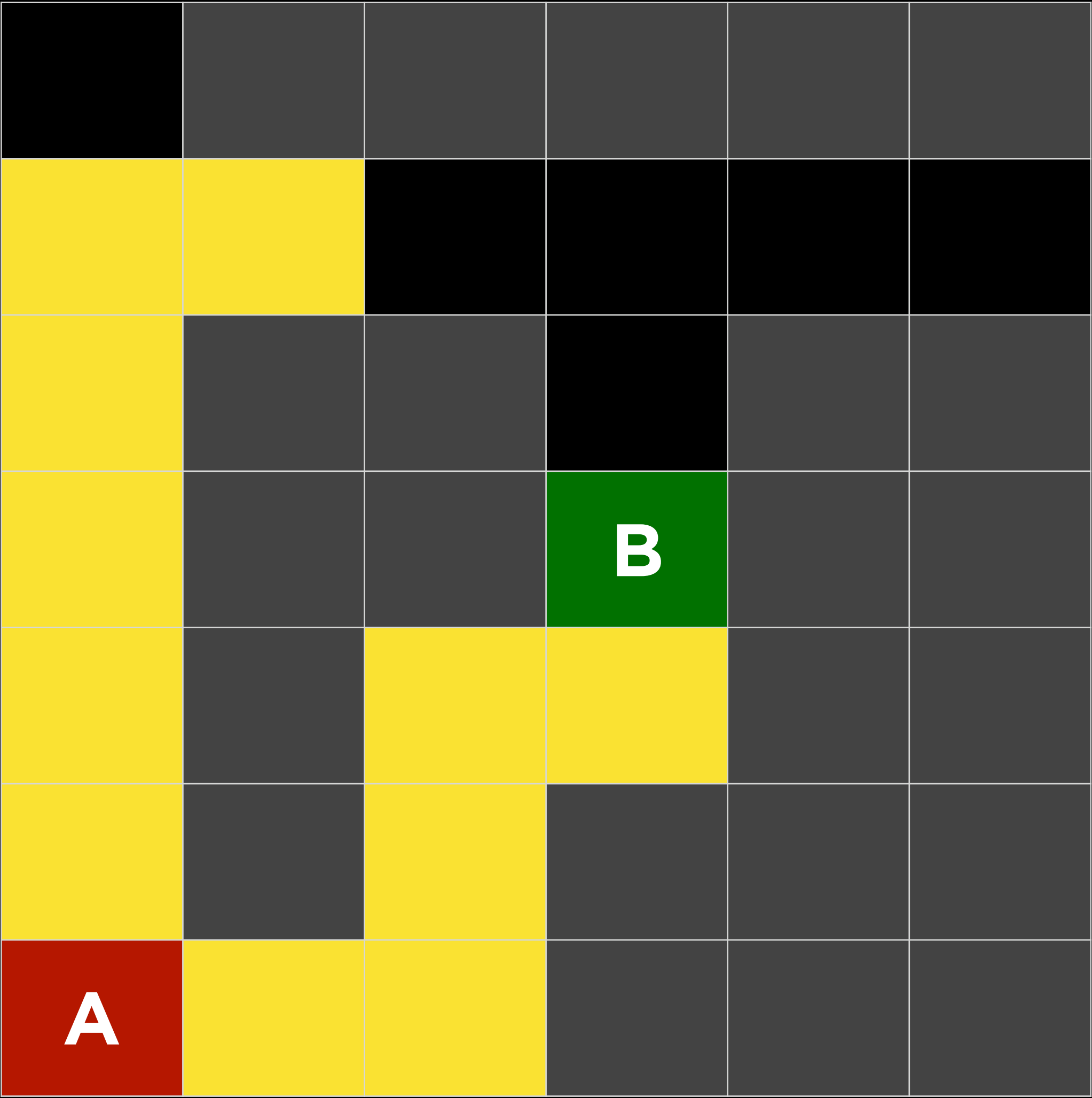
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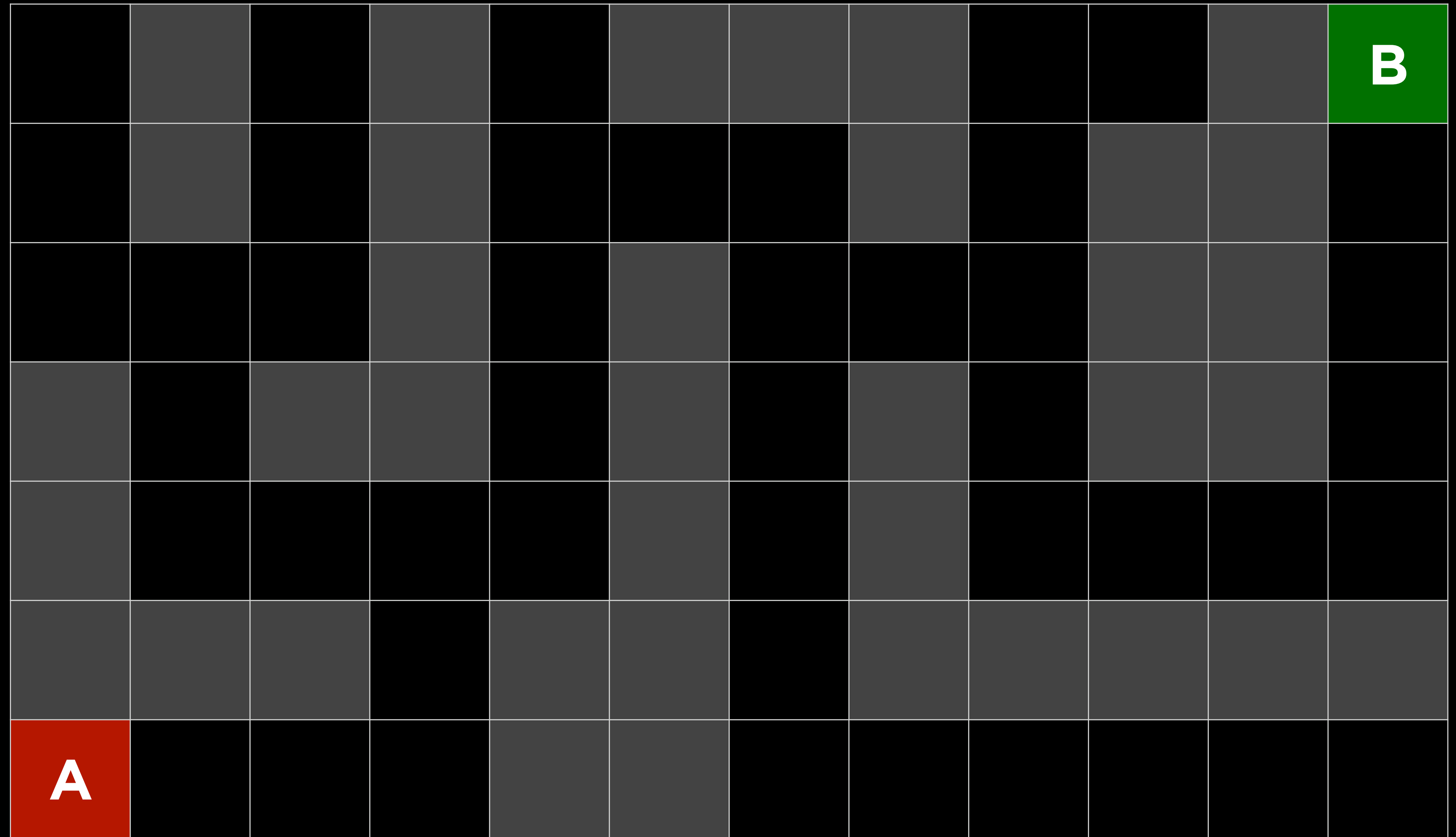
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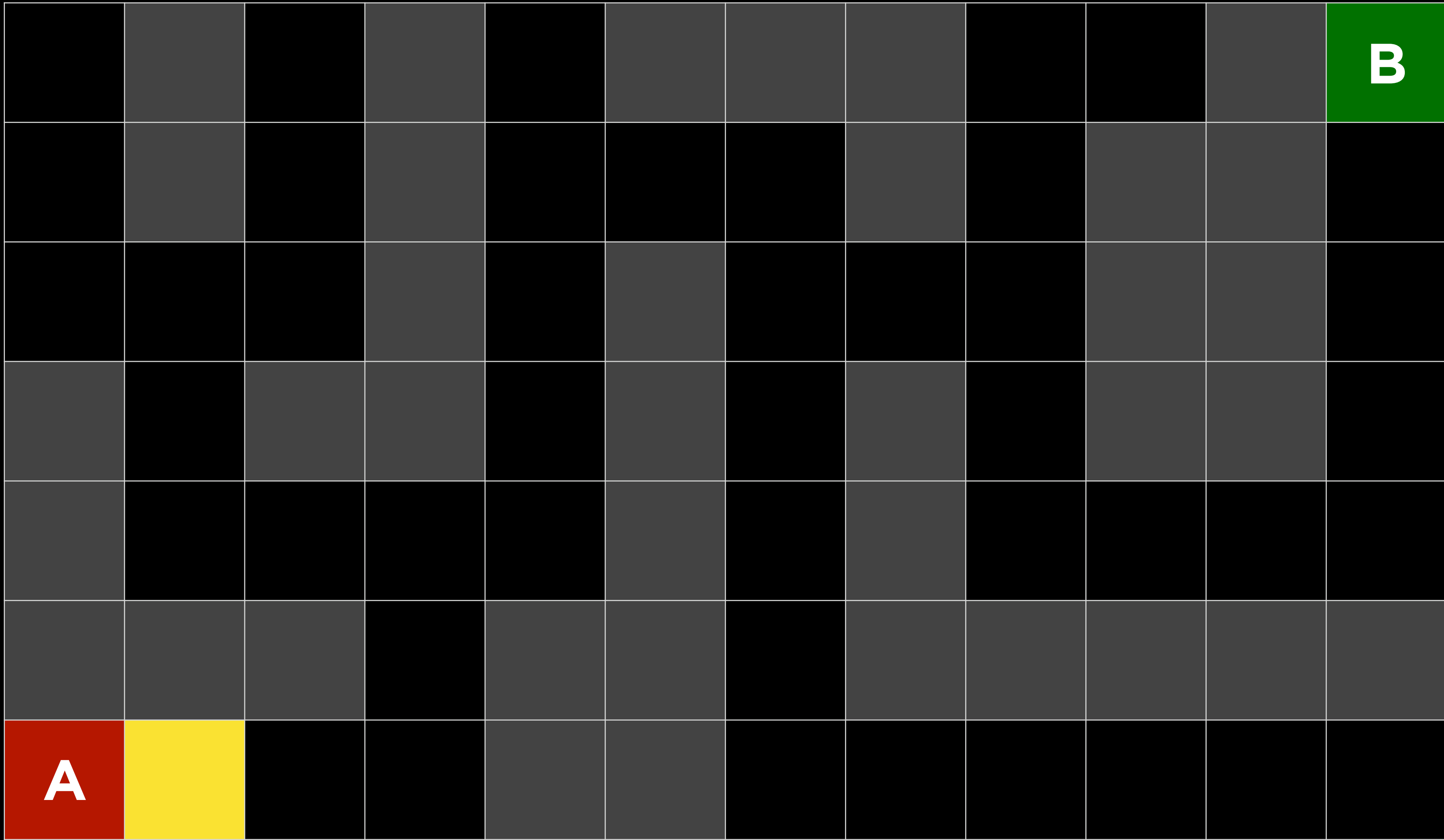
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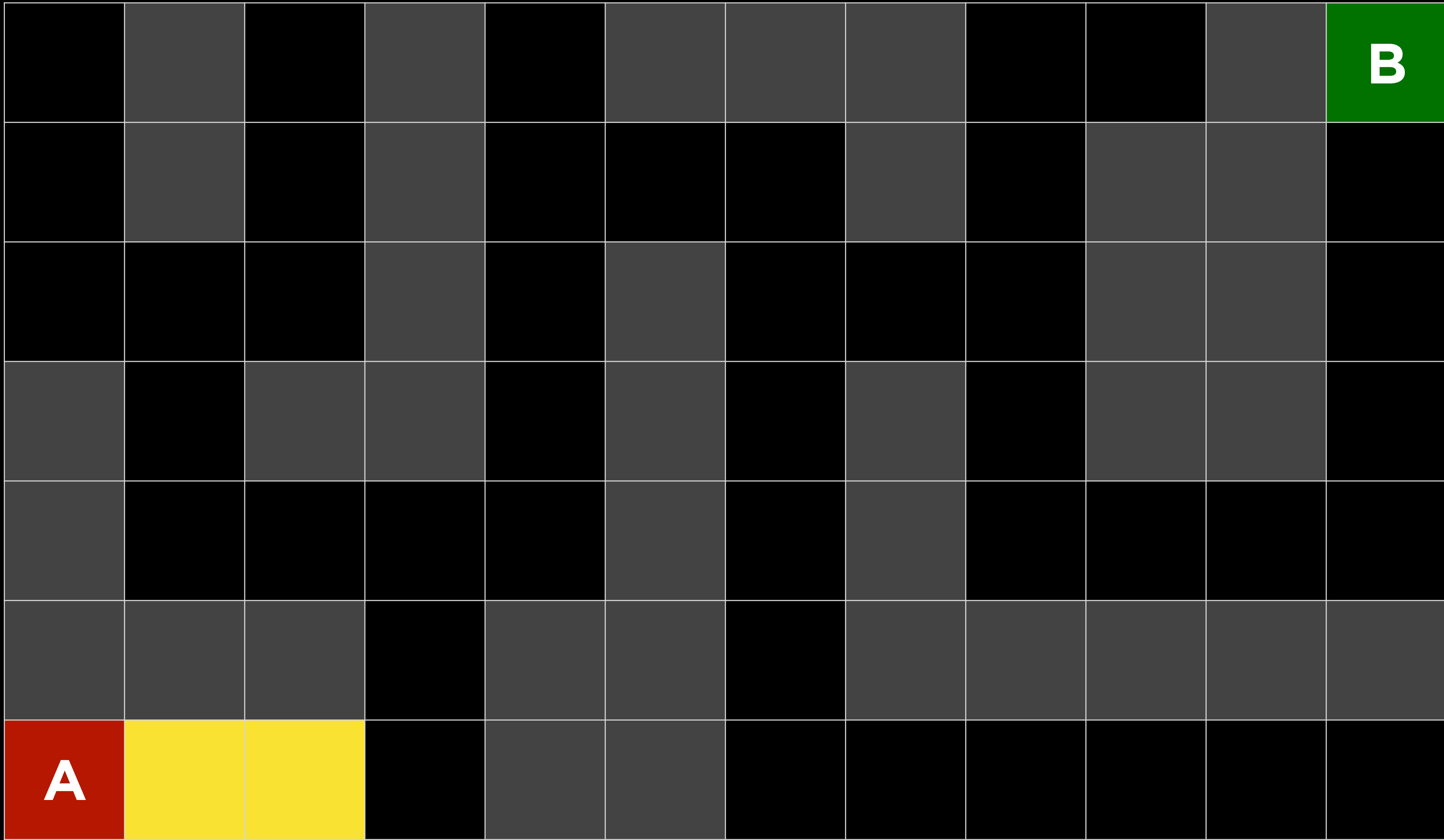
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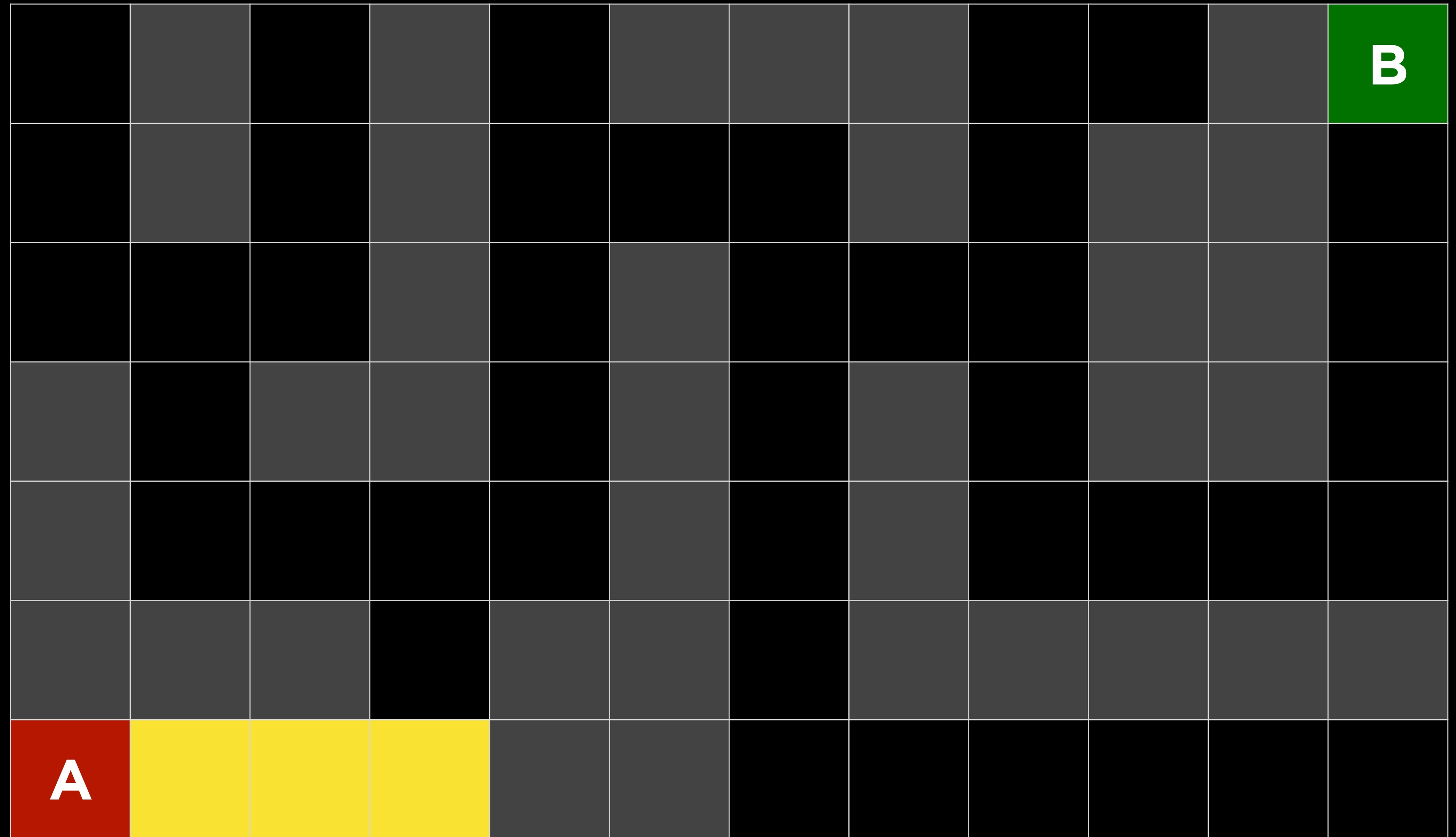
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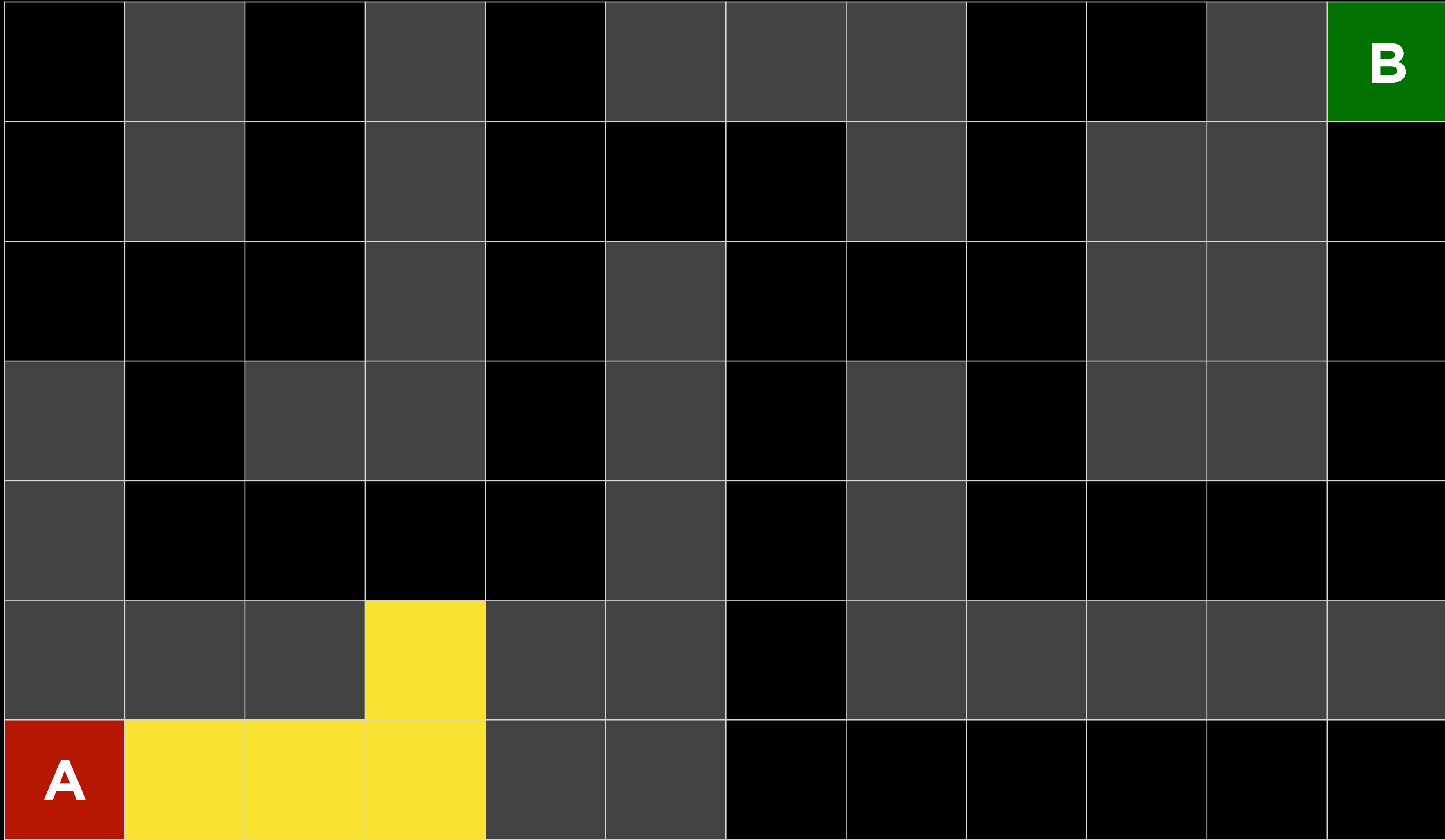
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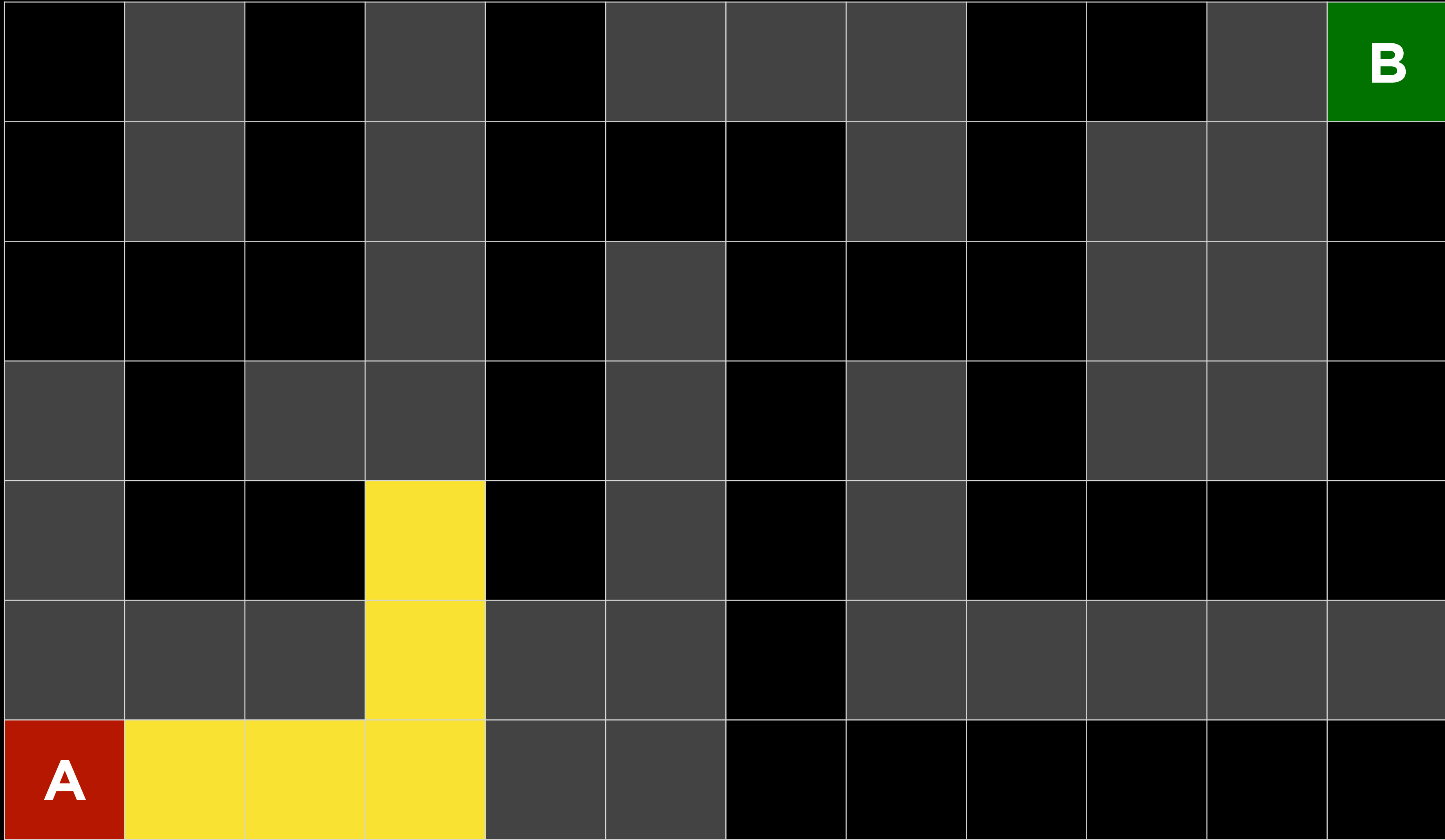
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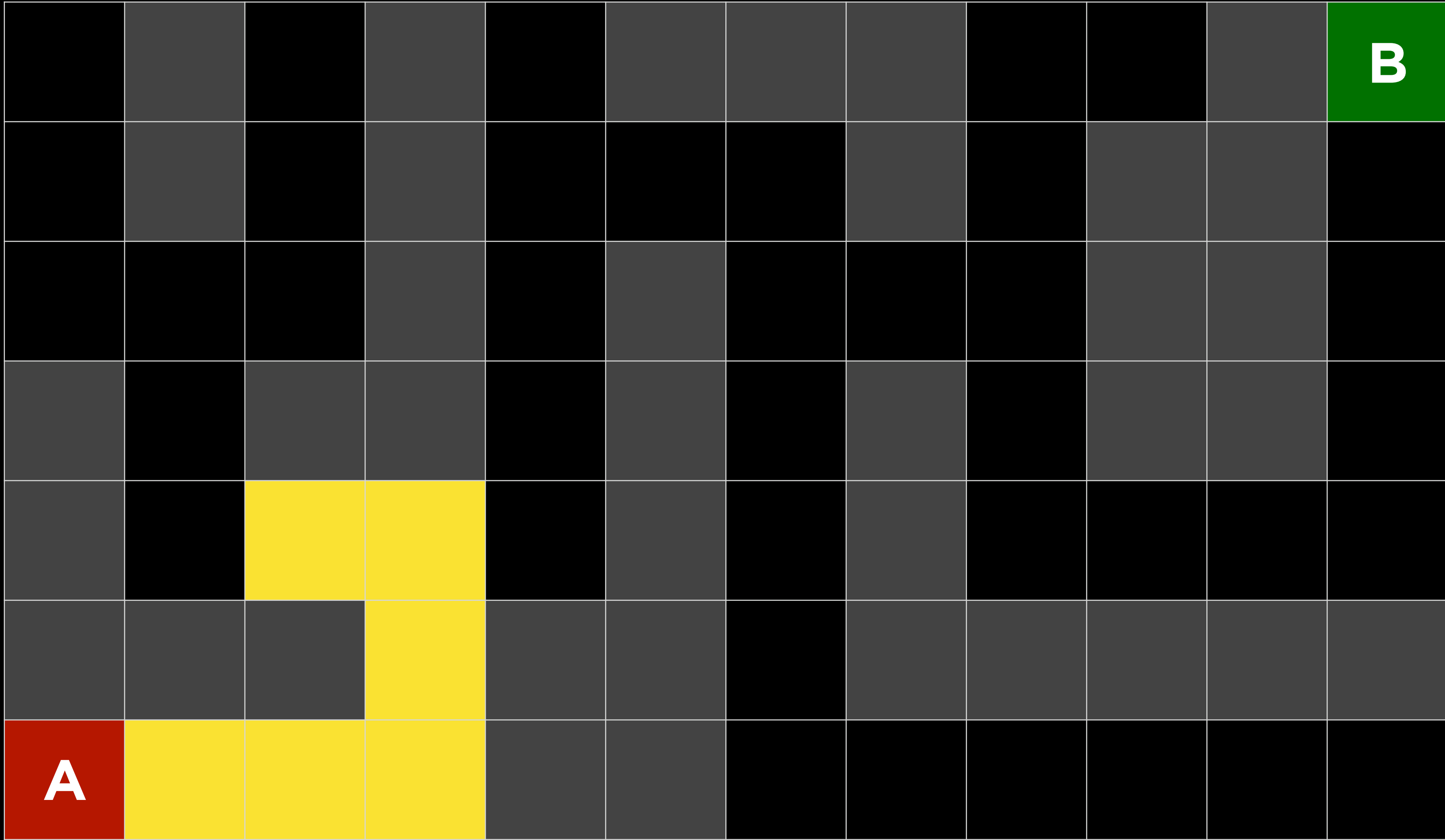
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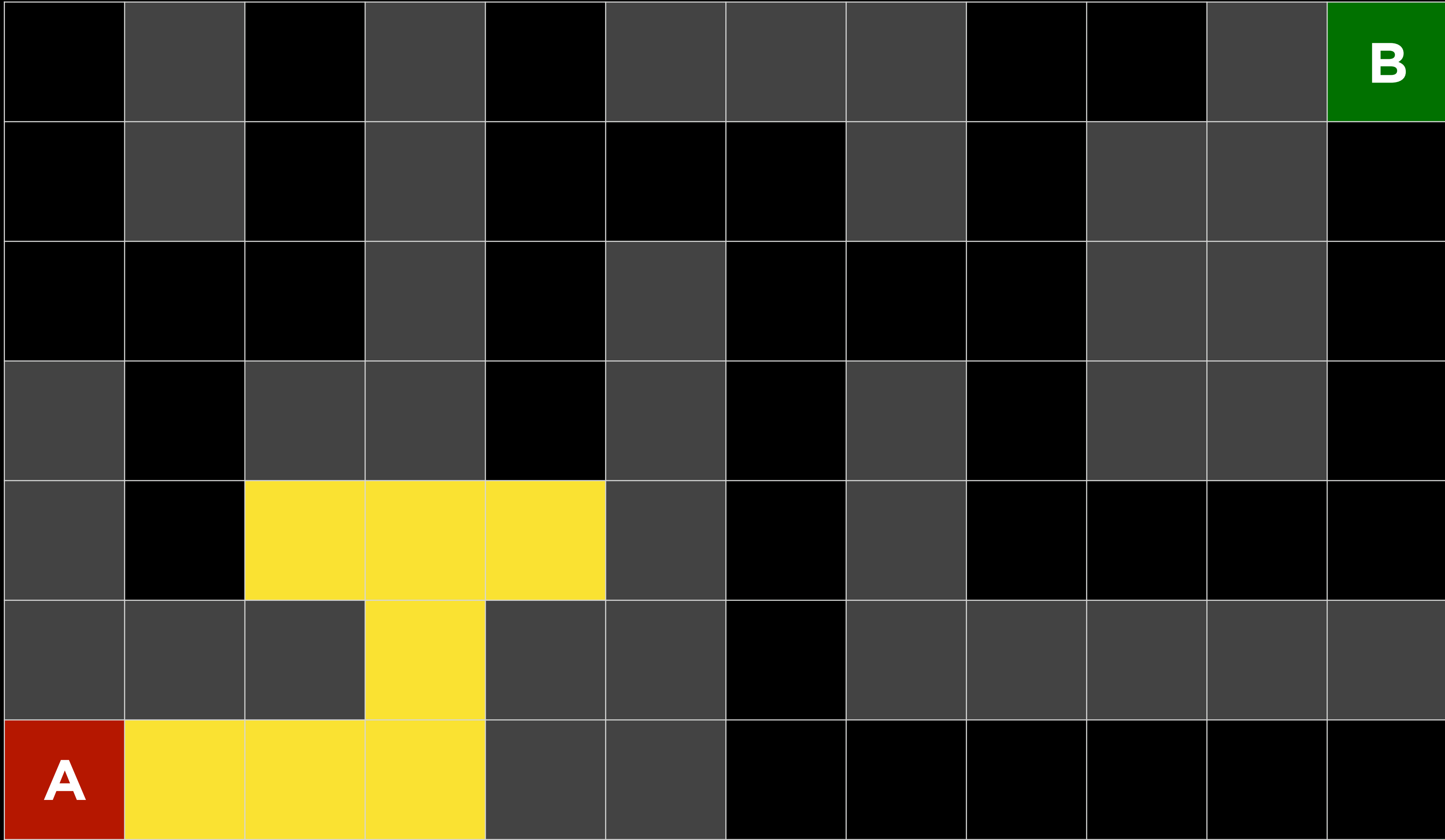
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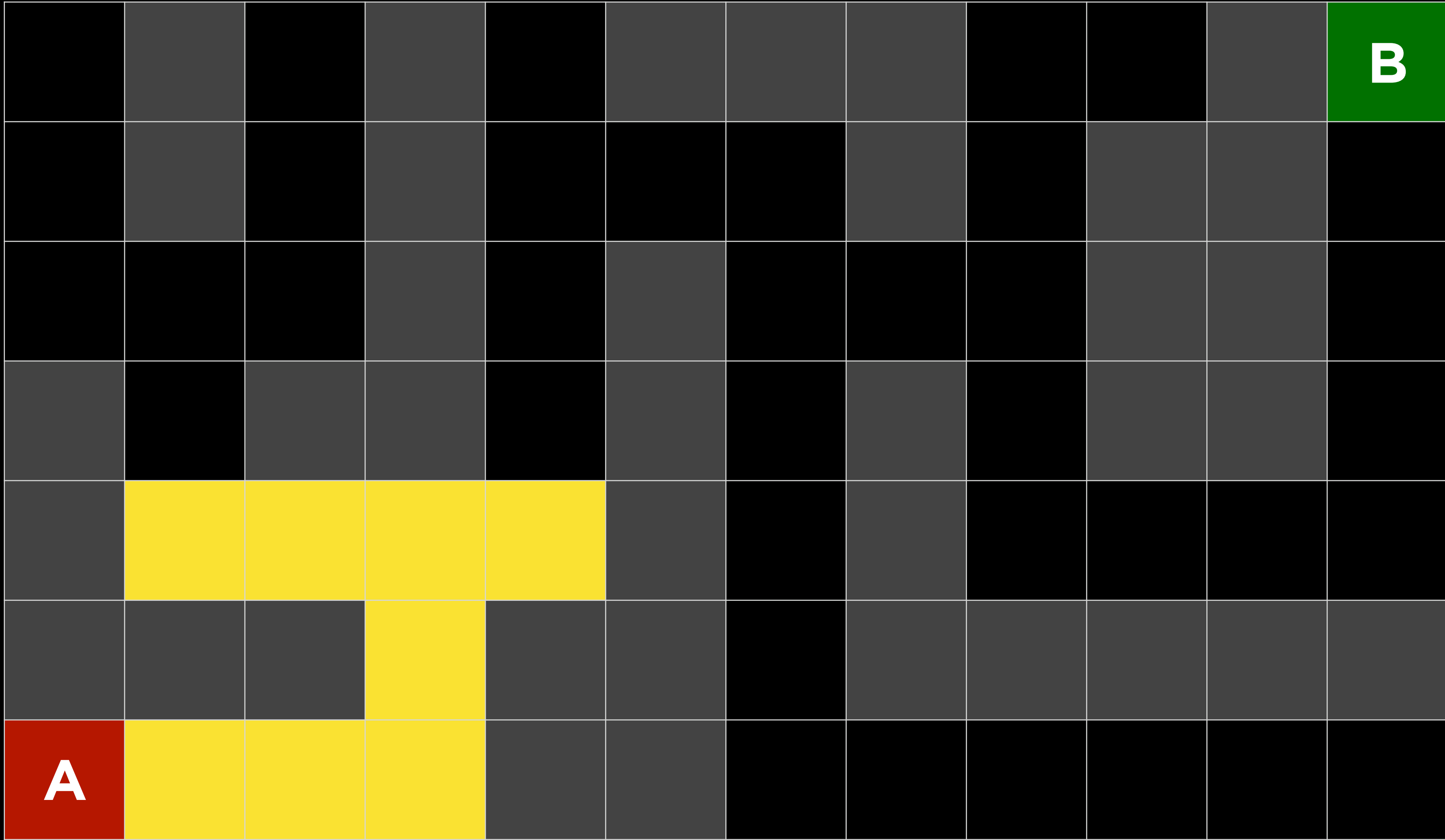
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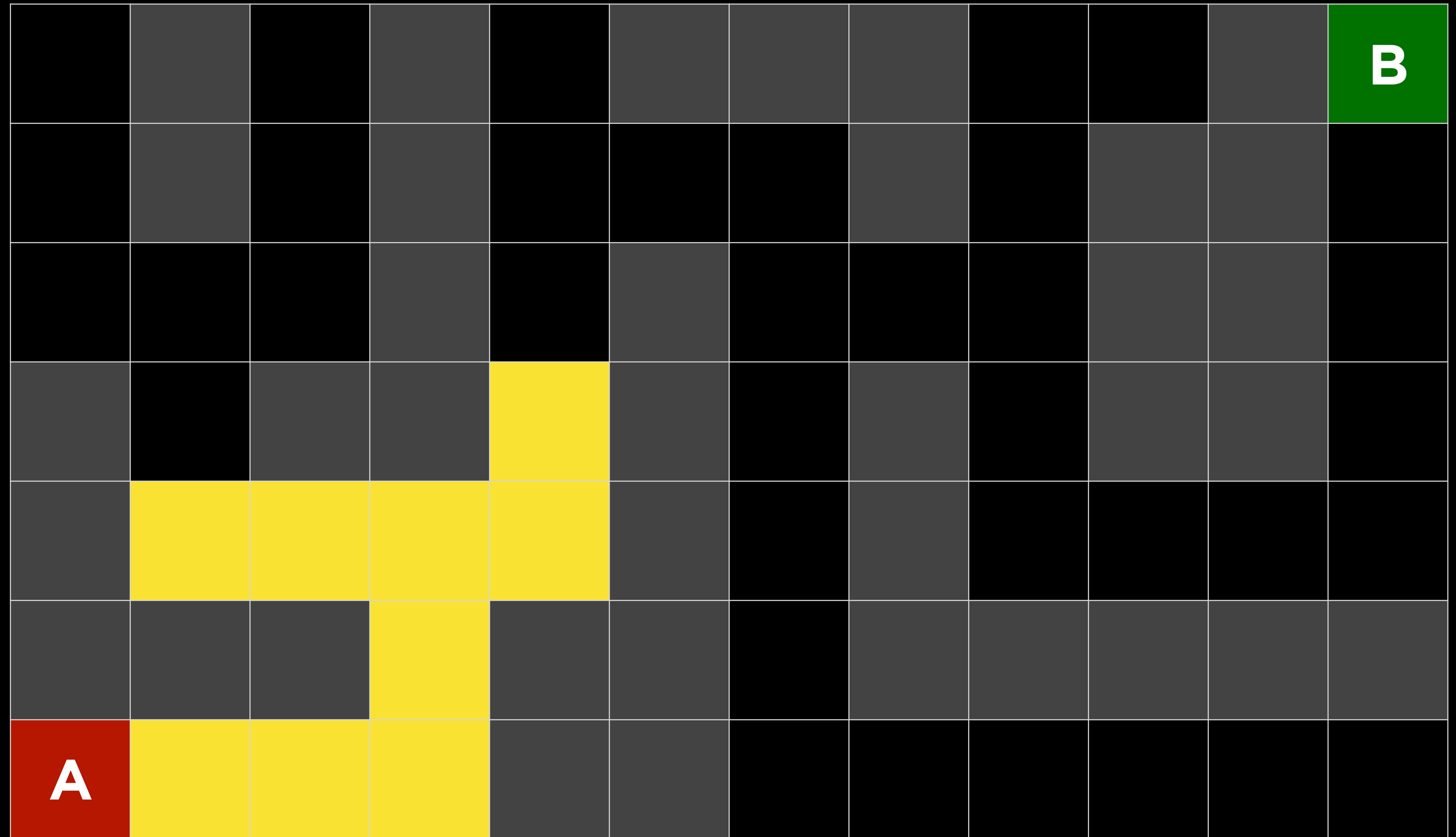
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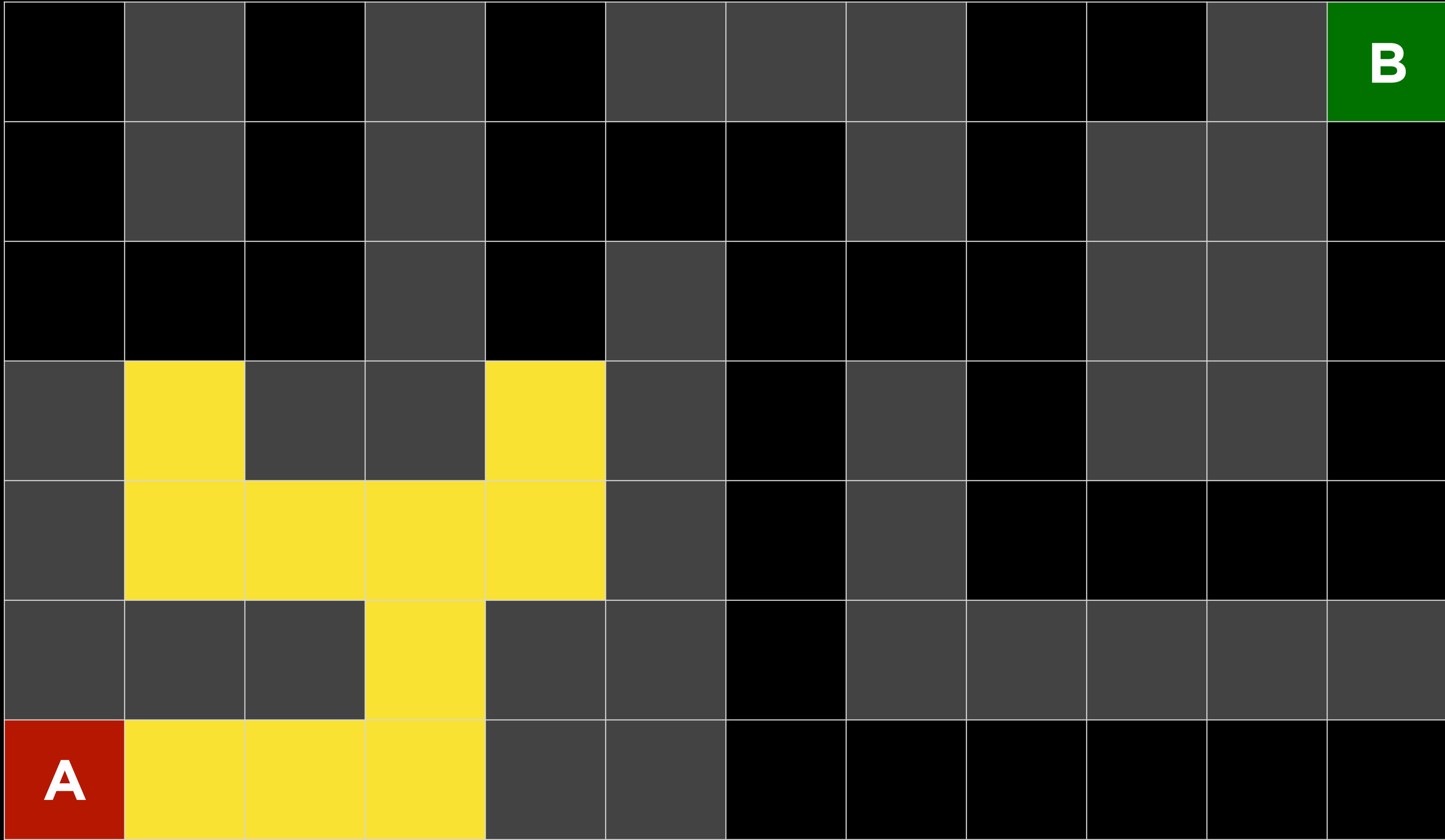
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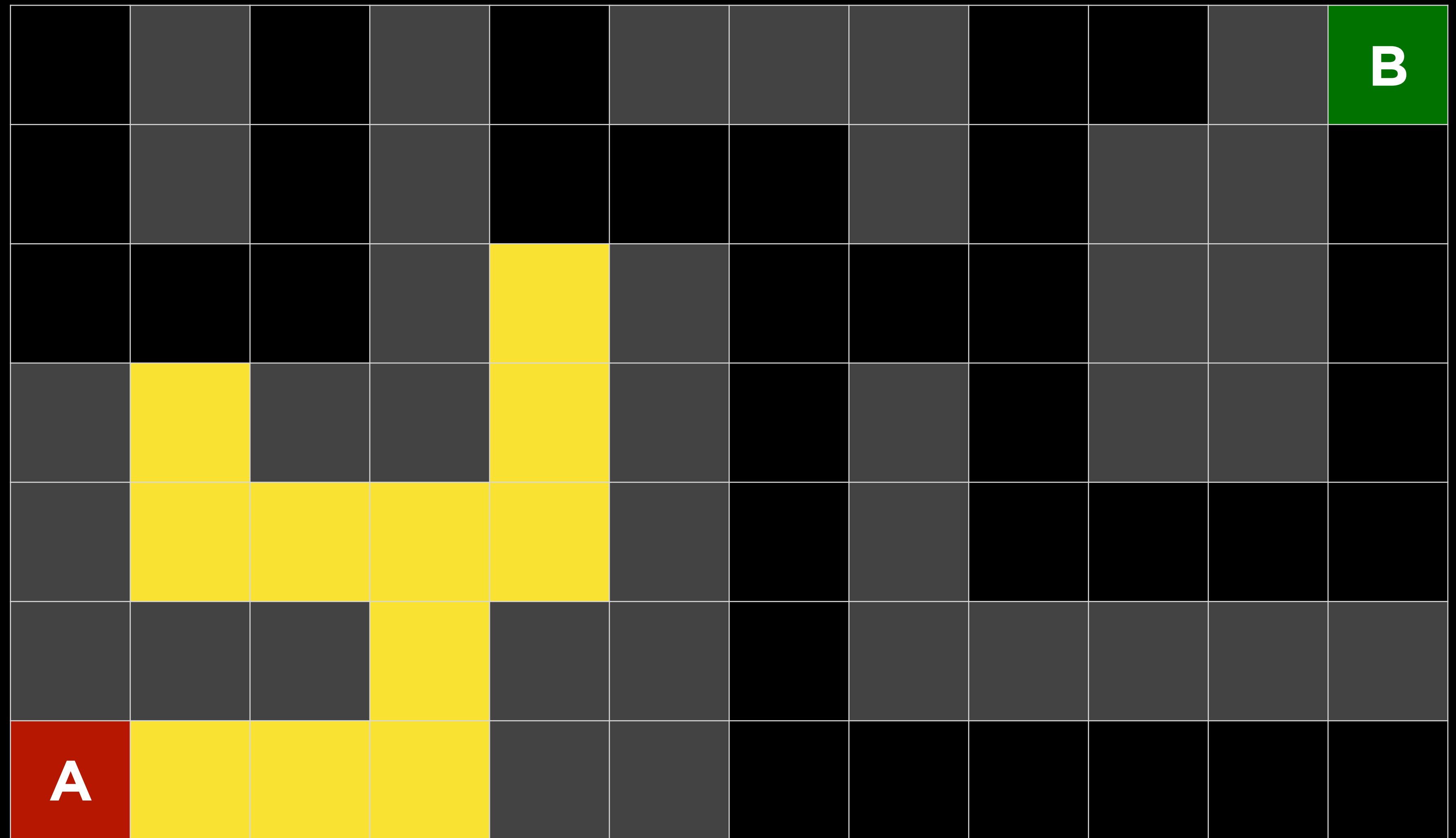
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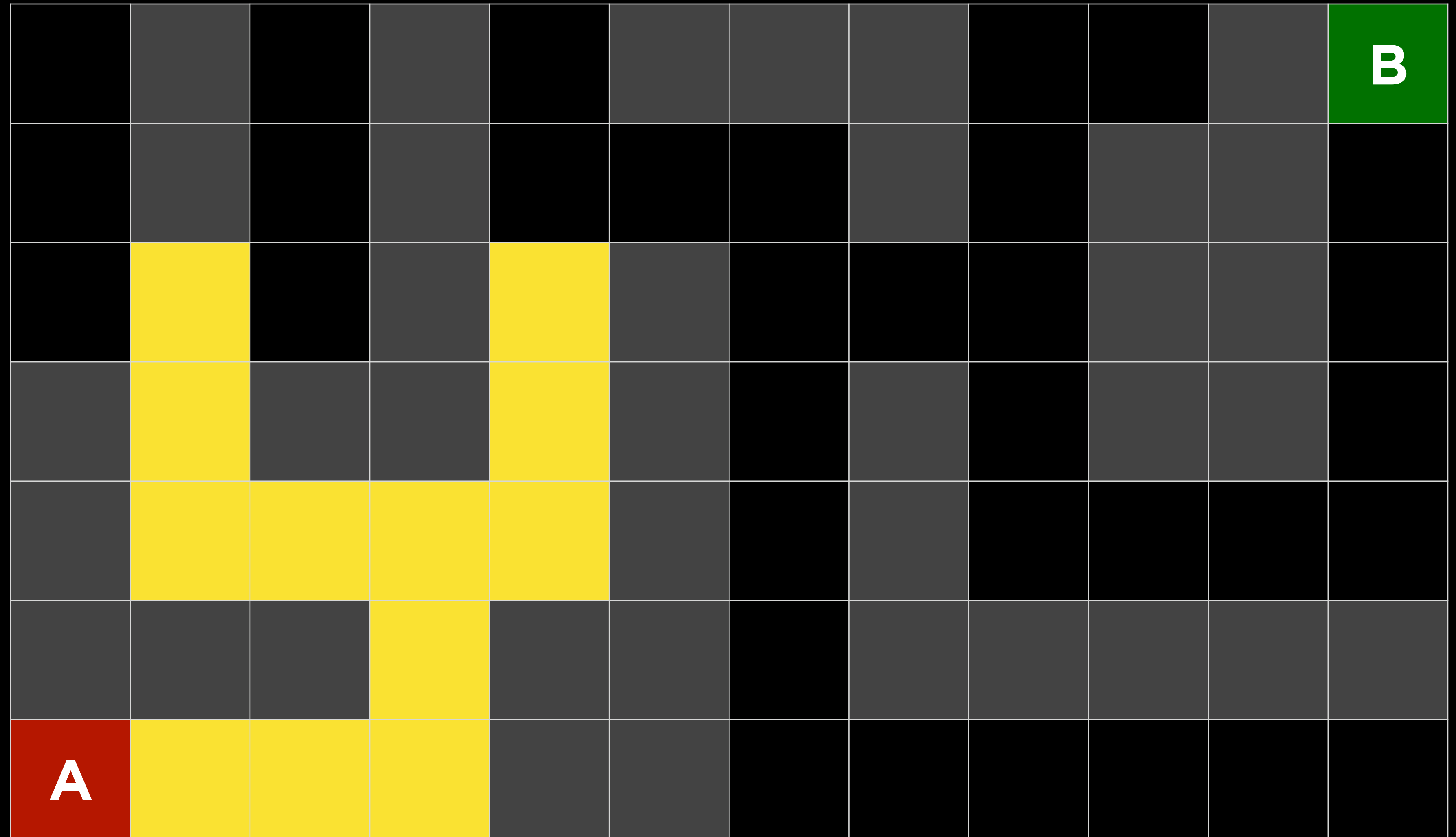
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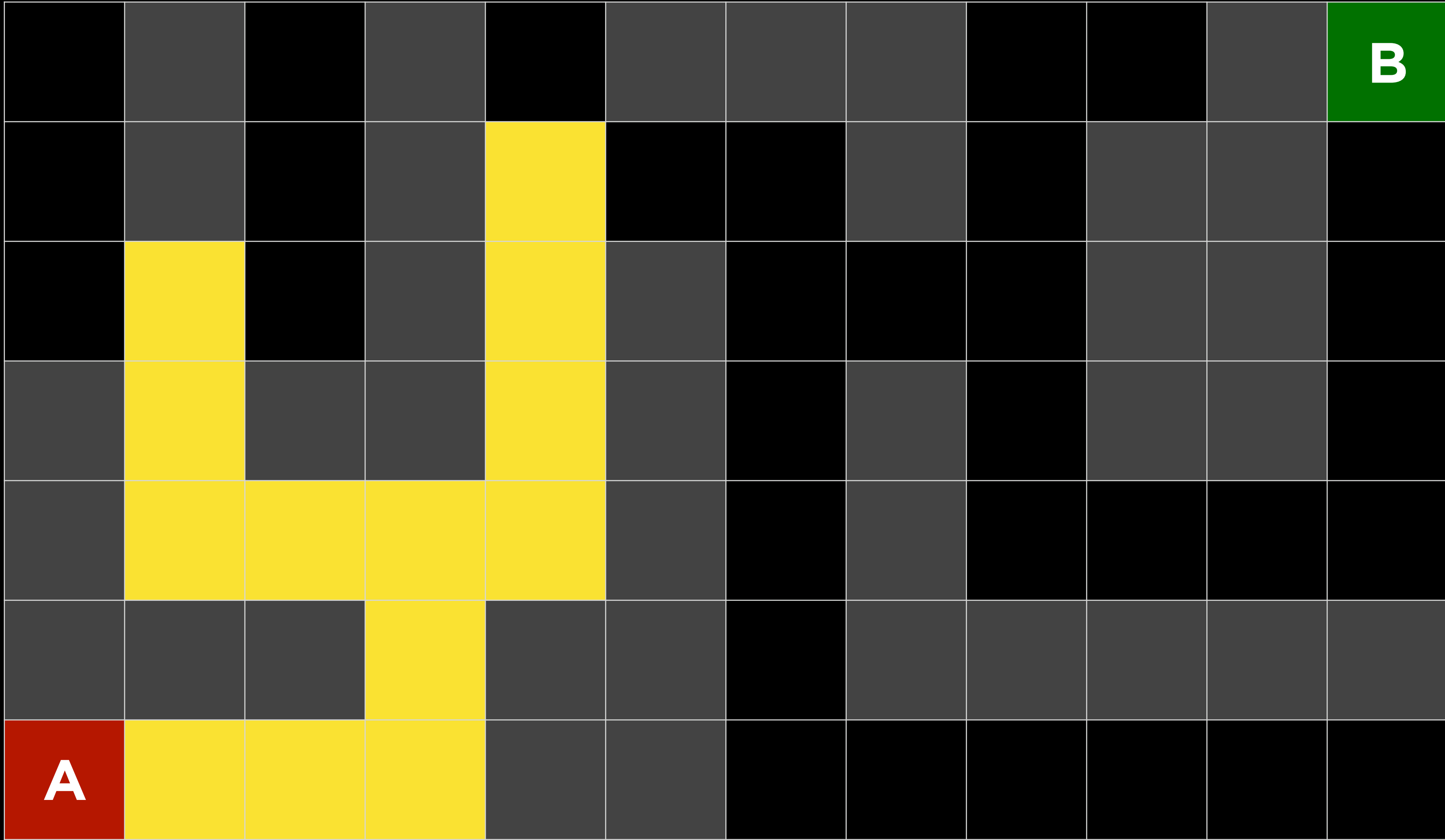
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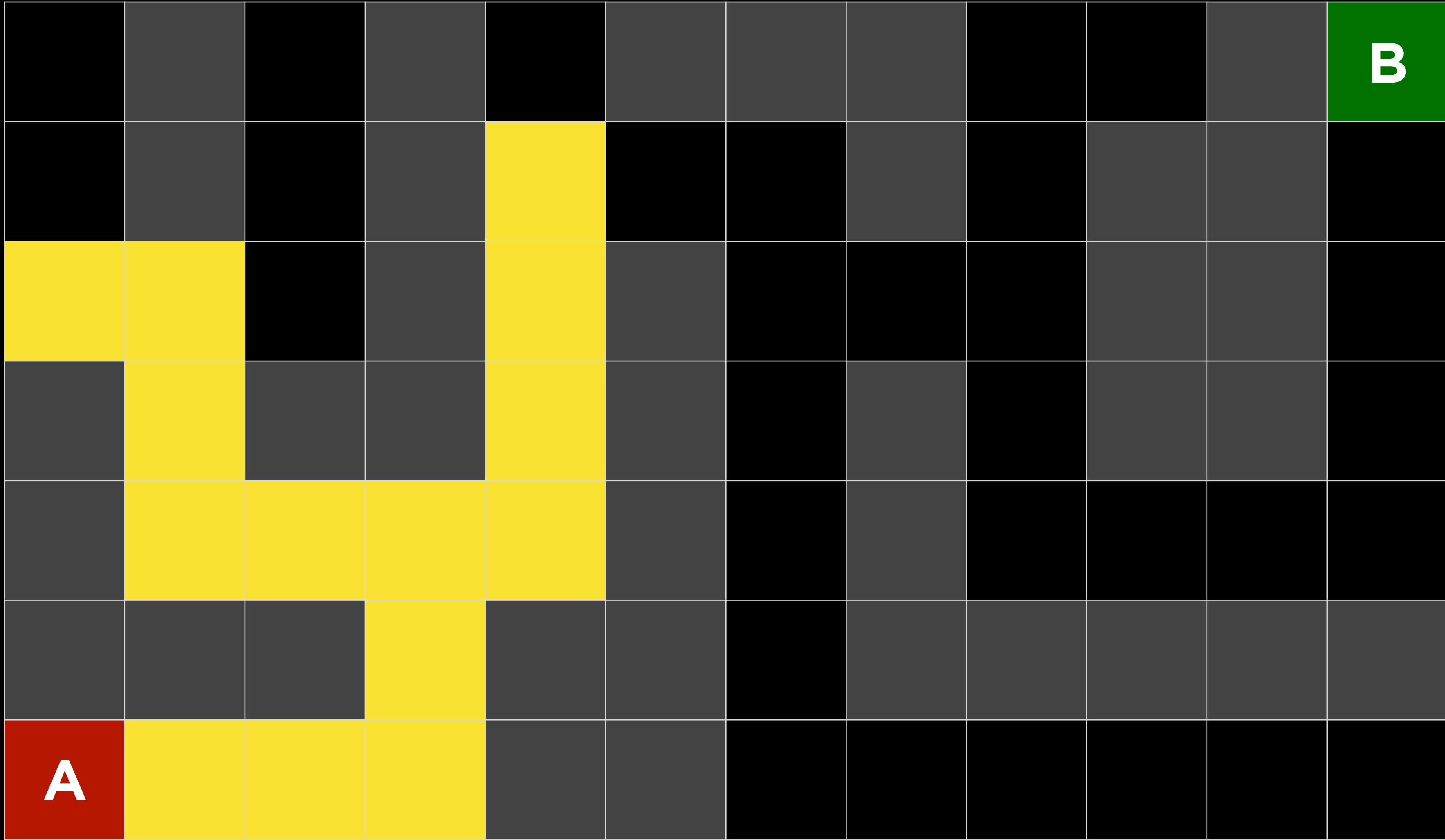
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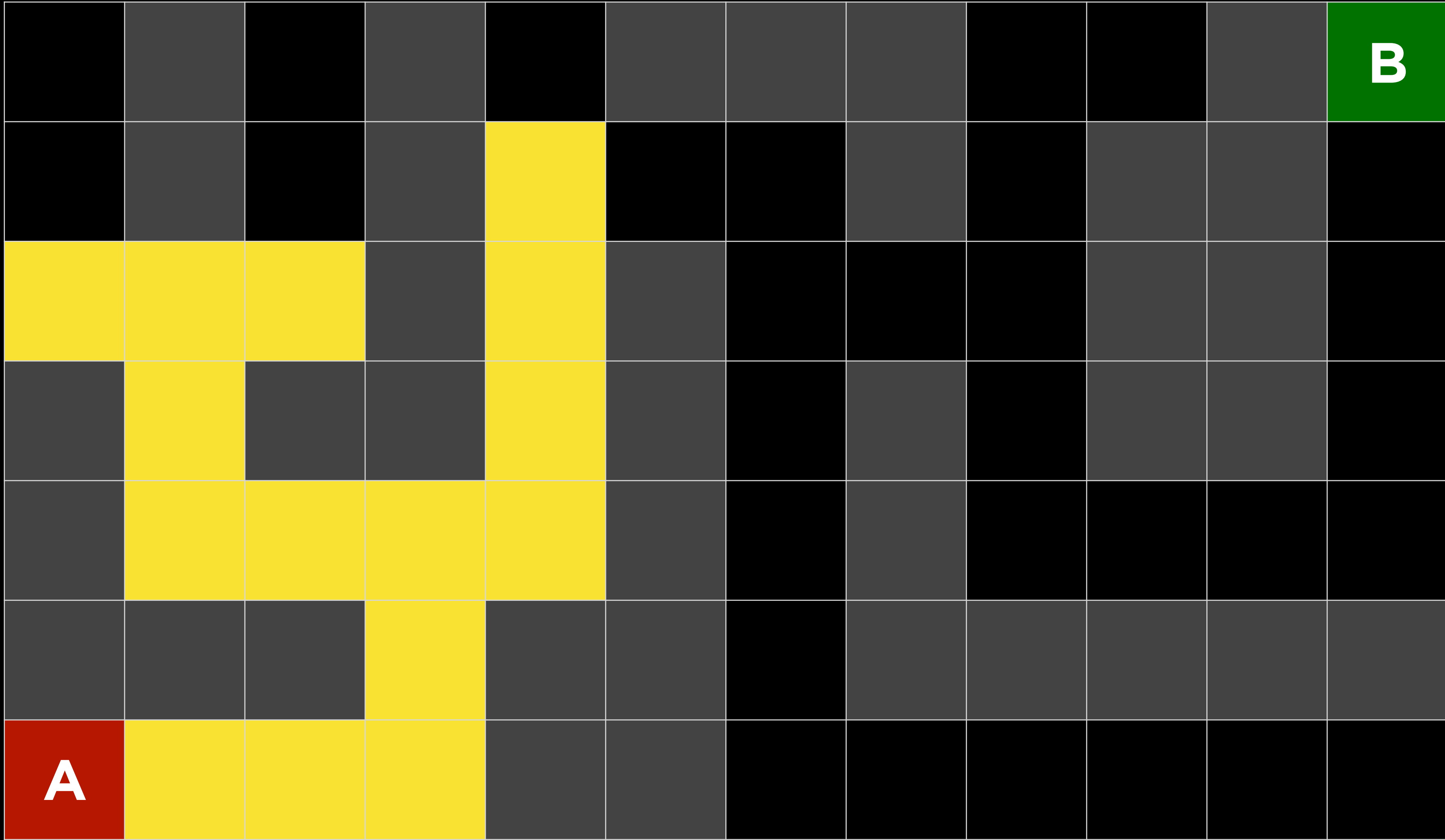
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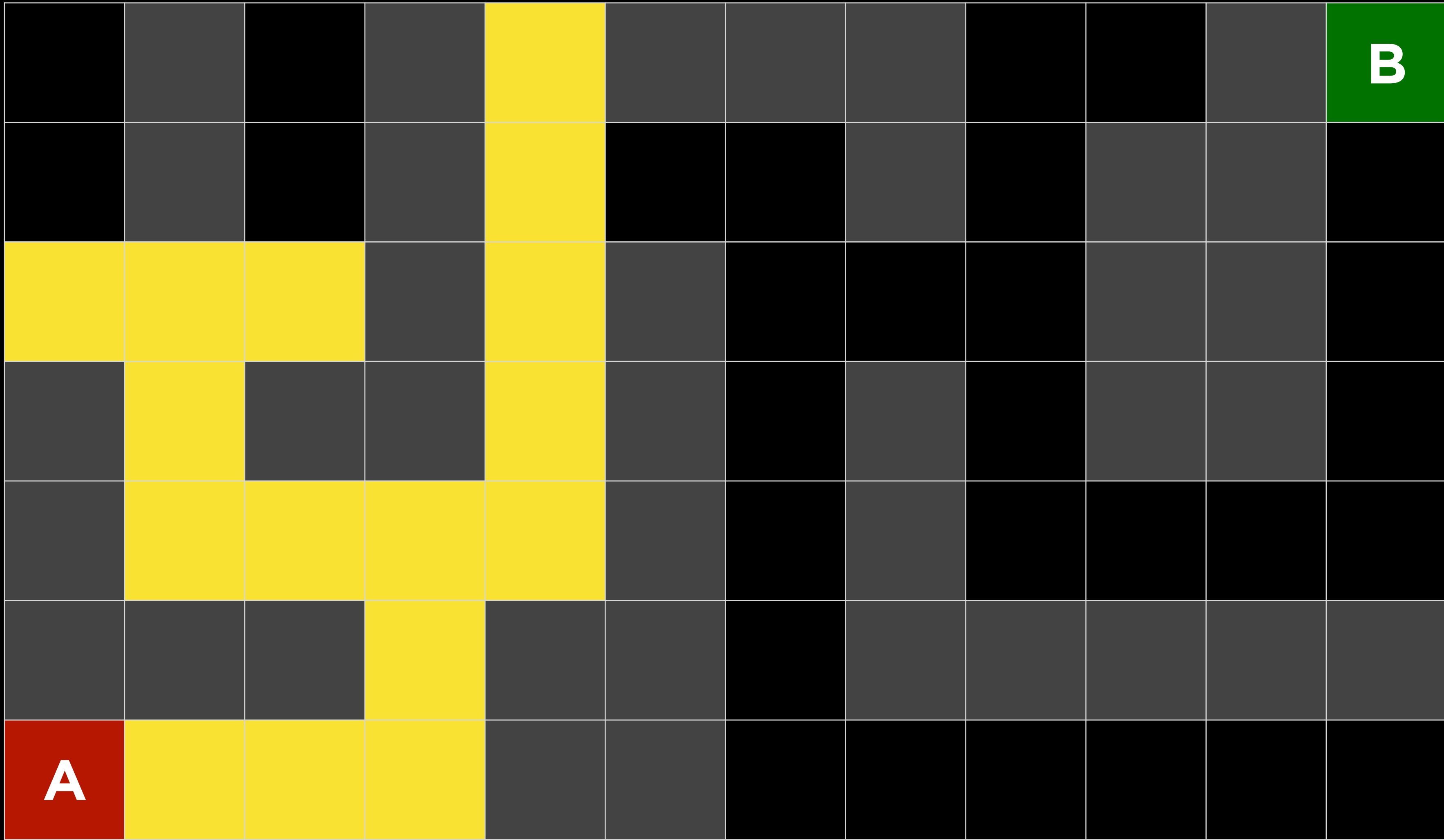
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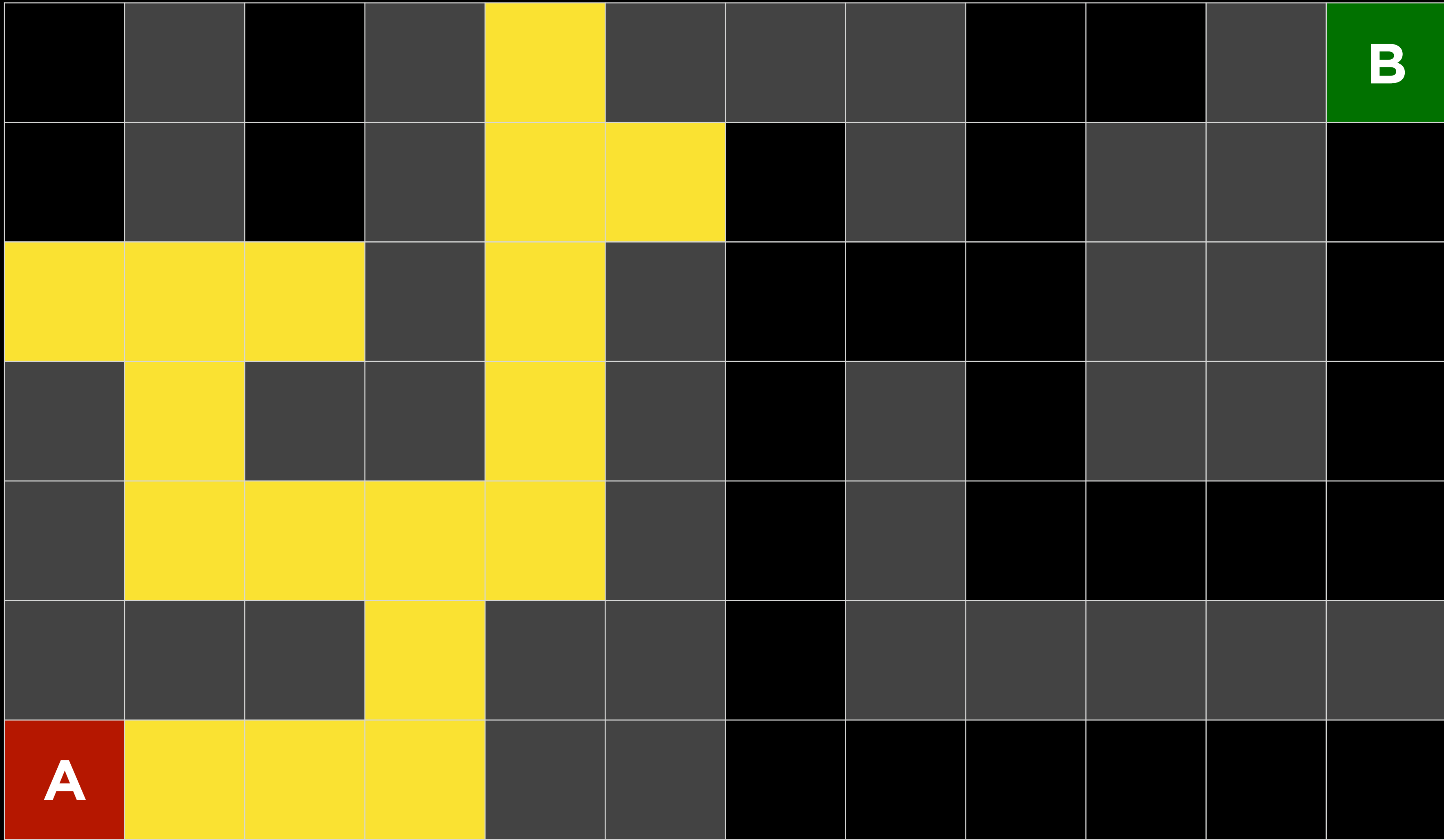
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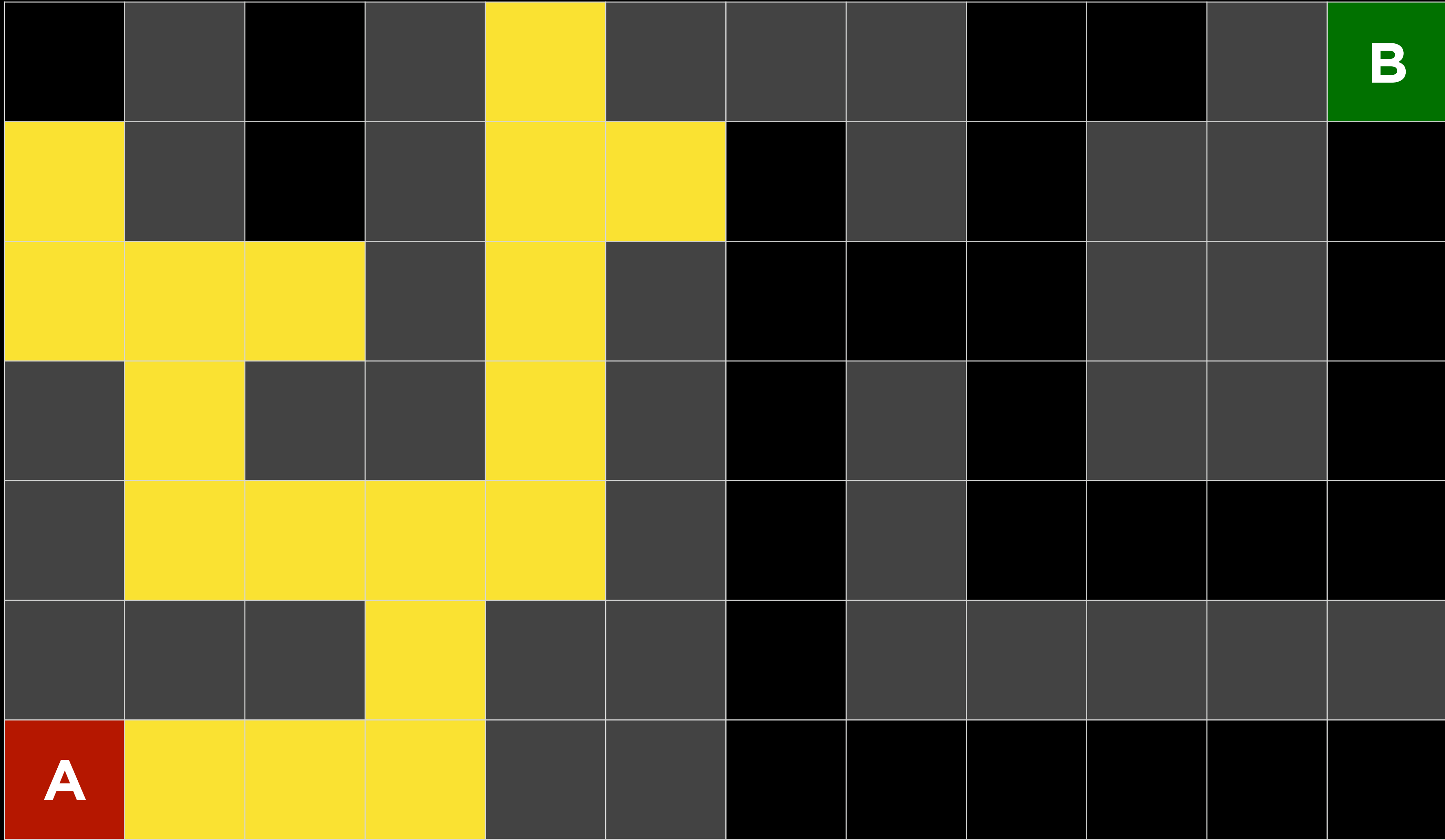
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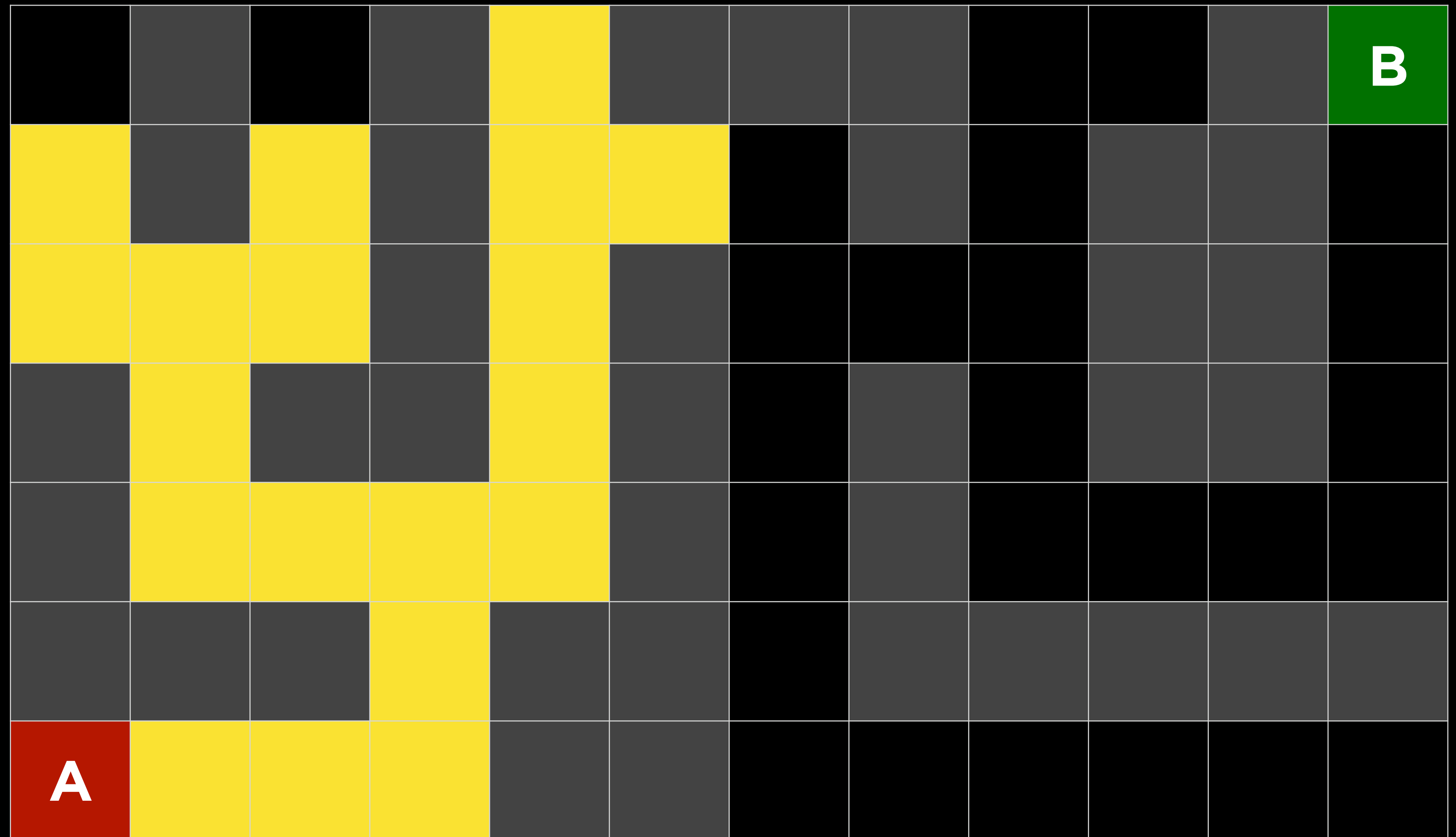
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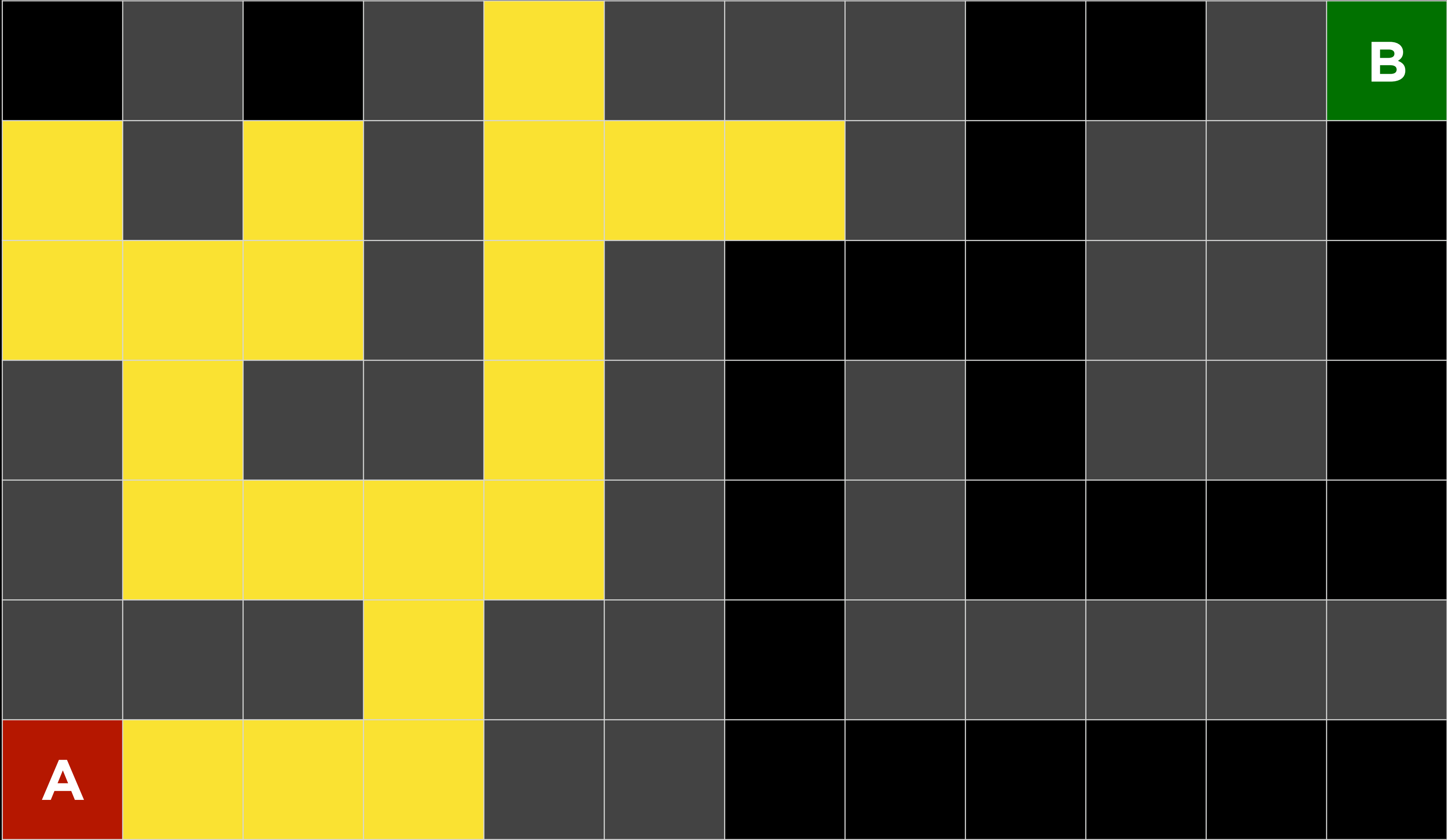
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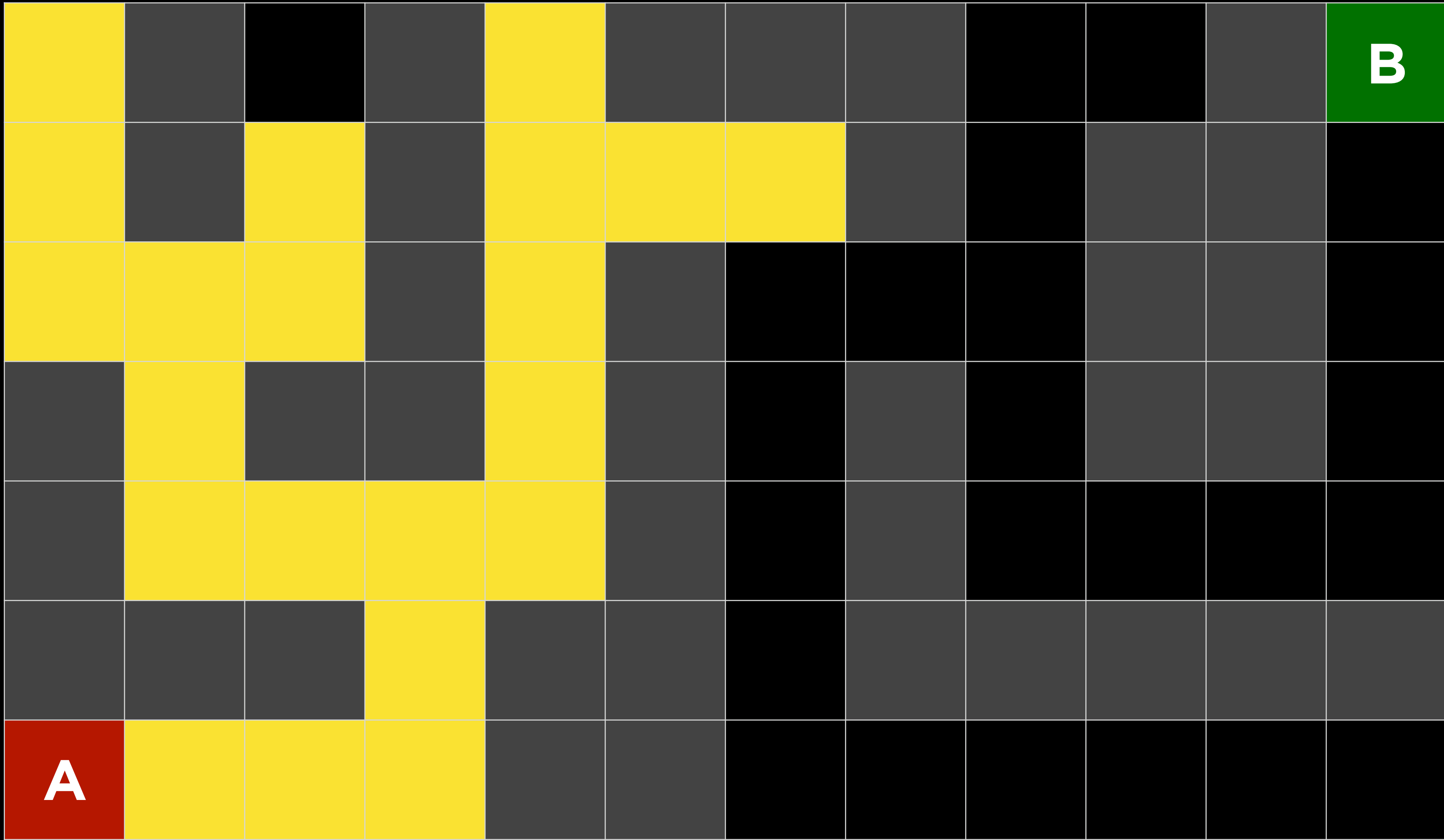
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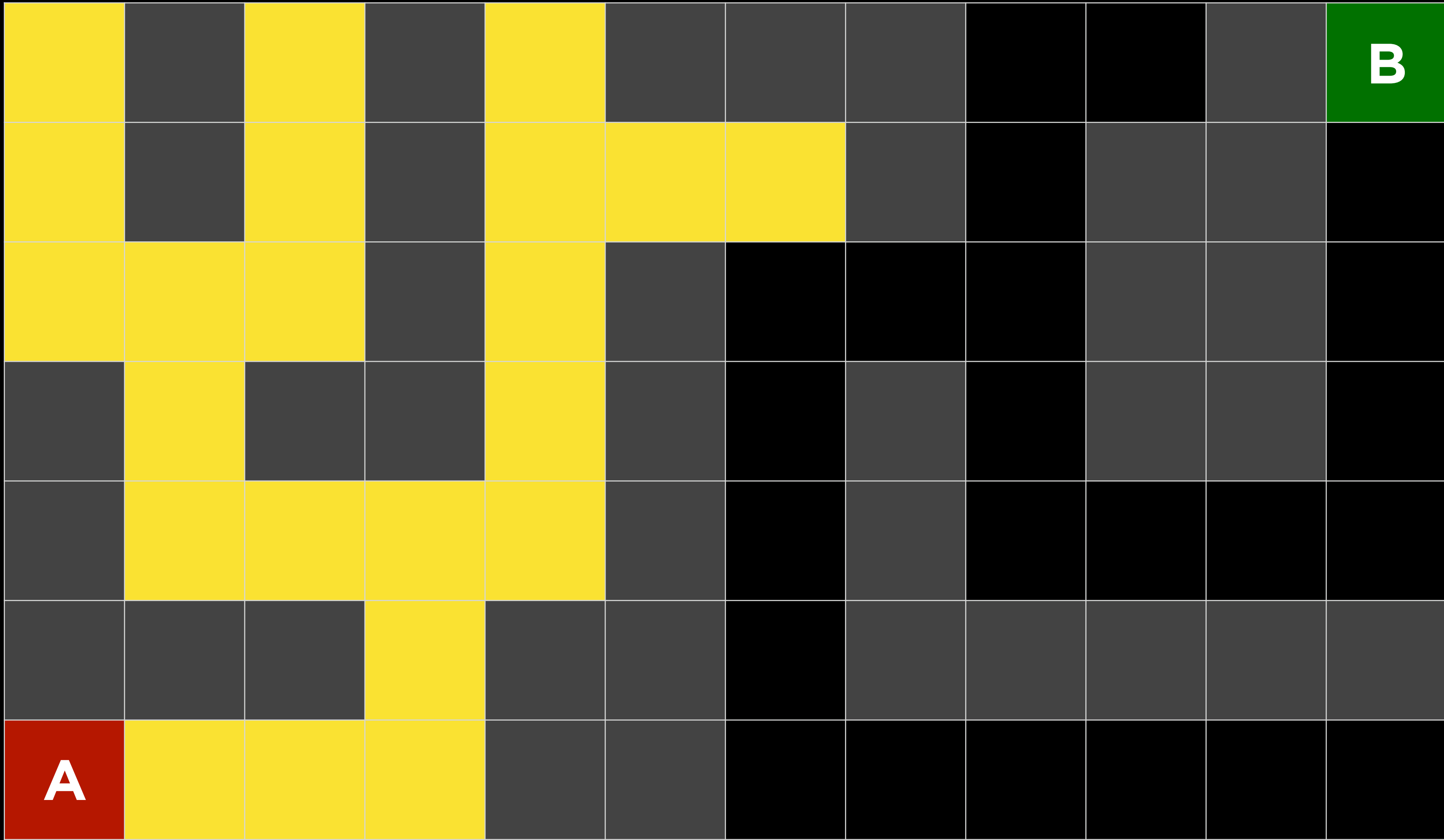
Breadth-First Search



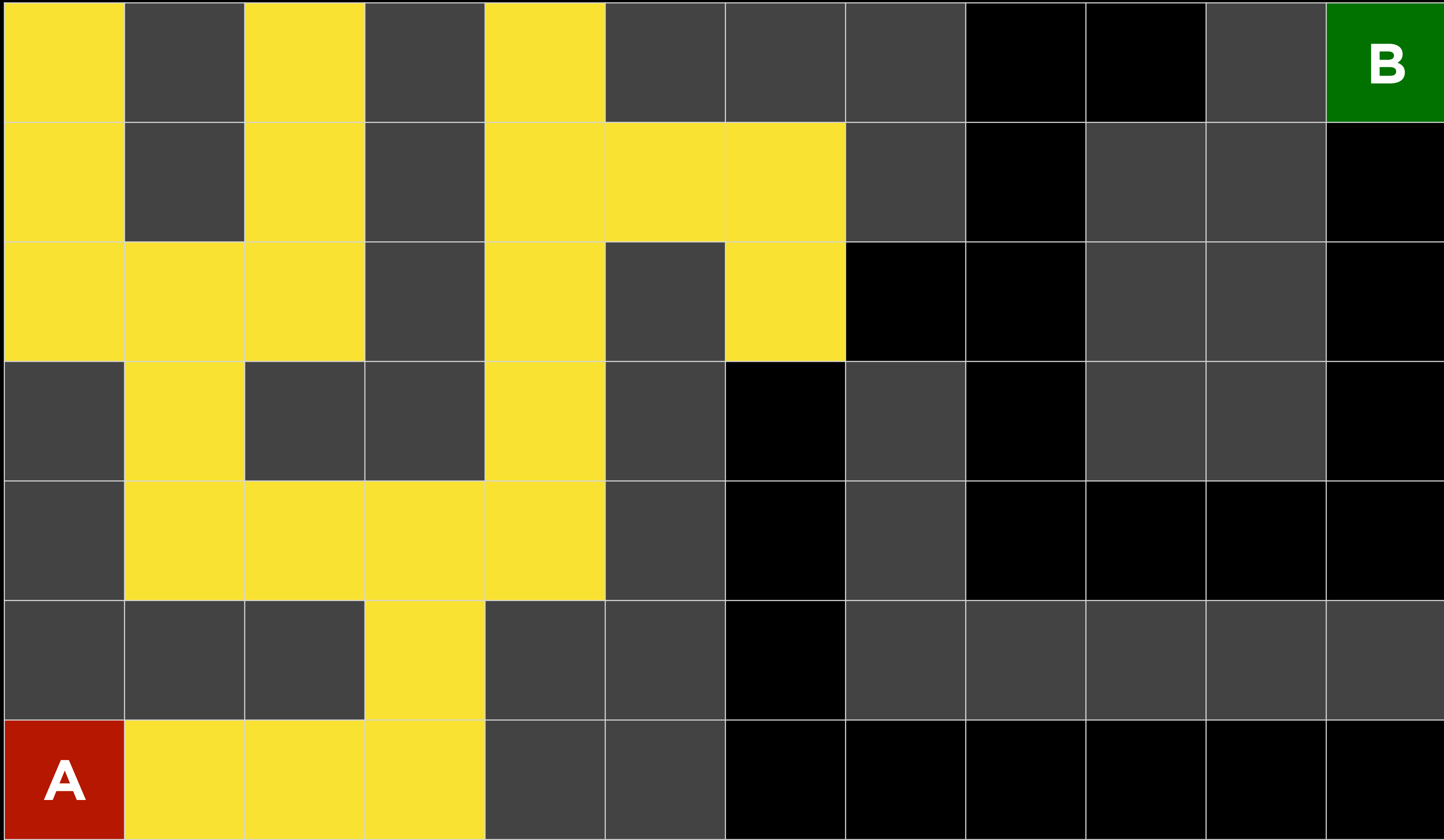
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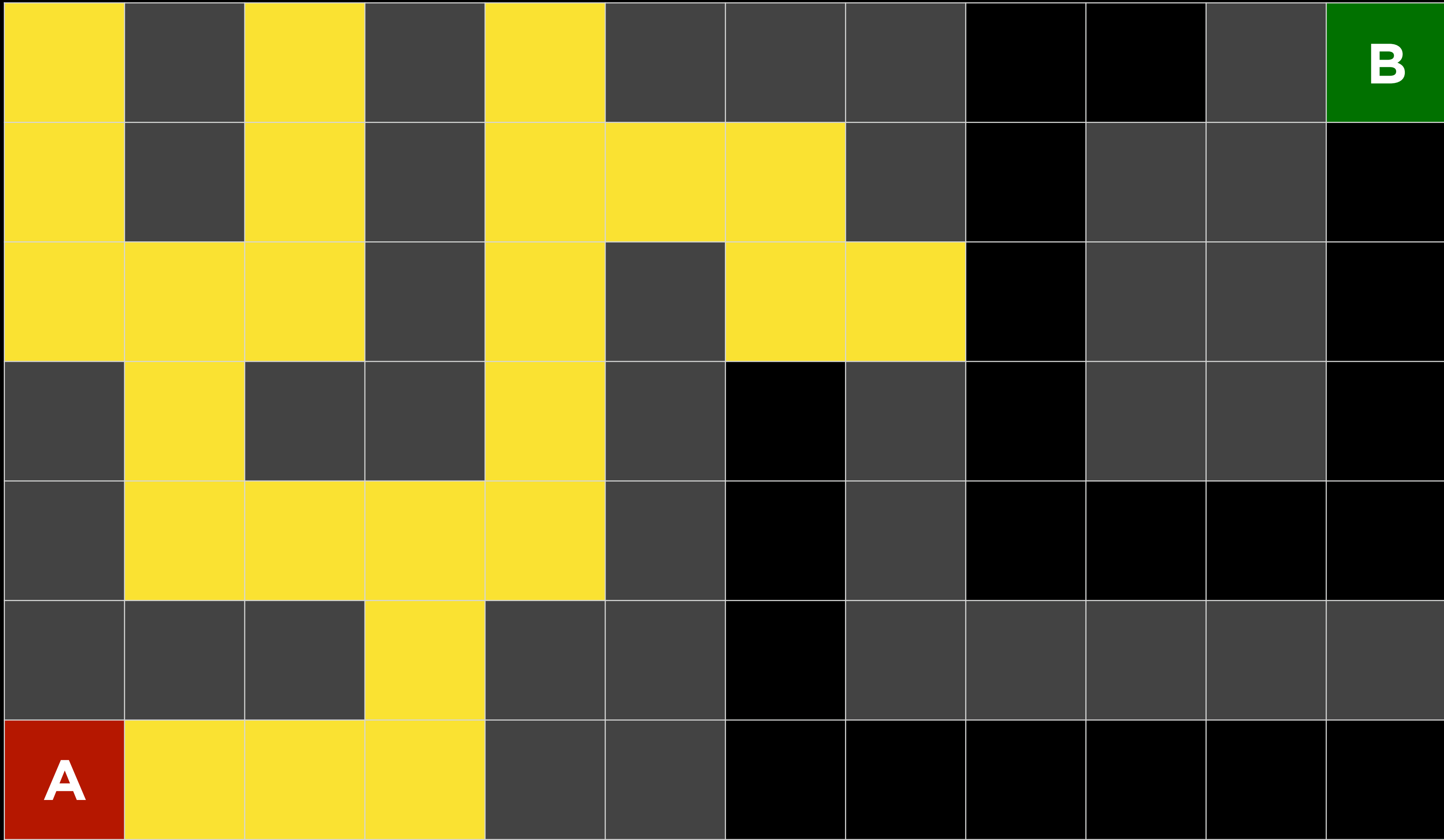
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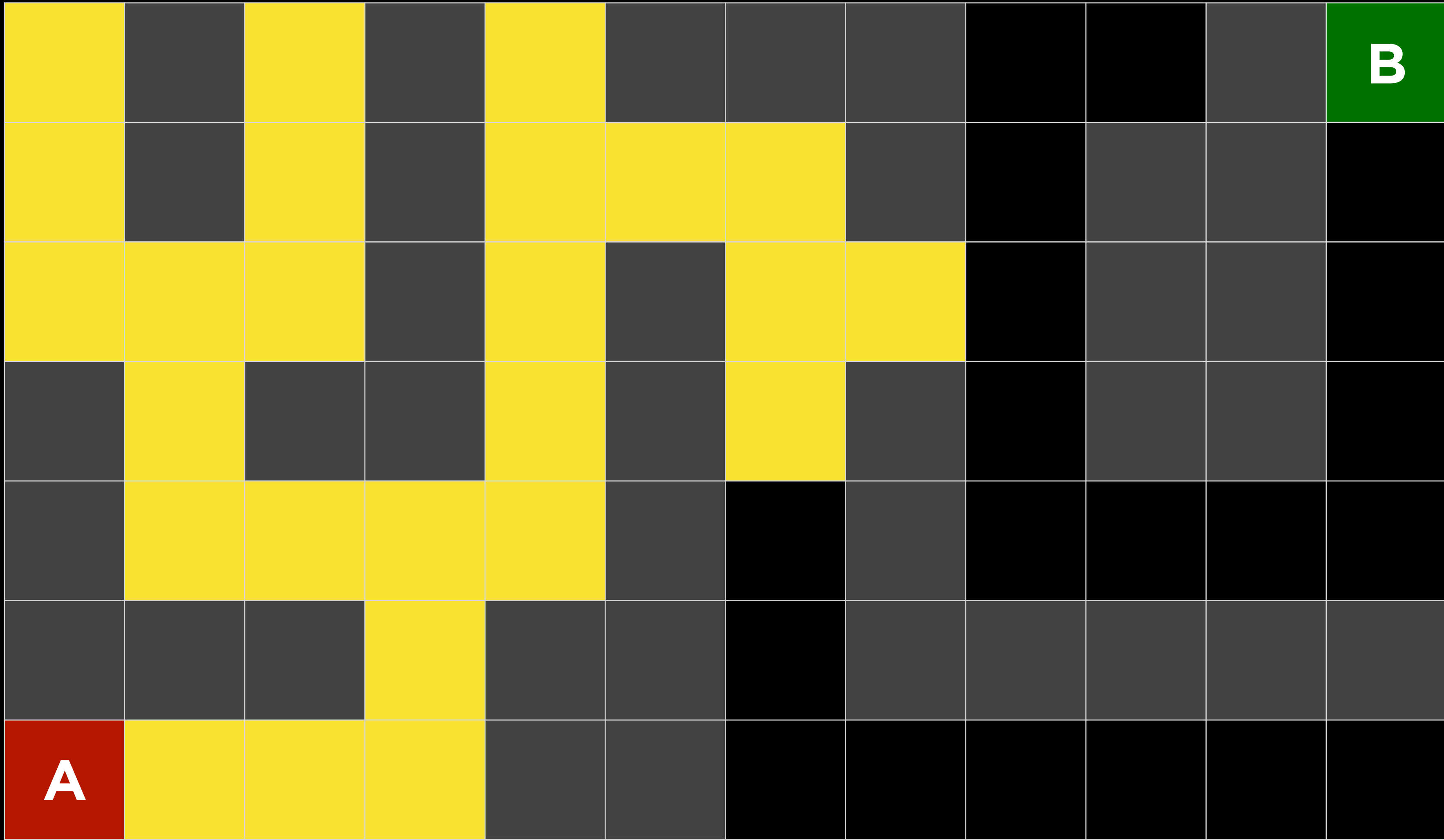
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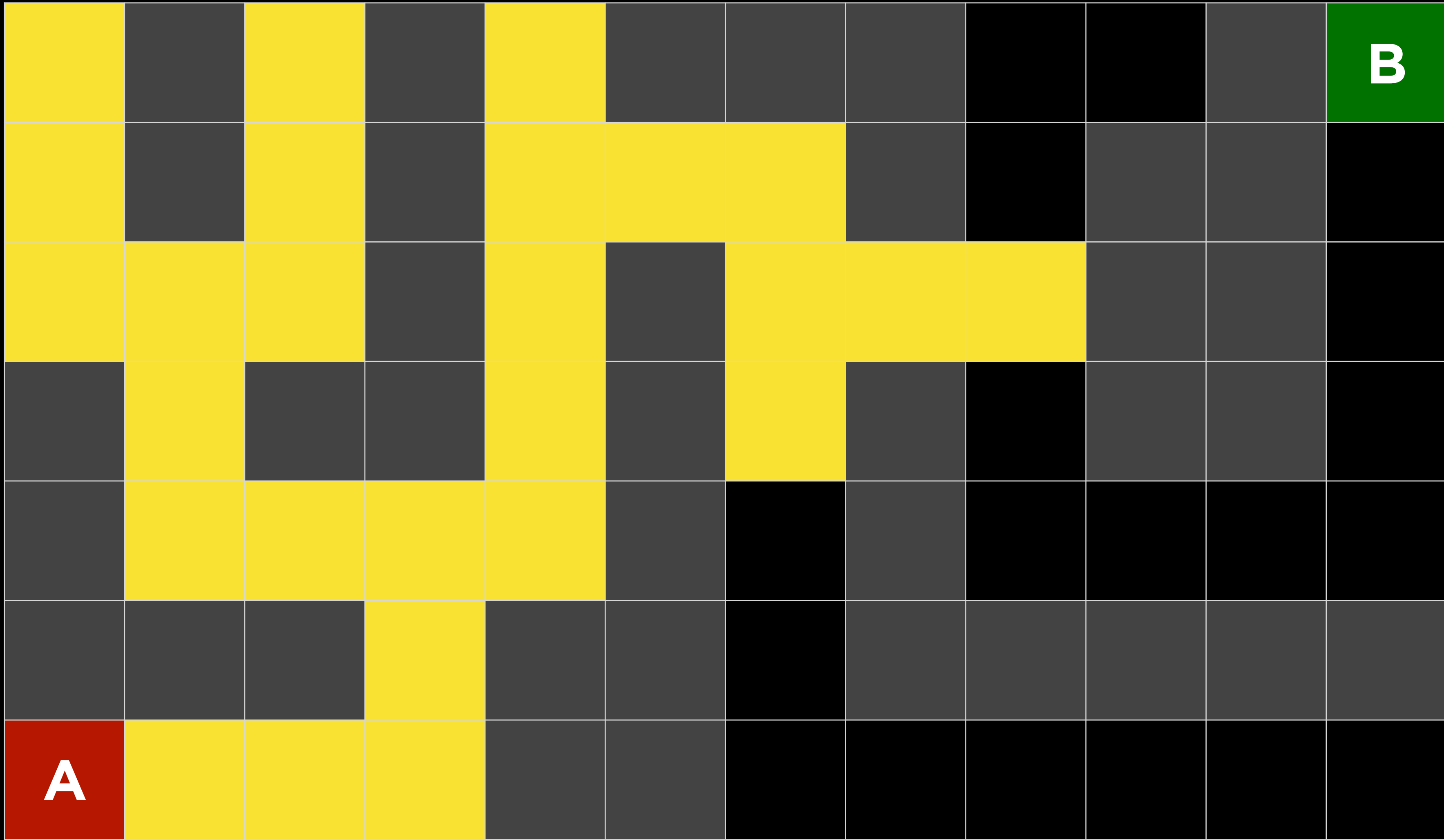
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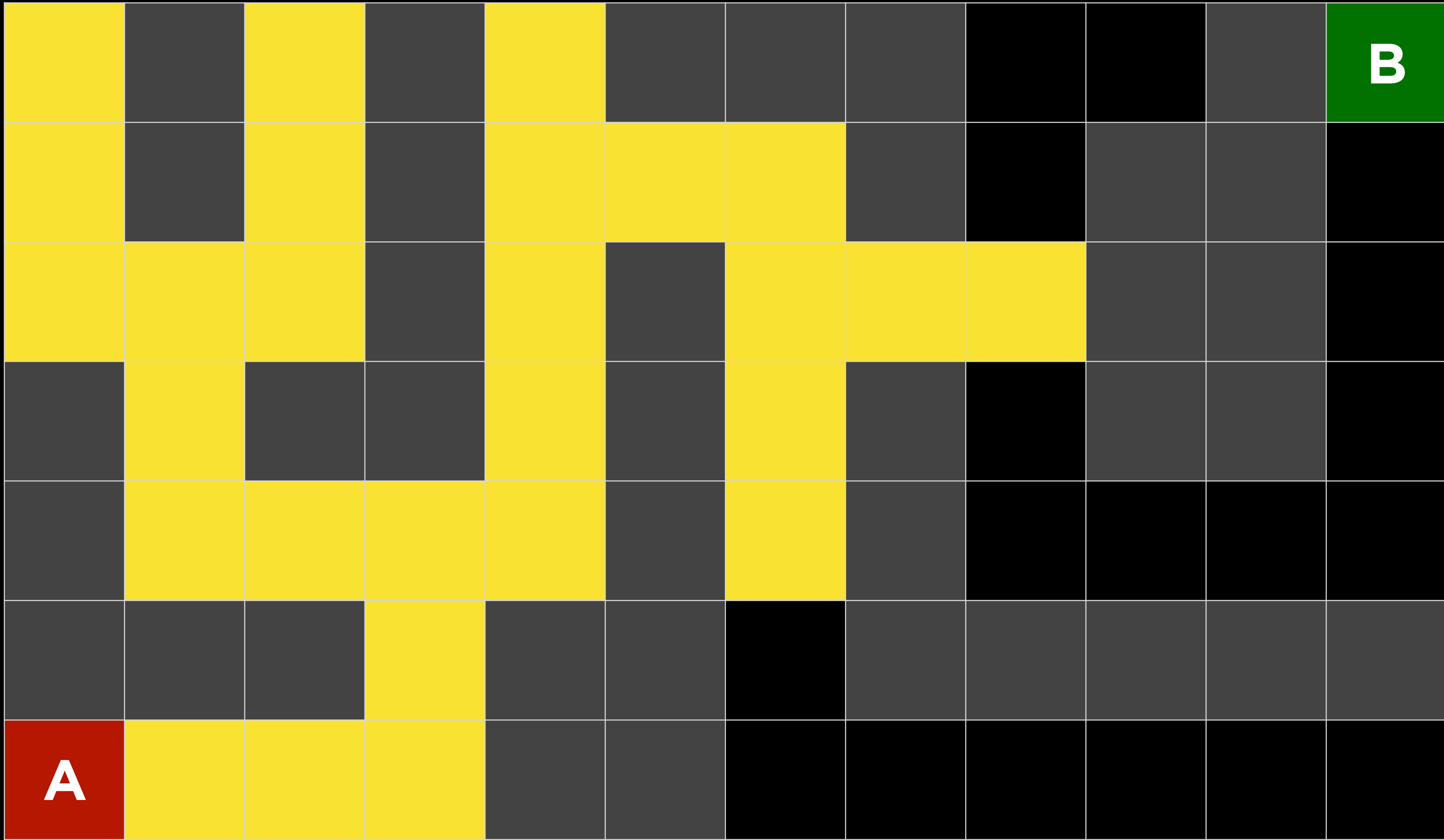
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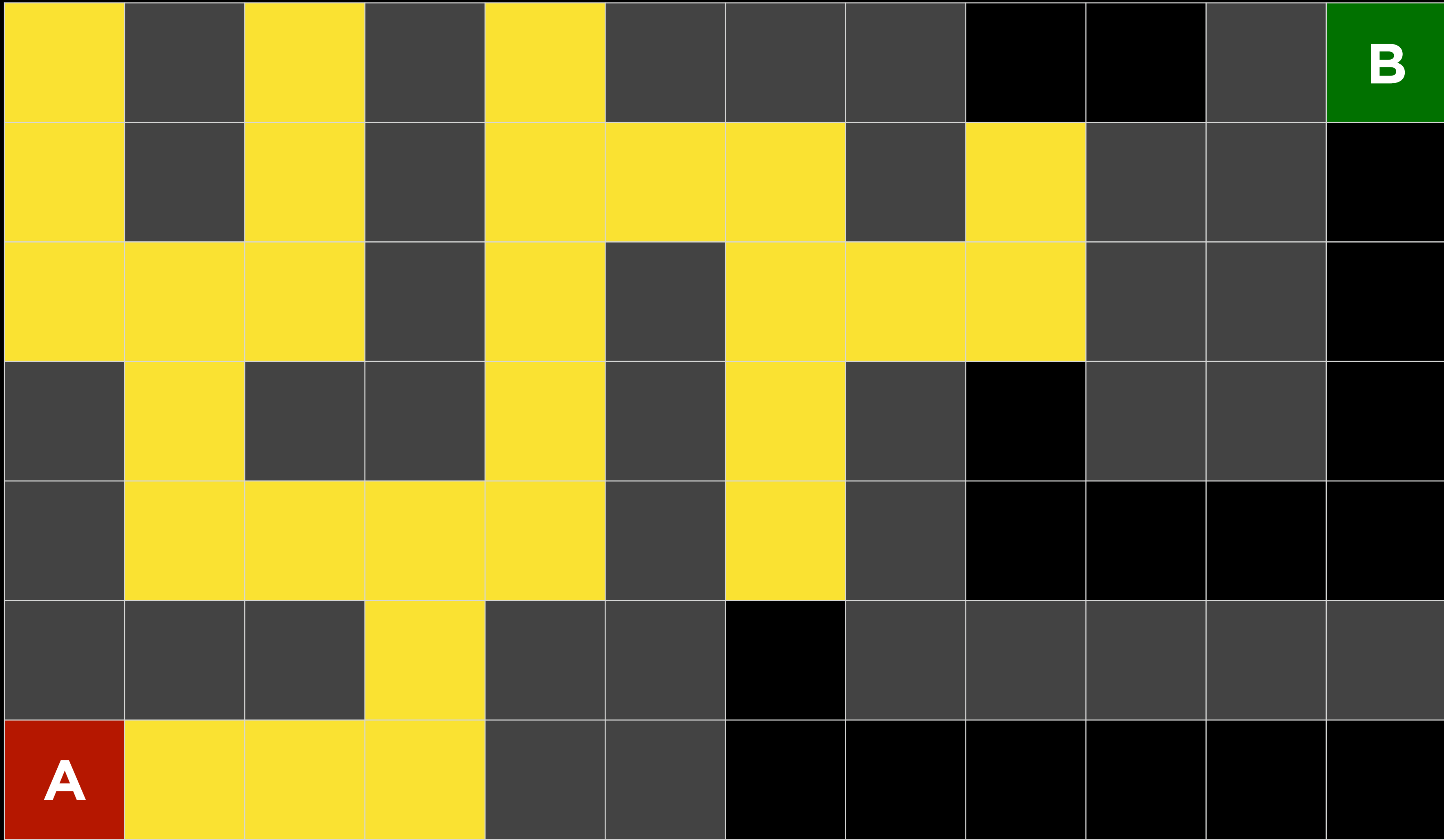
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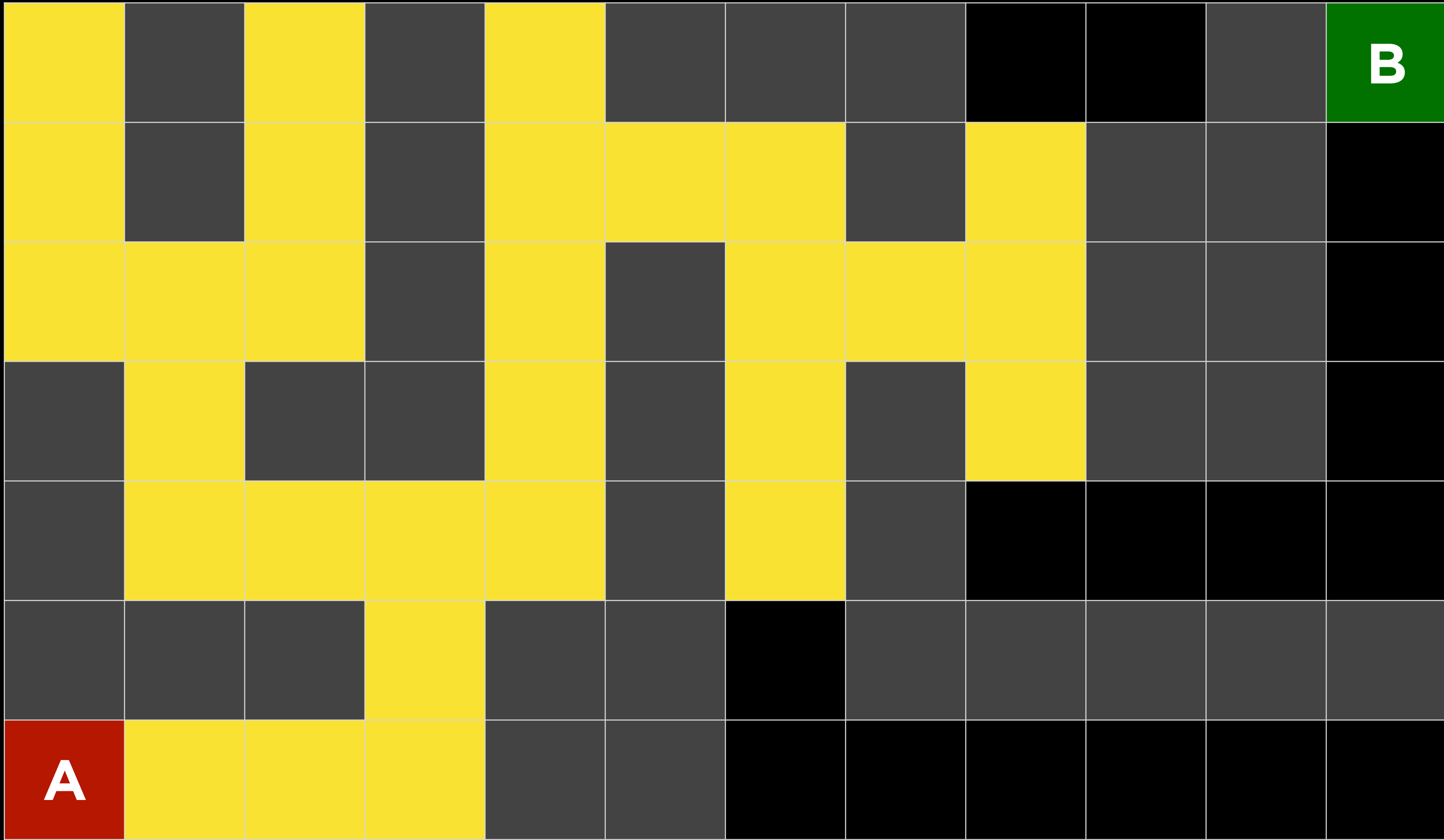
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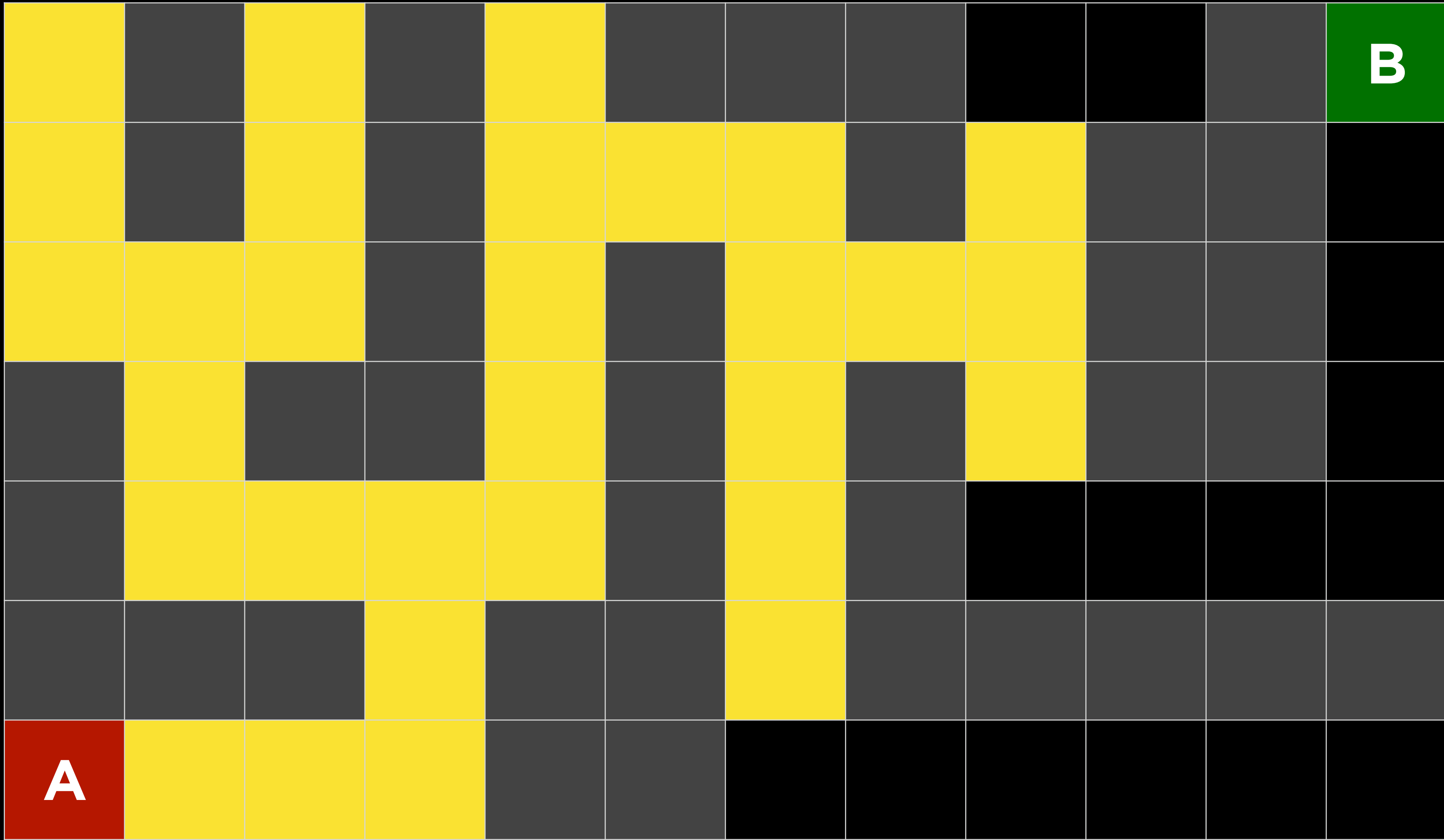
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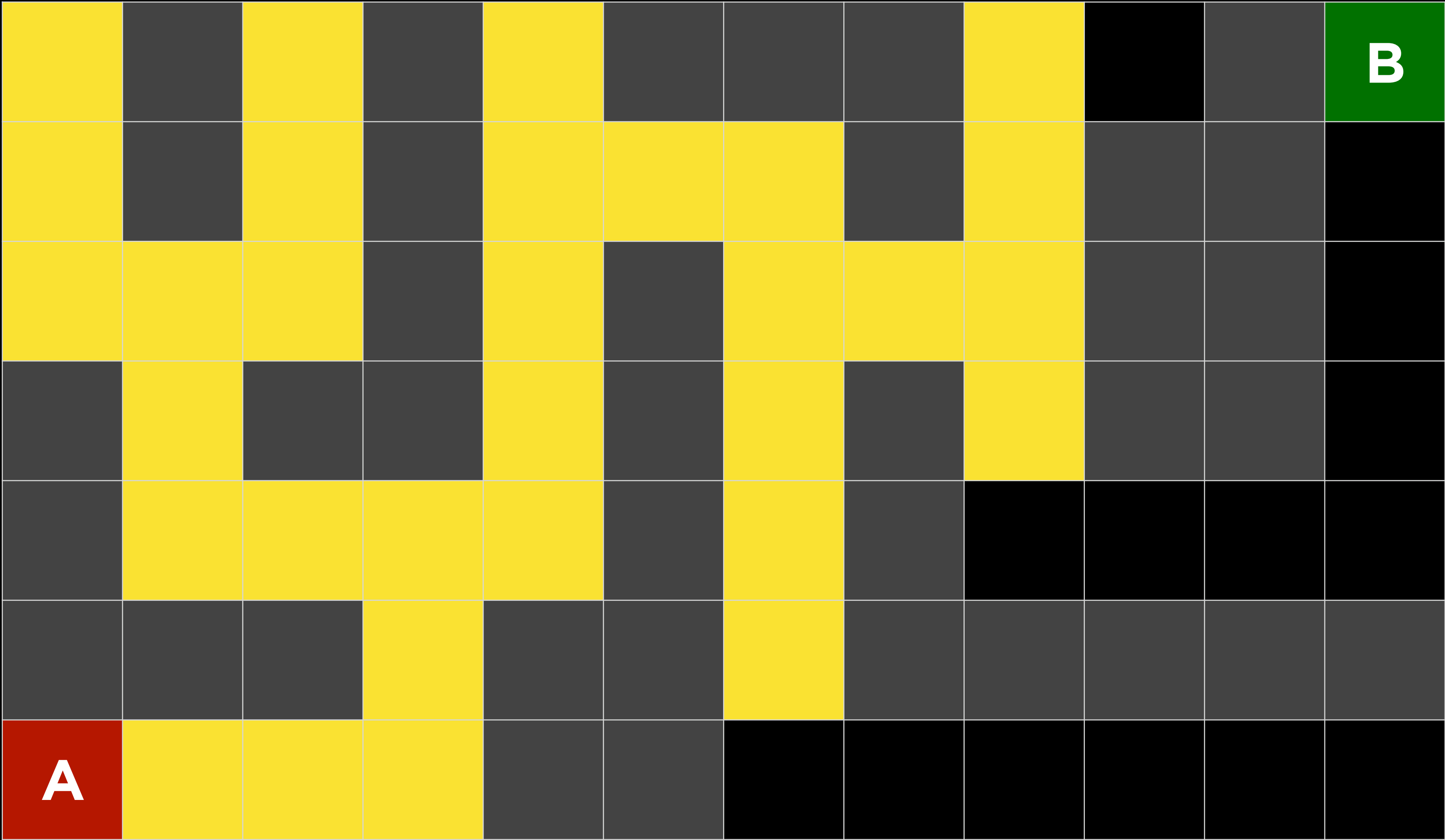
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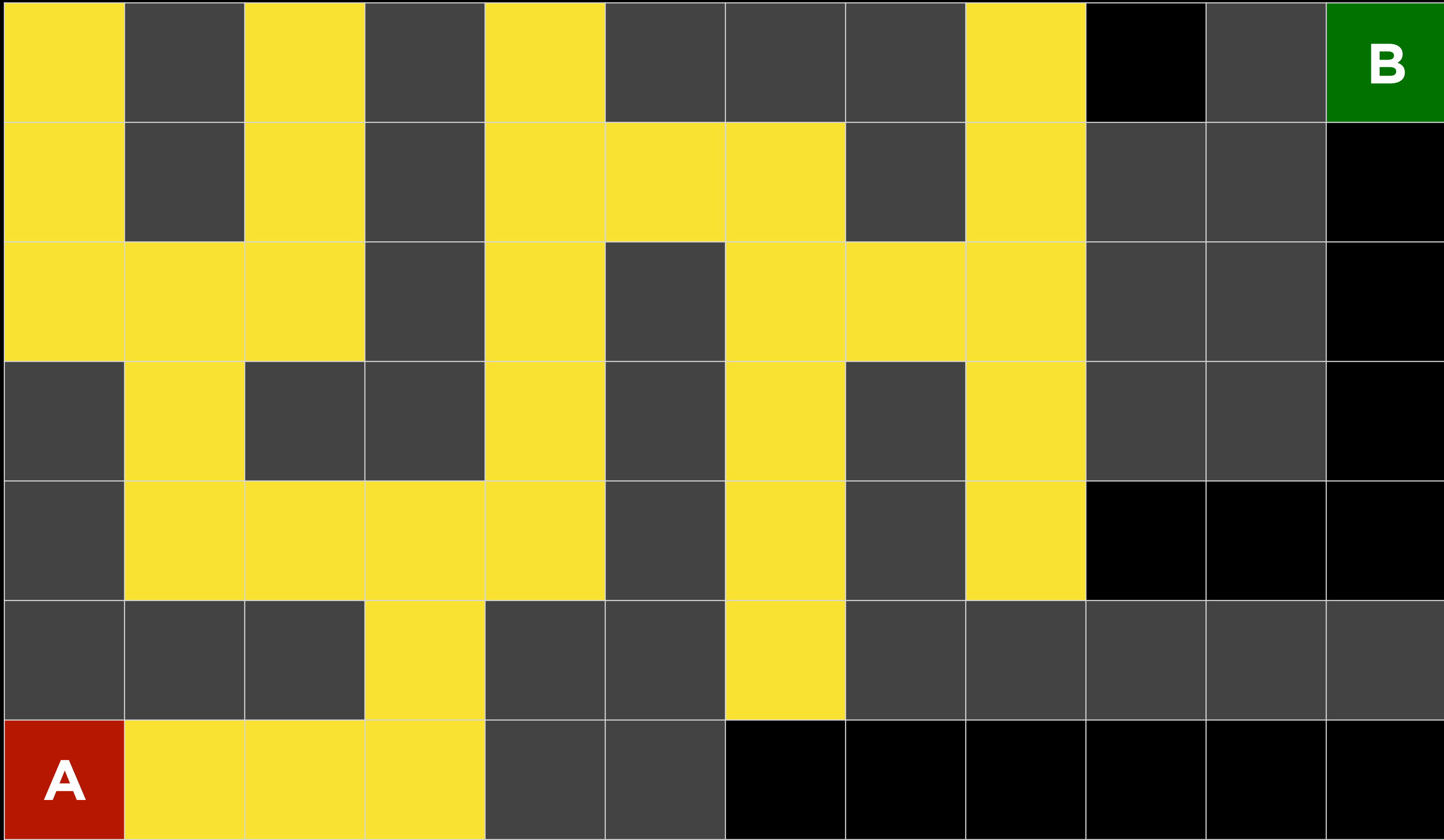
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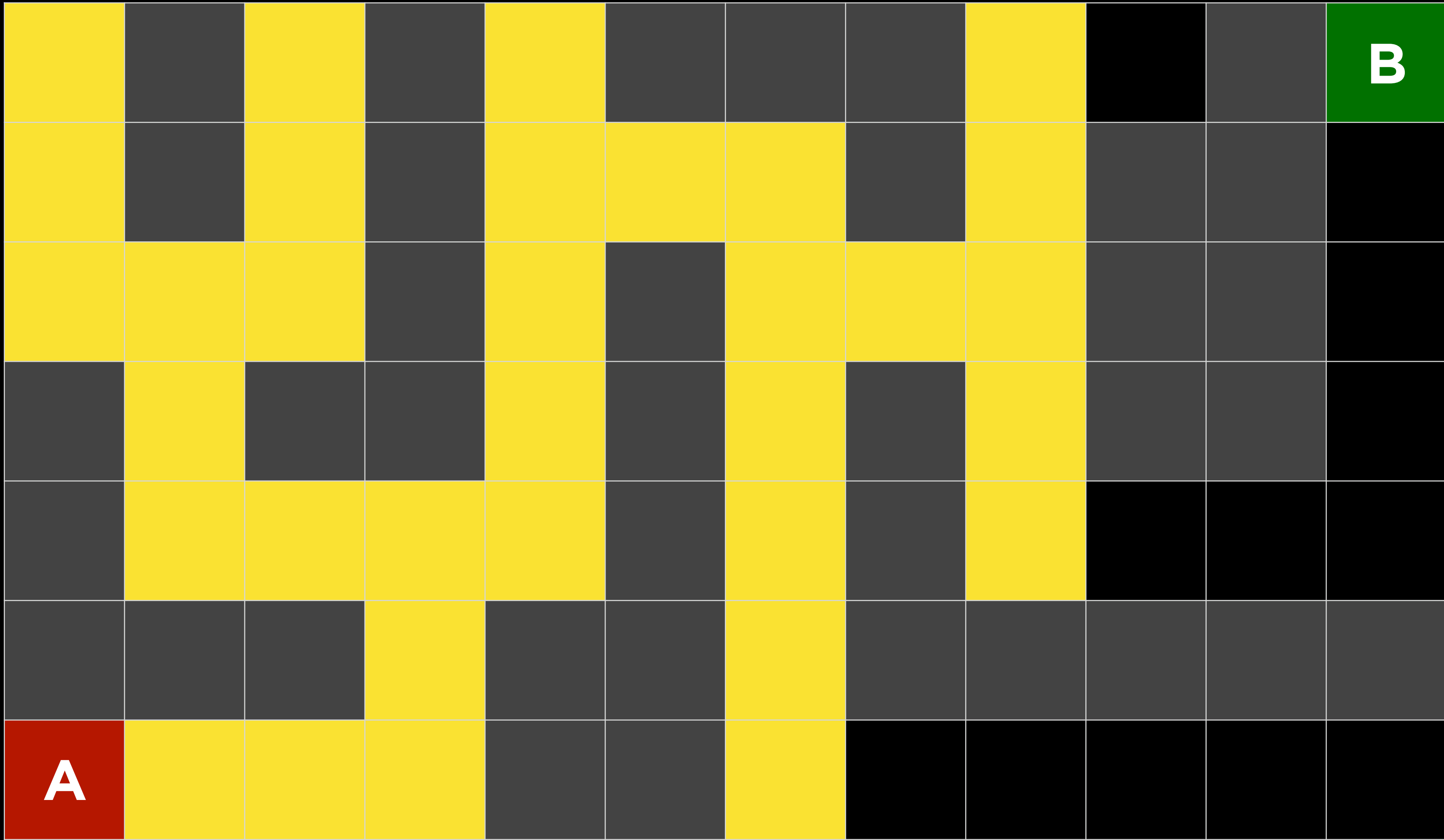
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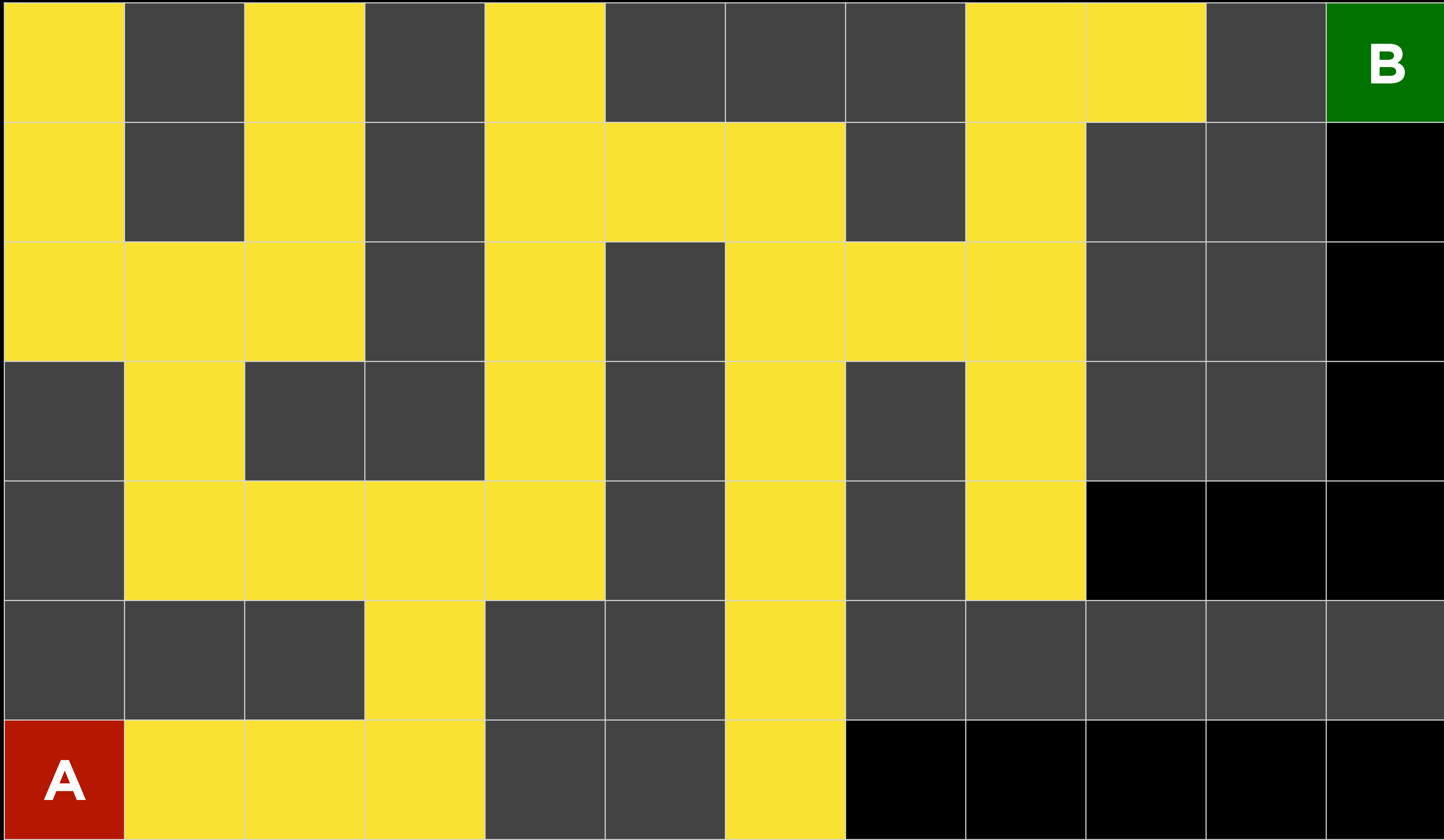
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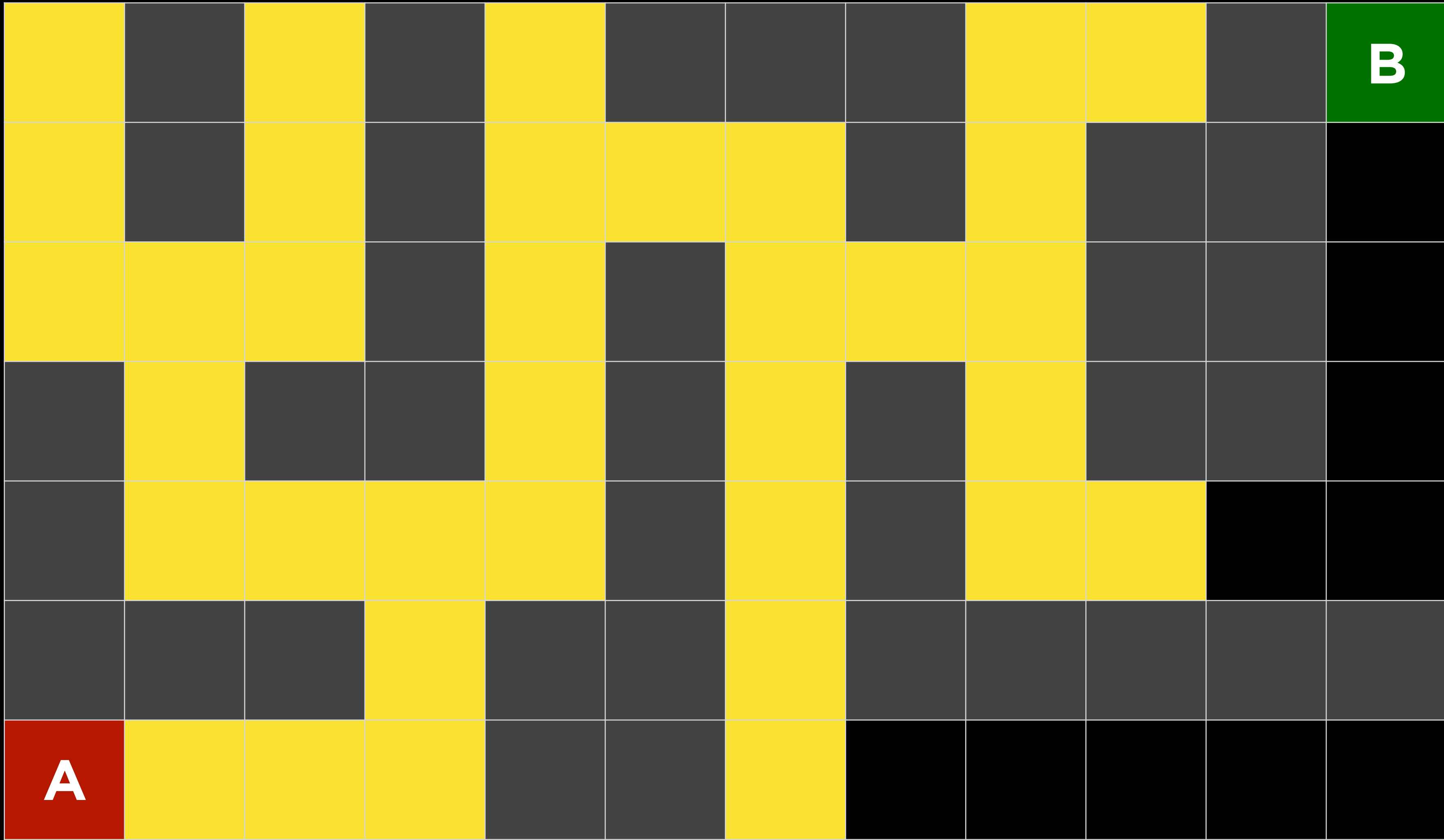
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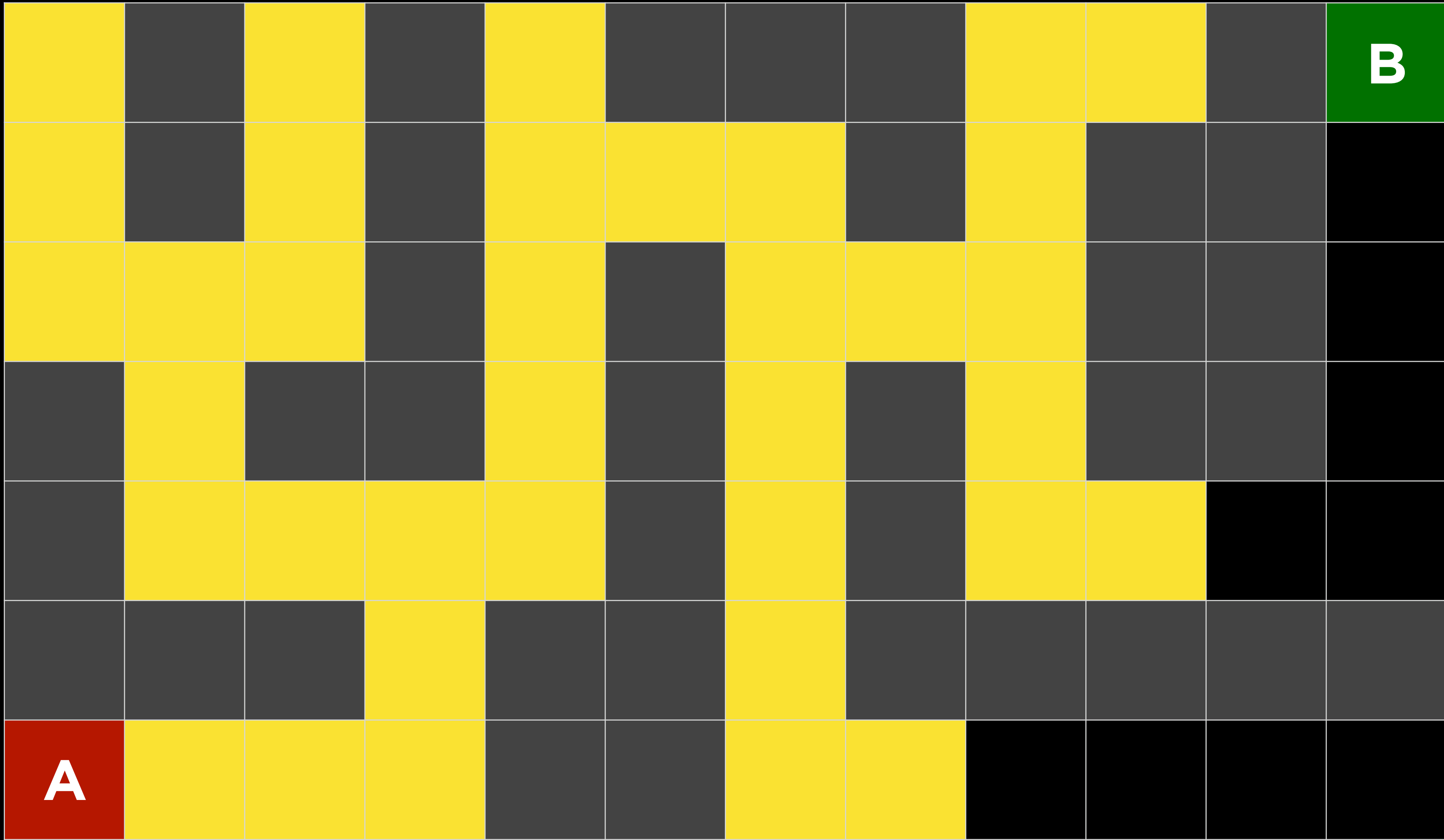
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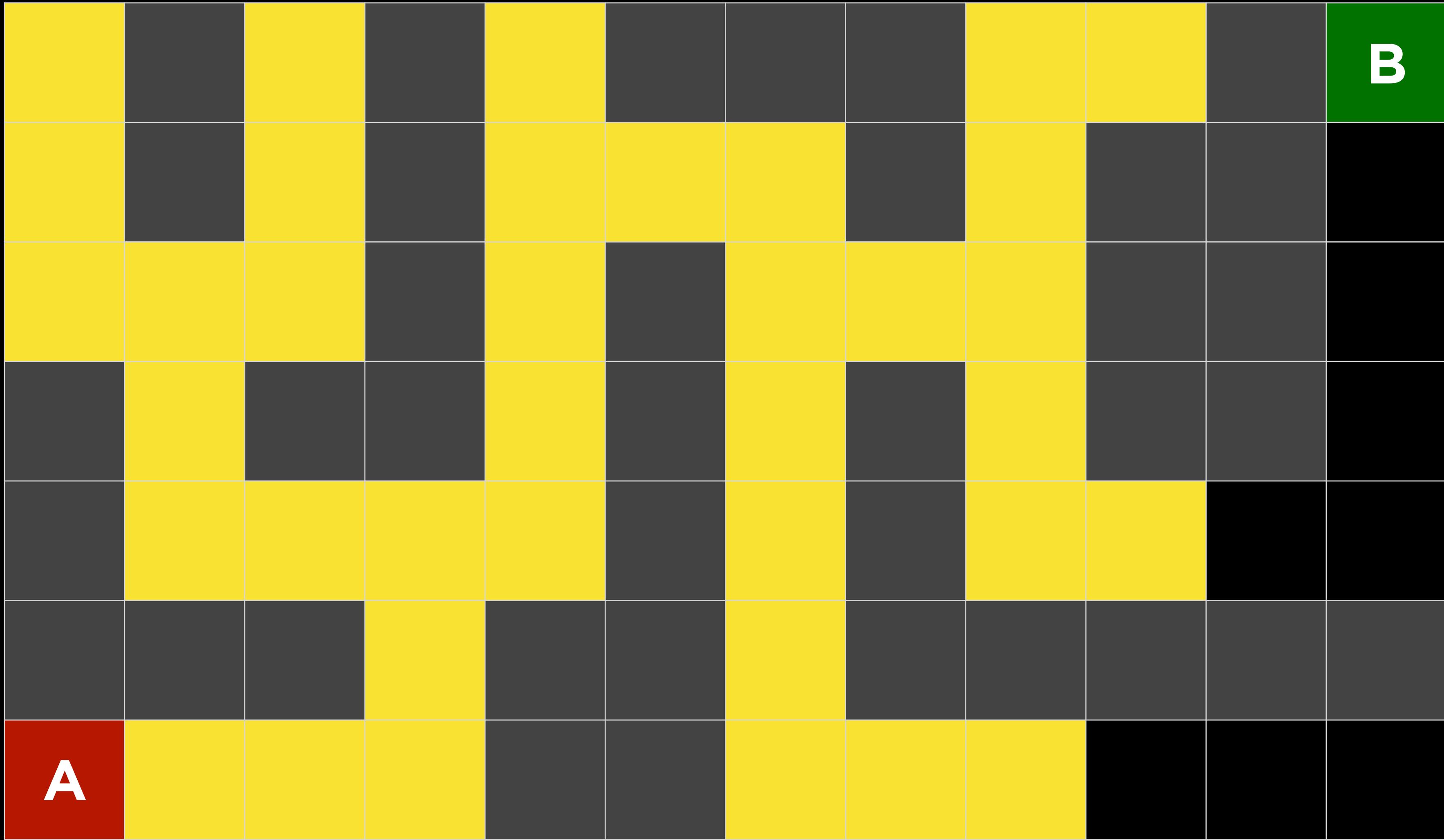
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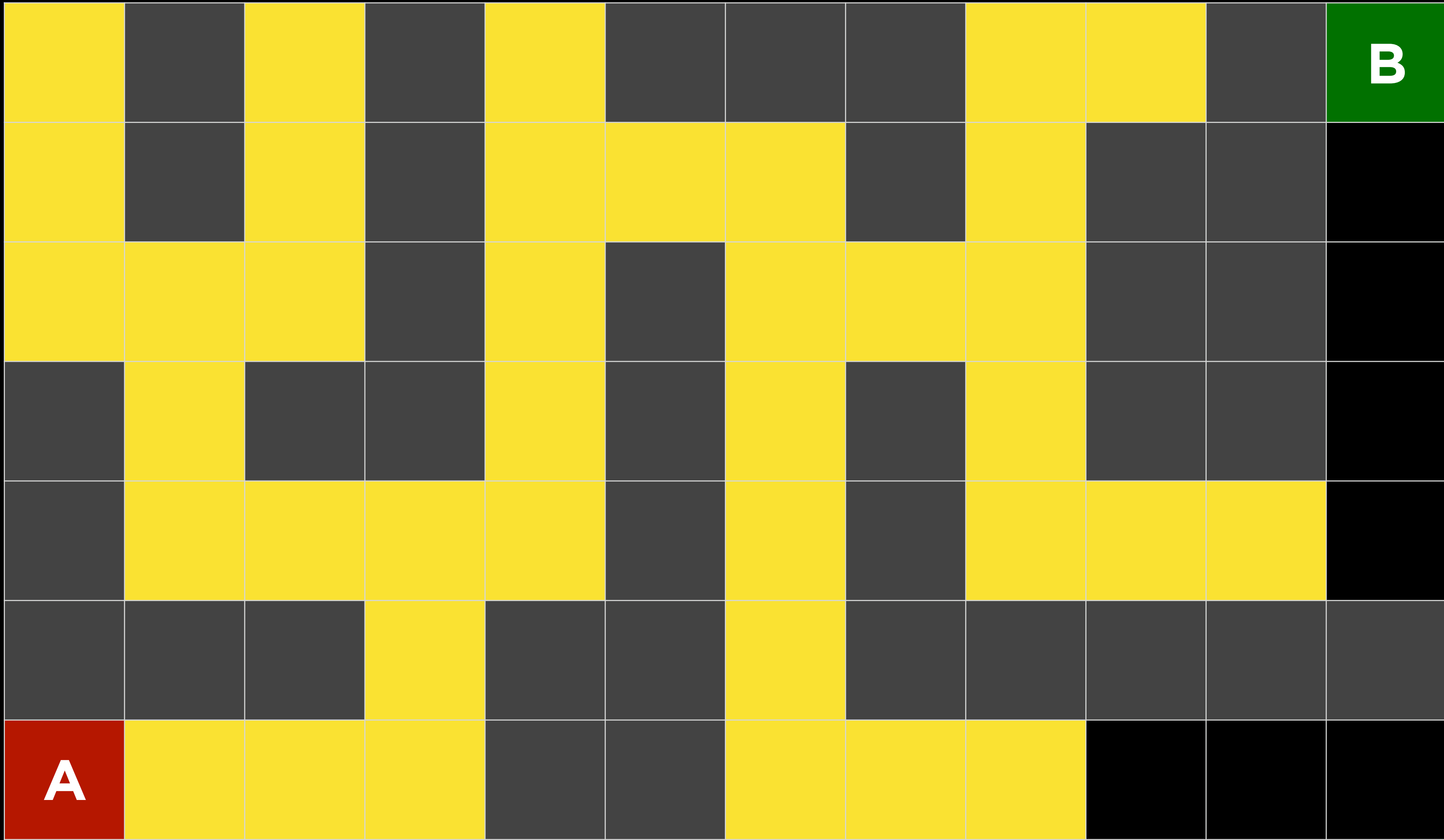
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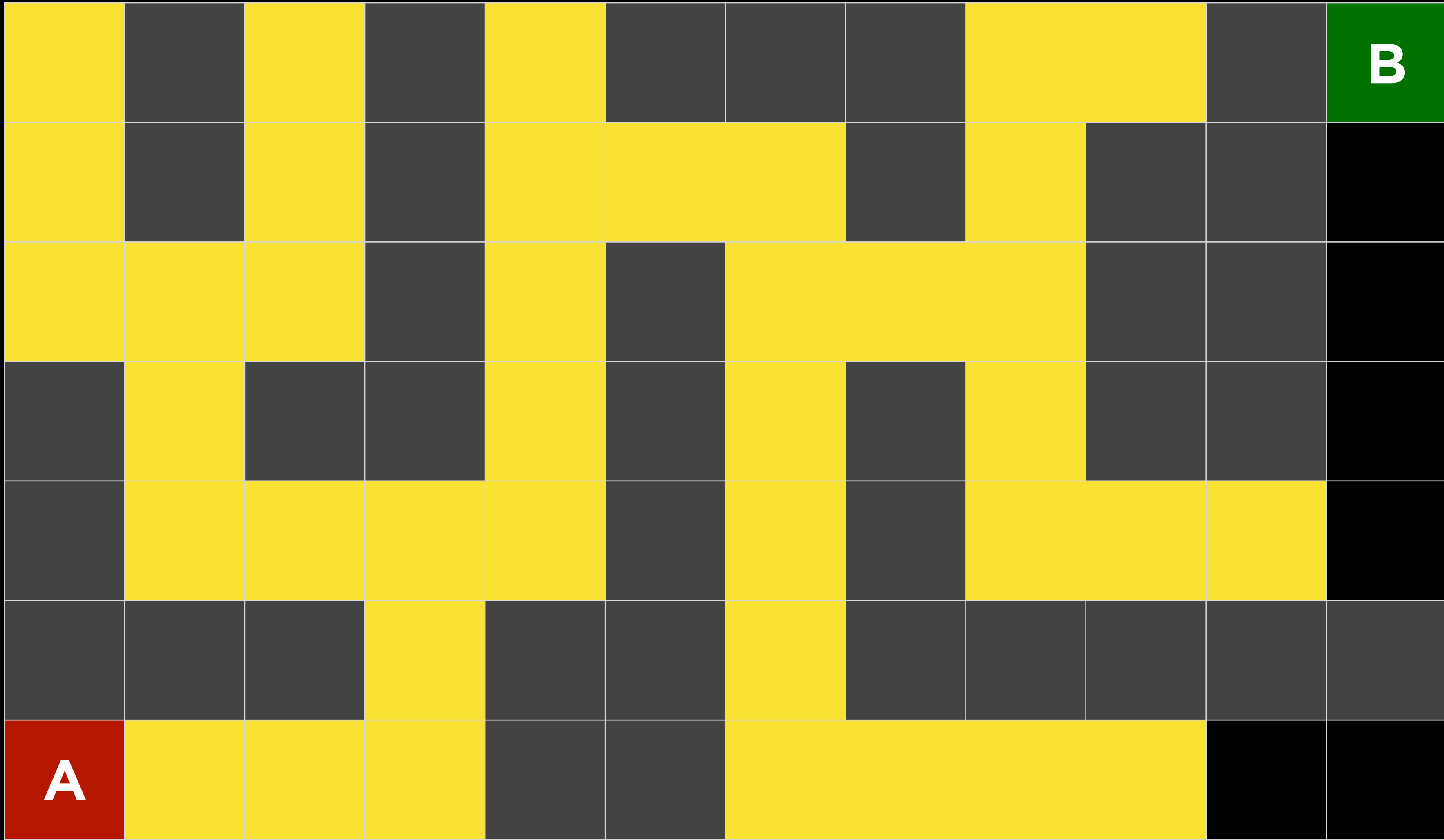
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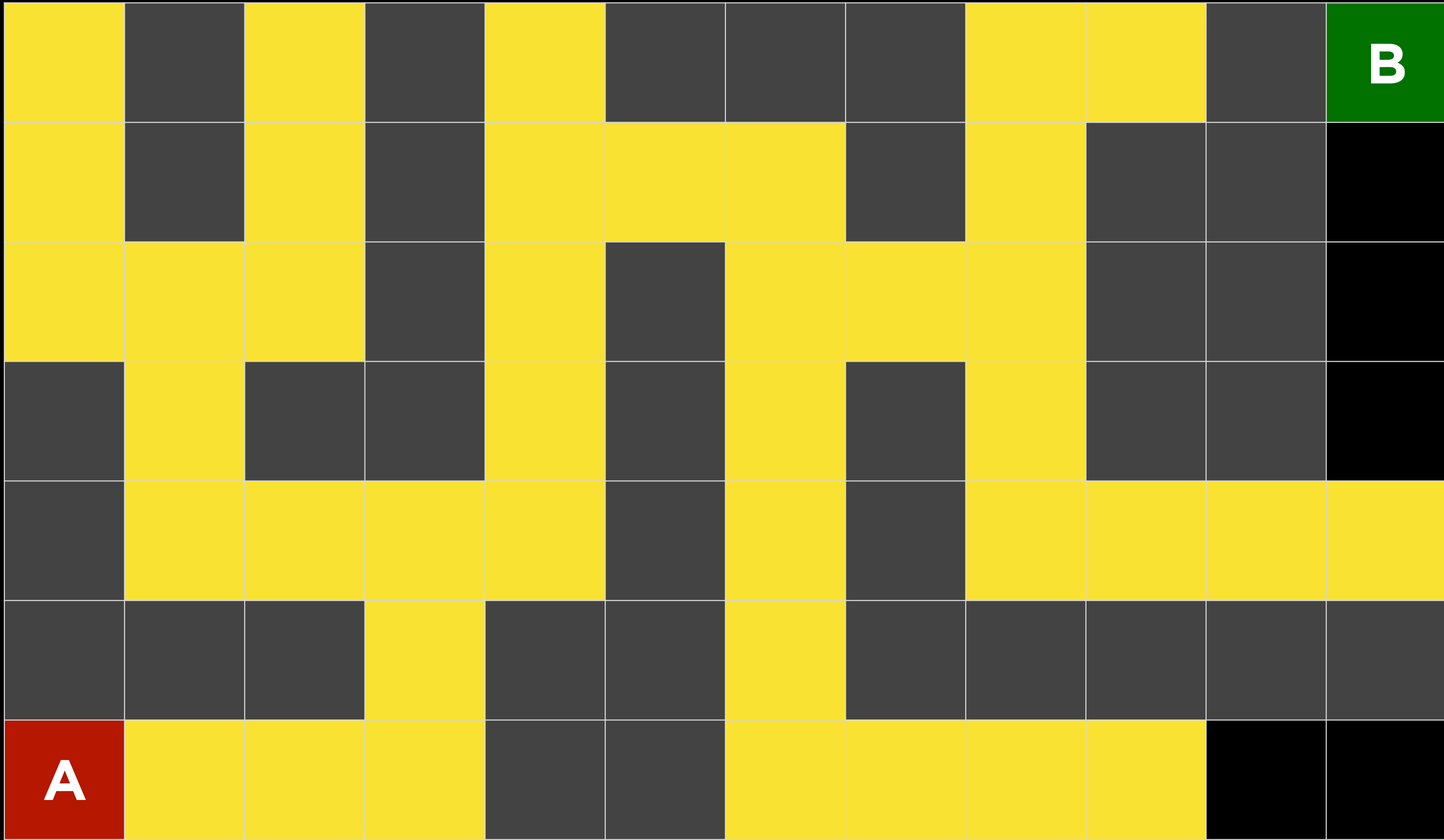
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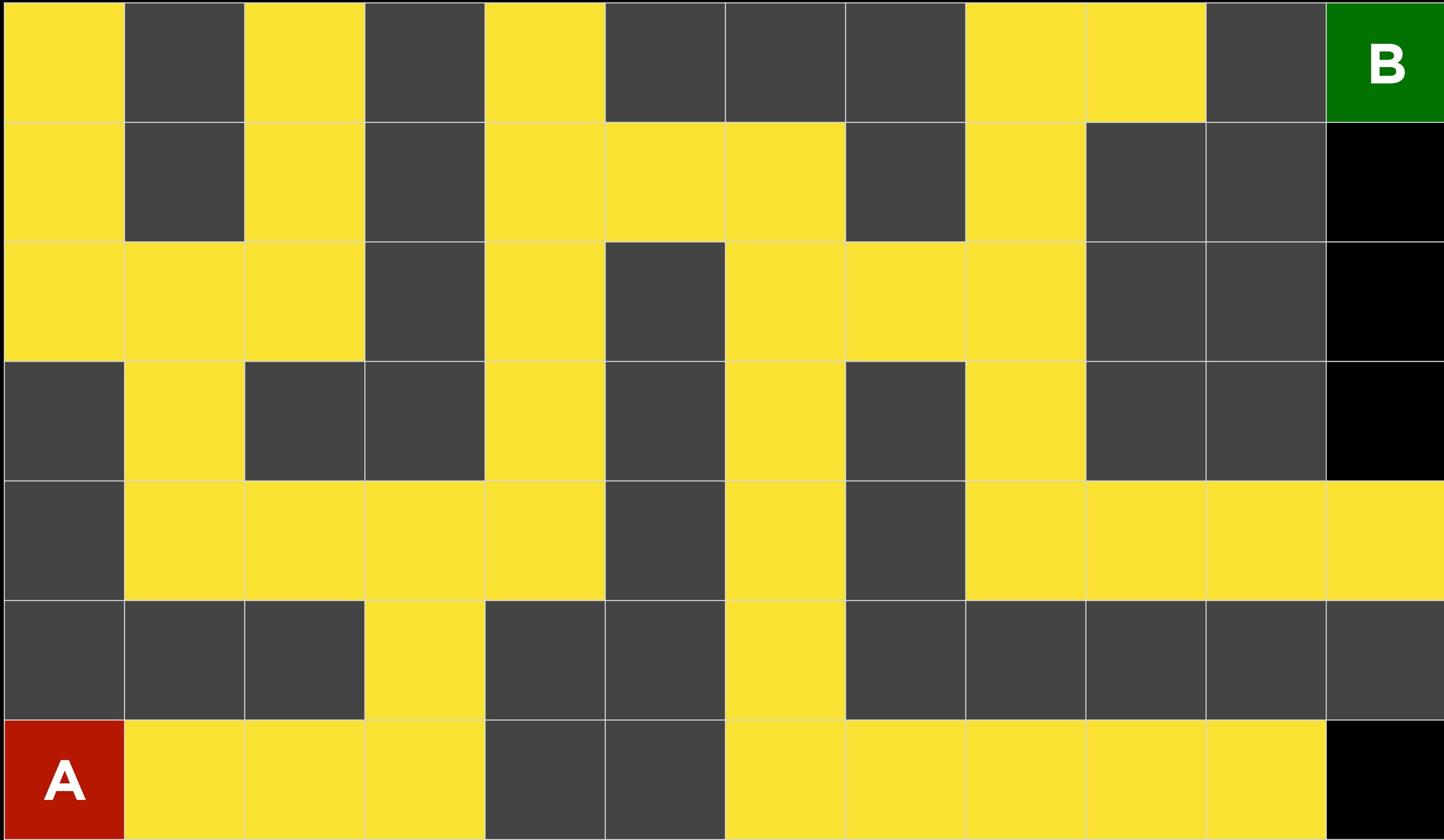
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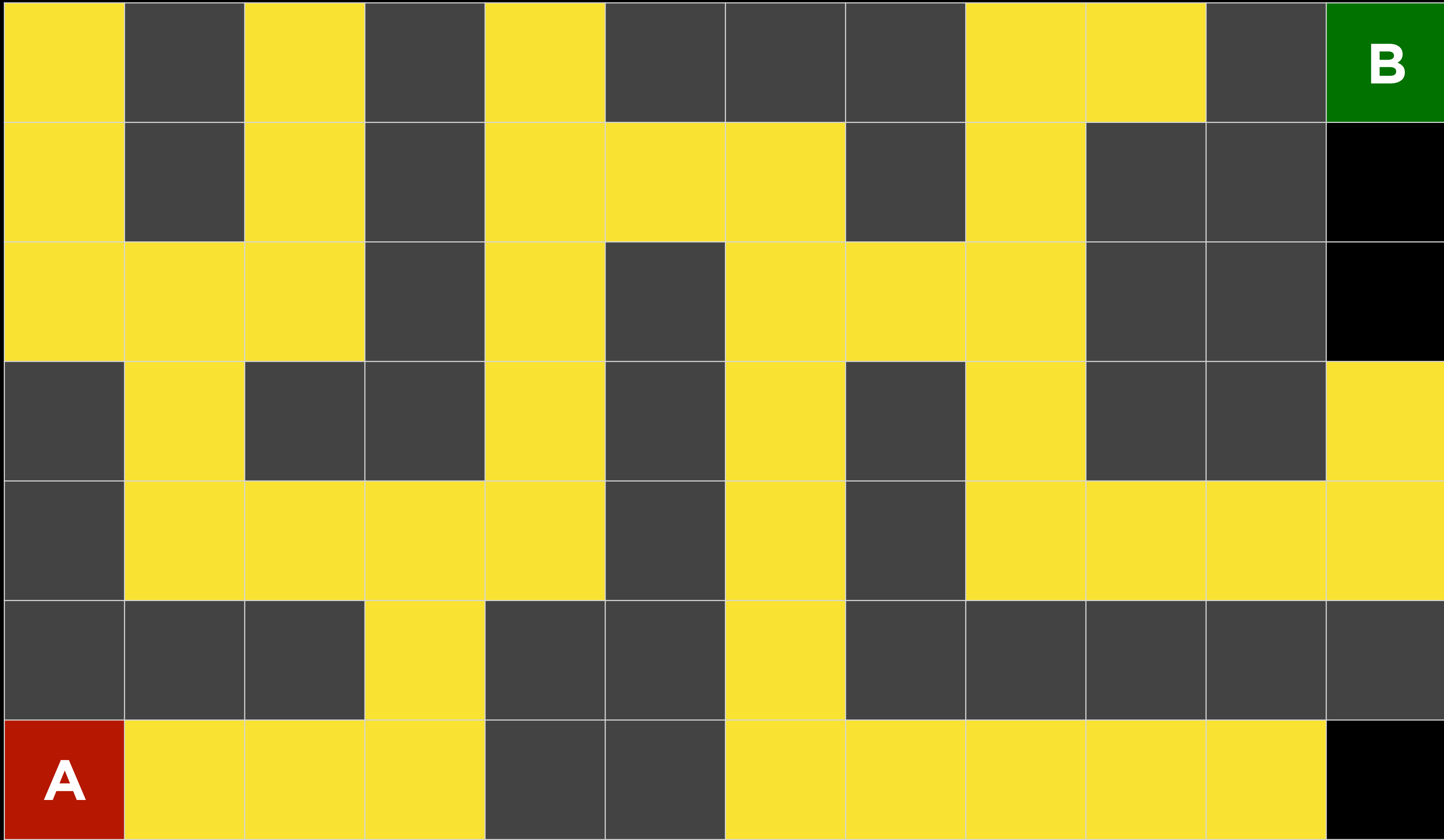
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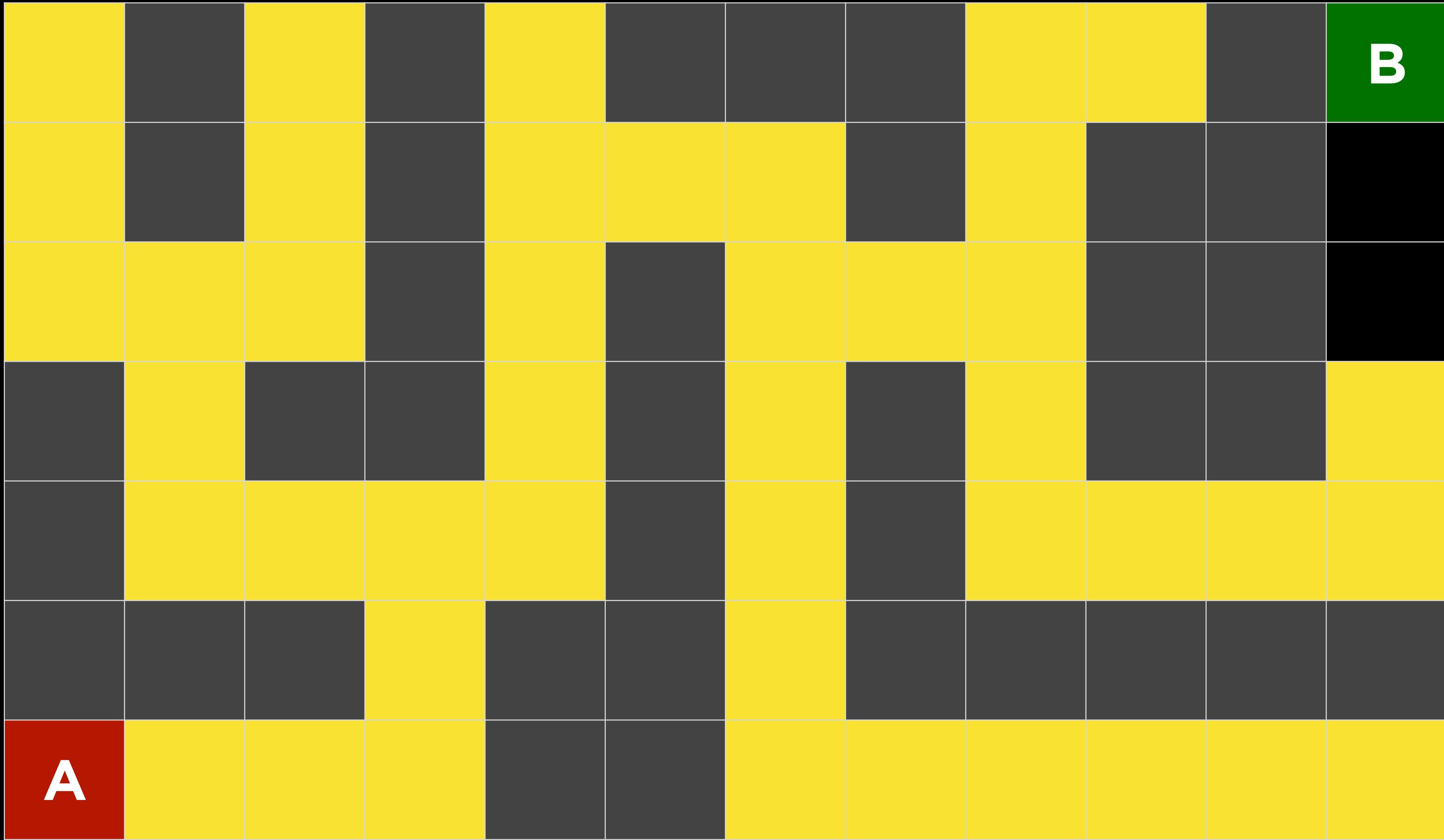
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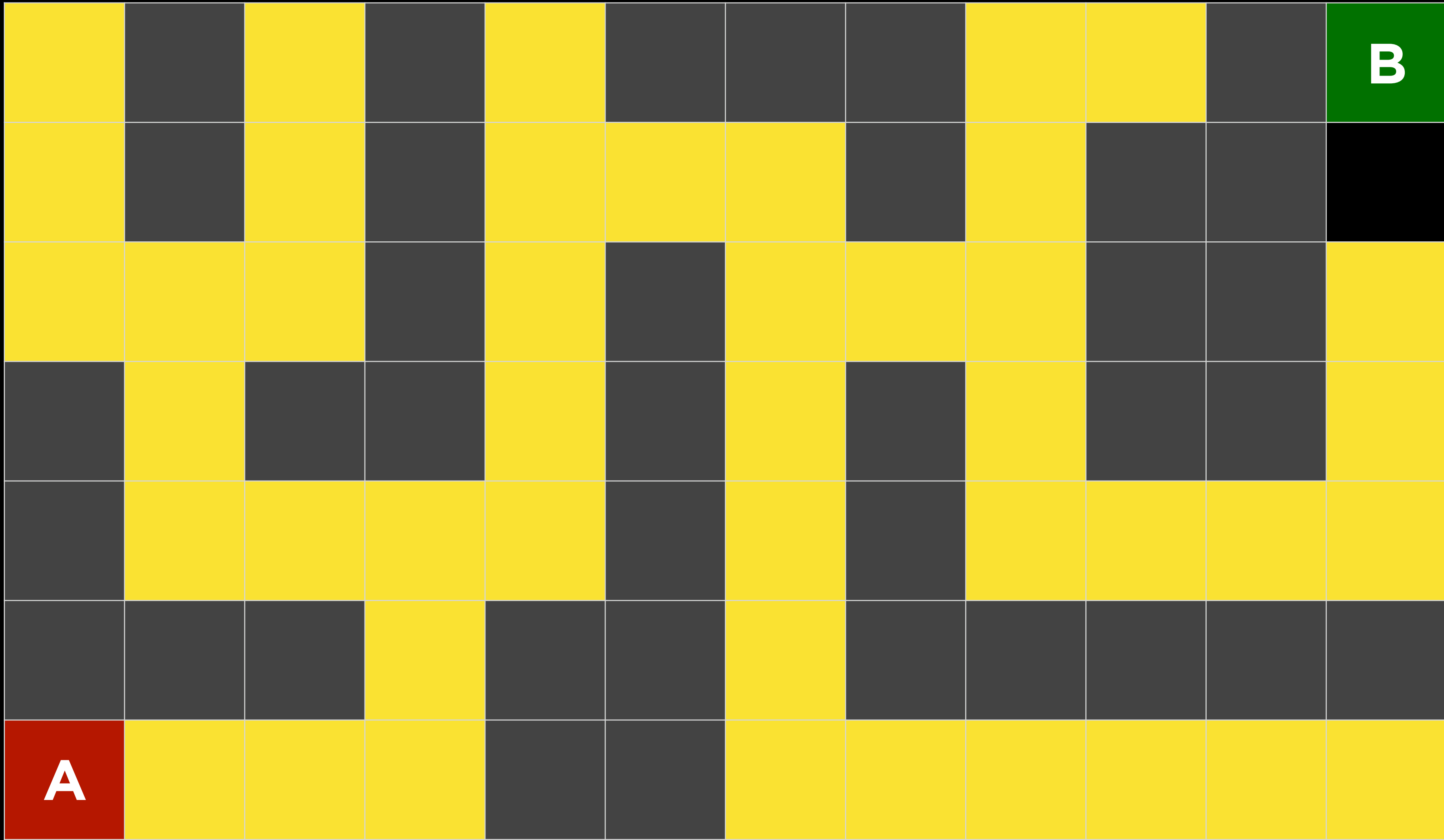
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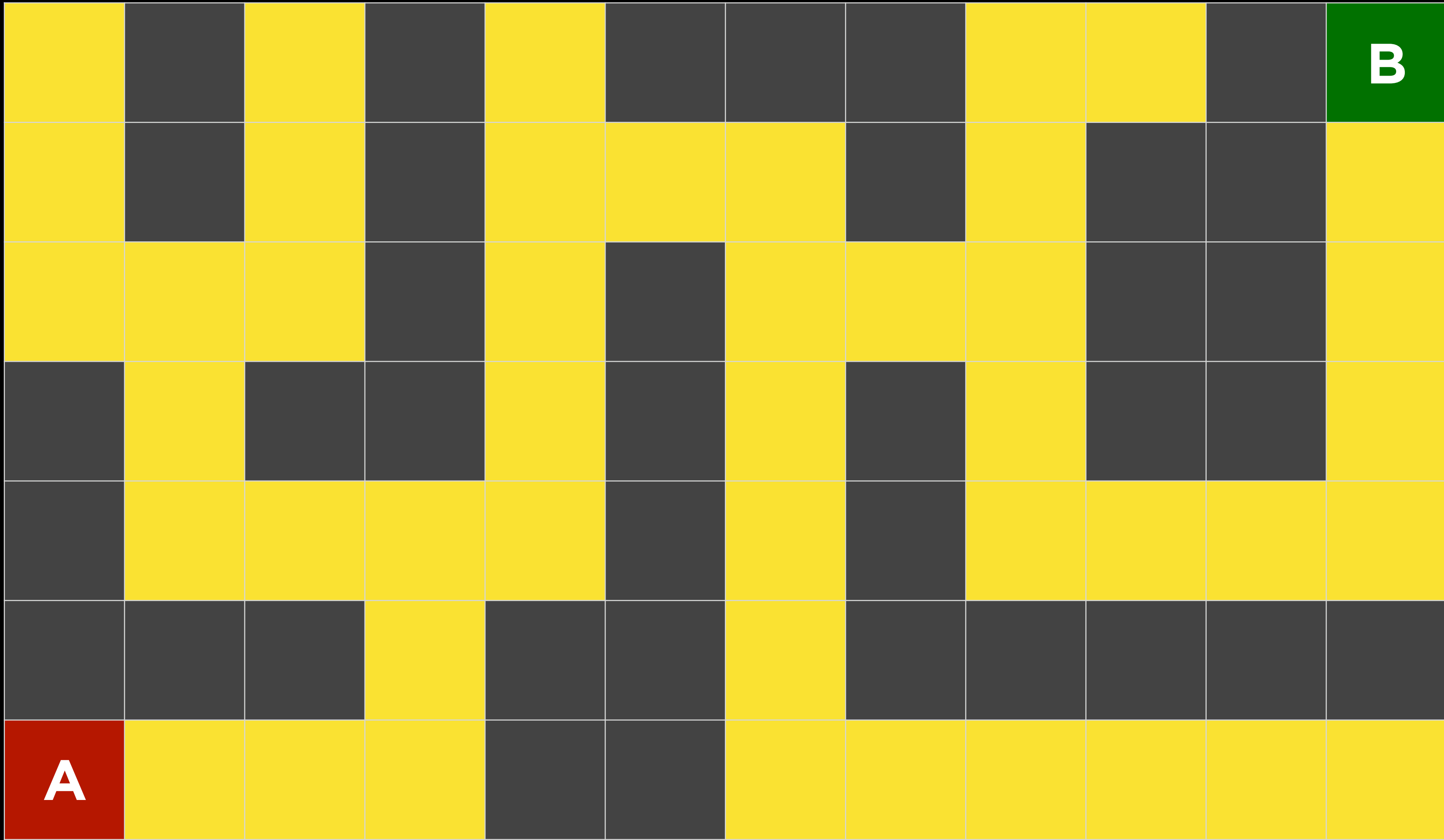
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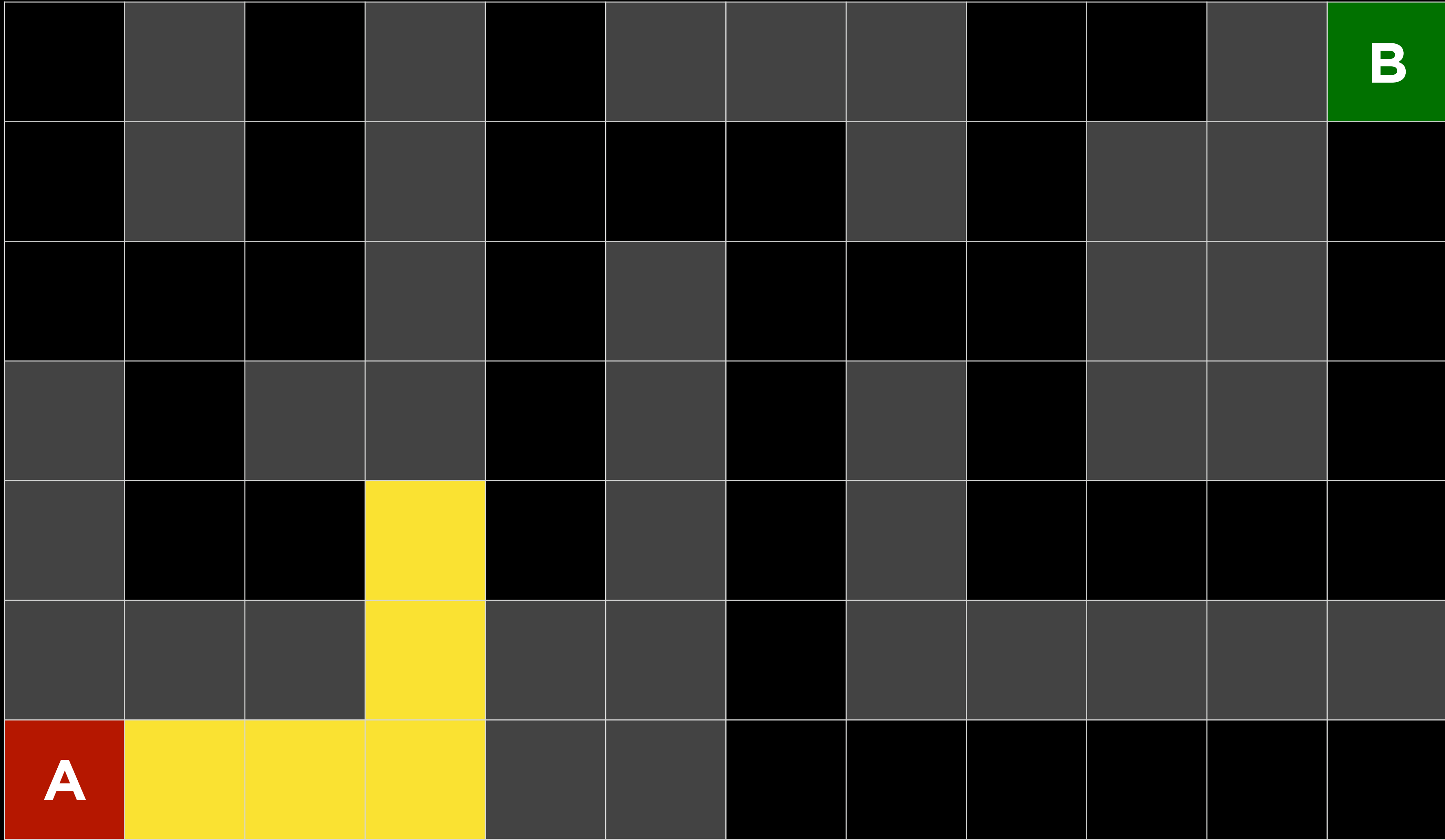
Breadth-First Search



Breadth-First Search



Breadth-First Search



uninformed search

search strategy that uses no problem-specific knowledge

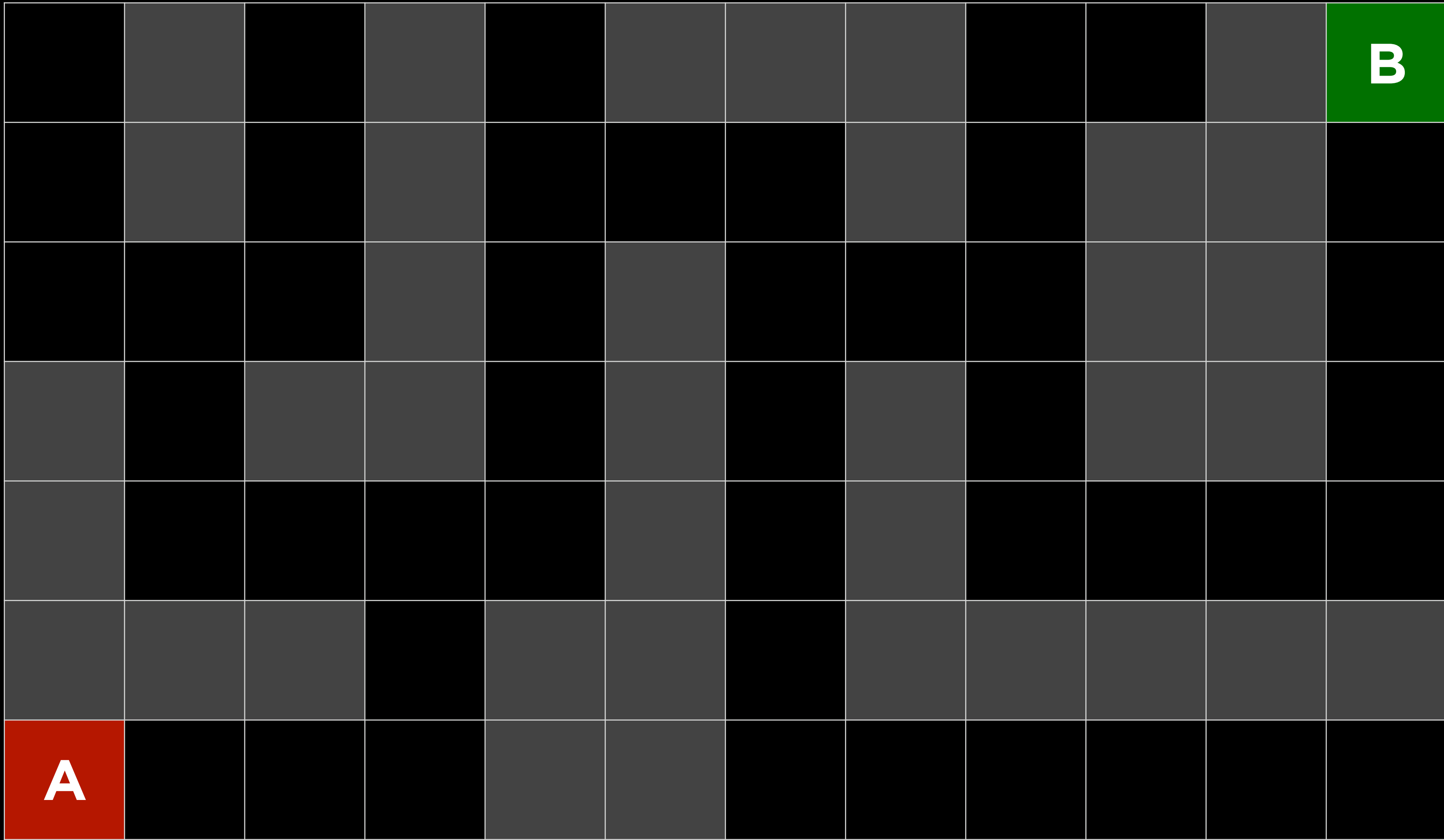
informed search

search strategy that uses problem-specific knowledge to find solutions more efficiently

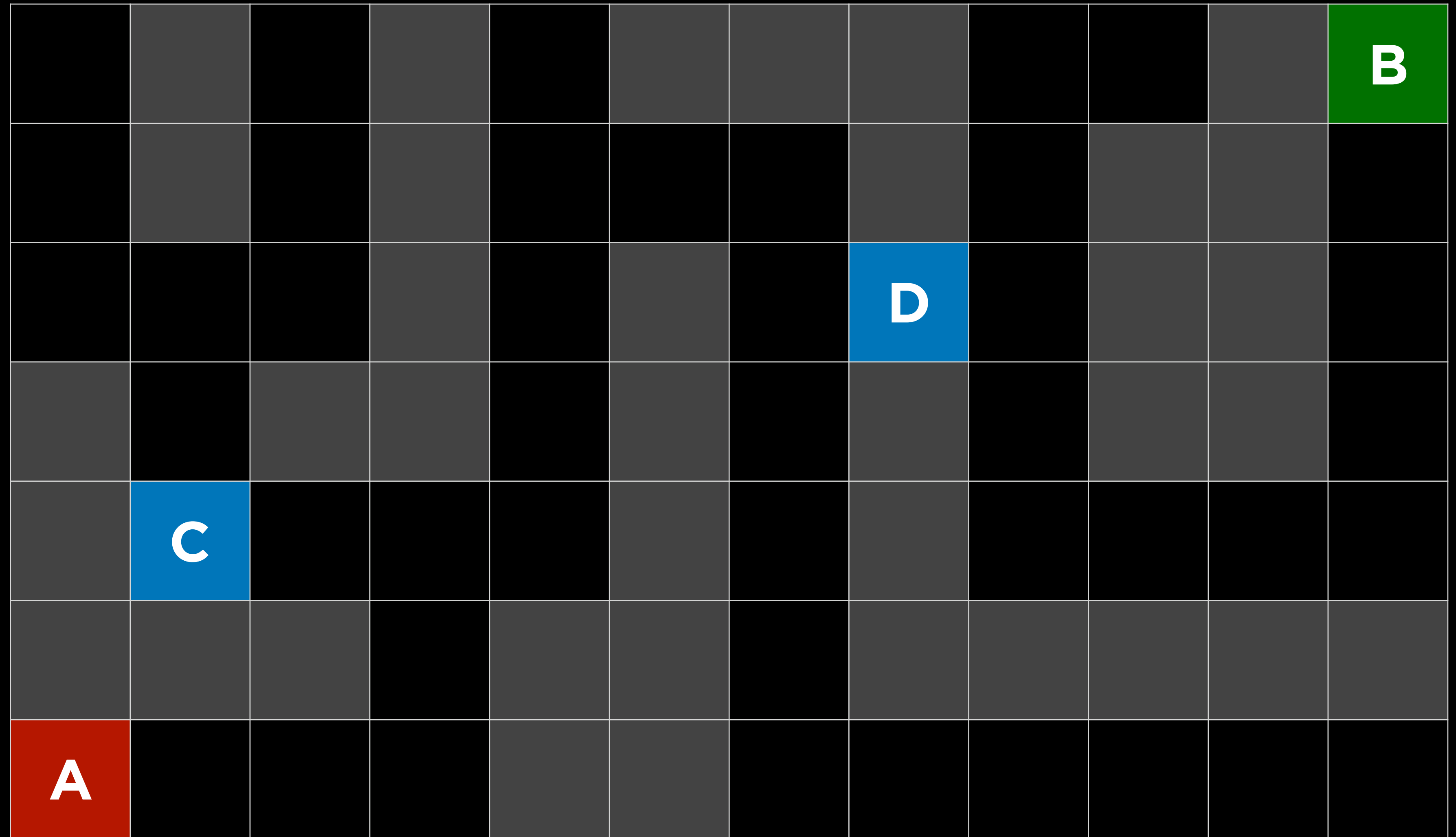
greedy best-first search

search algorithm that expands the node that is closest to the goal, as estimated by a heuristic function $h(n)$

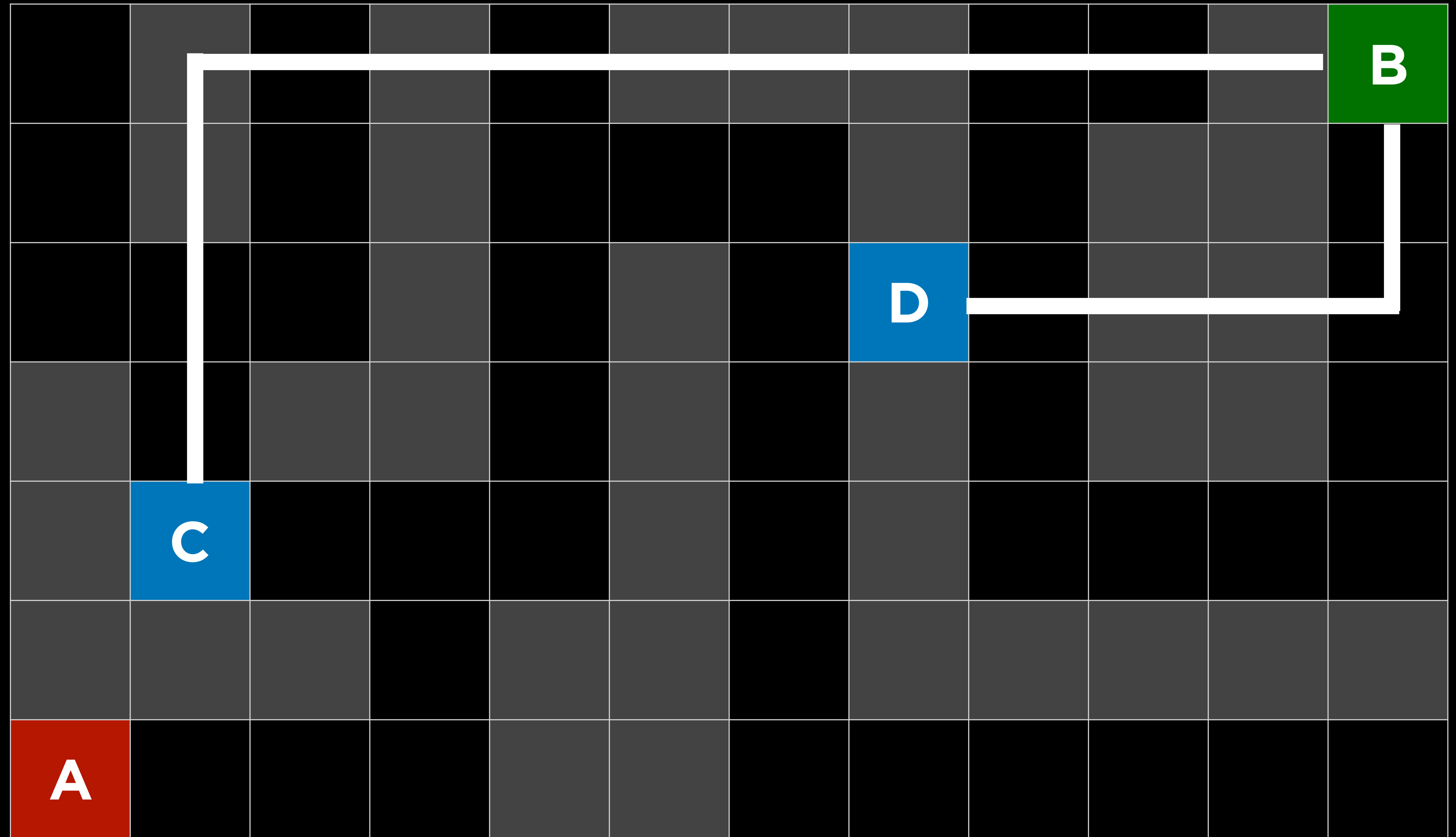
Heuristic function?



Heuristic function?



Heuristic function? Manhattan distance.



Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
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13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	15	14			11	10	9	8	7	6

Greedy Best-First Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

Greedy Best-First Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

Greedy Best-First Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

A* search

search algorithm that expands node with lowest value of $g(n) + h(n)$

$g(n)$ = cost to reach node

$h(n)$ = estimated cost to goal

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	15	14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	6+13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	10	9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

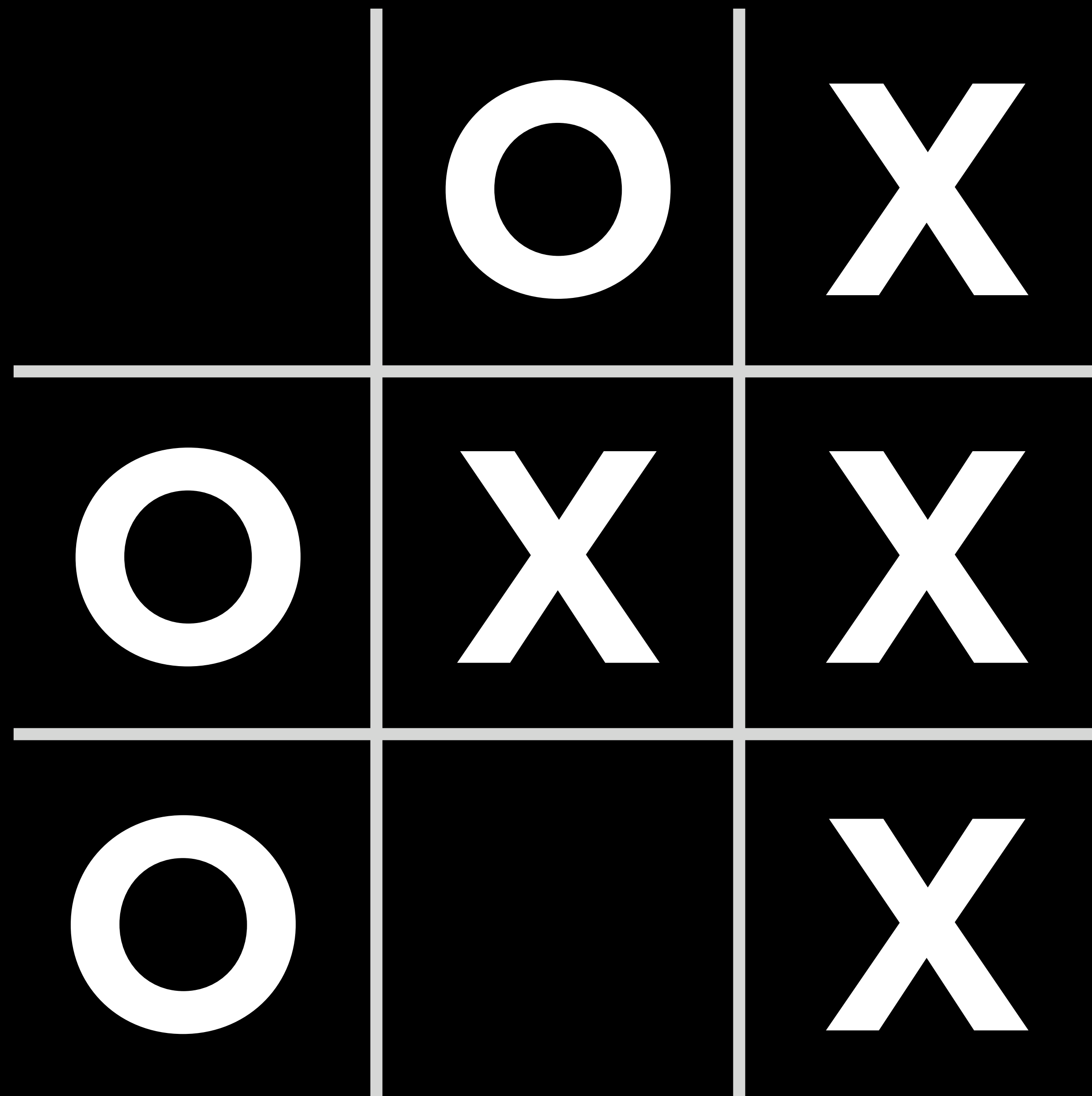
	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	20+1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

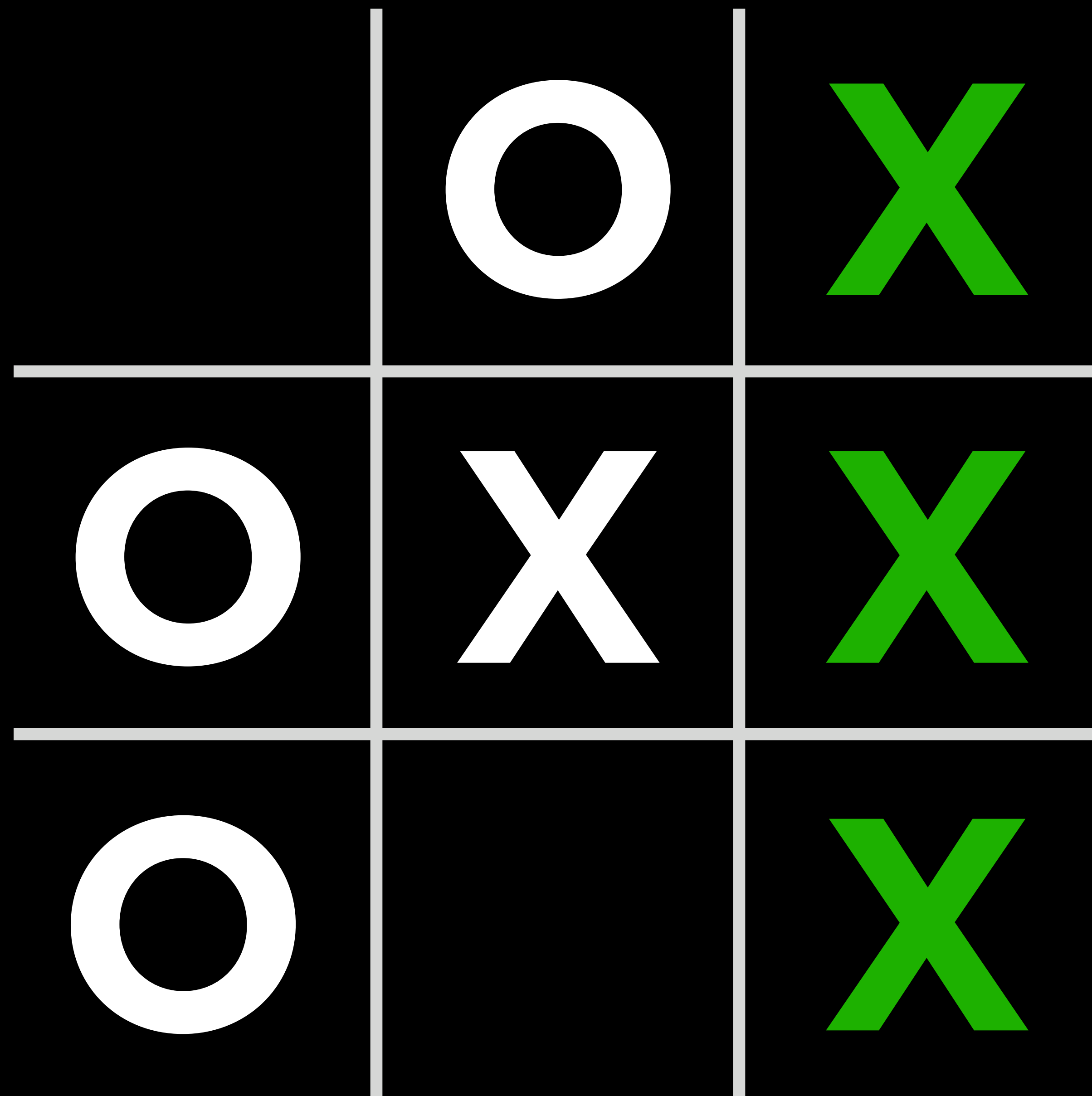
A* search

optimal if

- $h(n)$ is admissible (never overestimates the true cost), and
- $h(n)$ is consistent (for every node n and successor n' with step cost c , $h(n) \leq h(n') + c$)

Adversarial Search





Minimax

O	X	X
O	O	
O	X	X

-1

X	O	X
O	O	X
X	X	O

0

O		X
	X	O
X	O	X

1

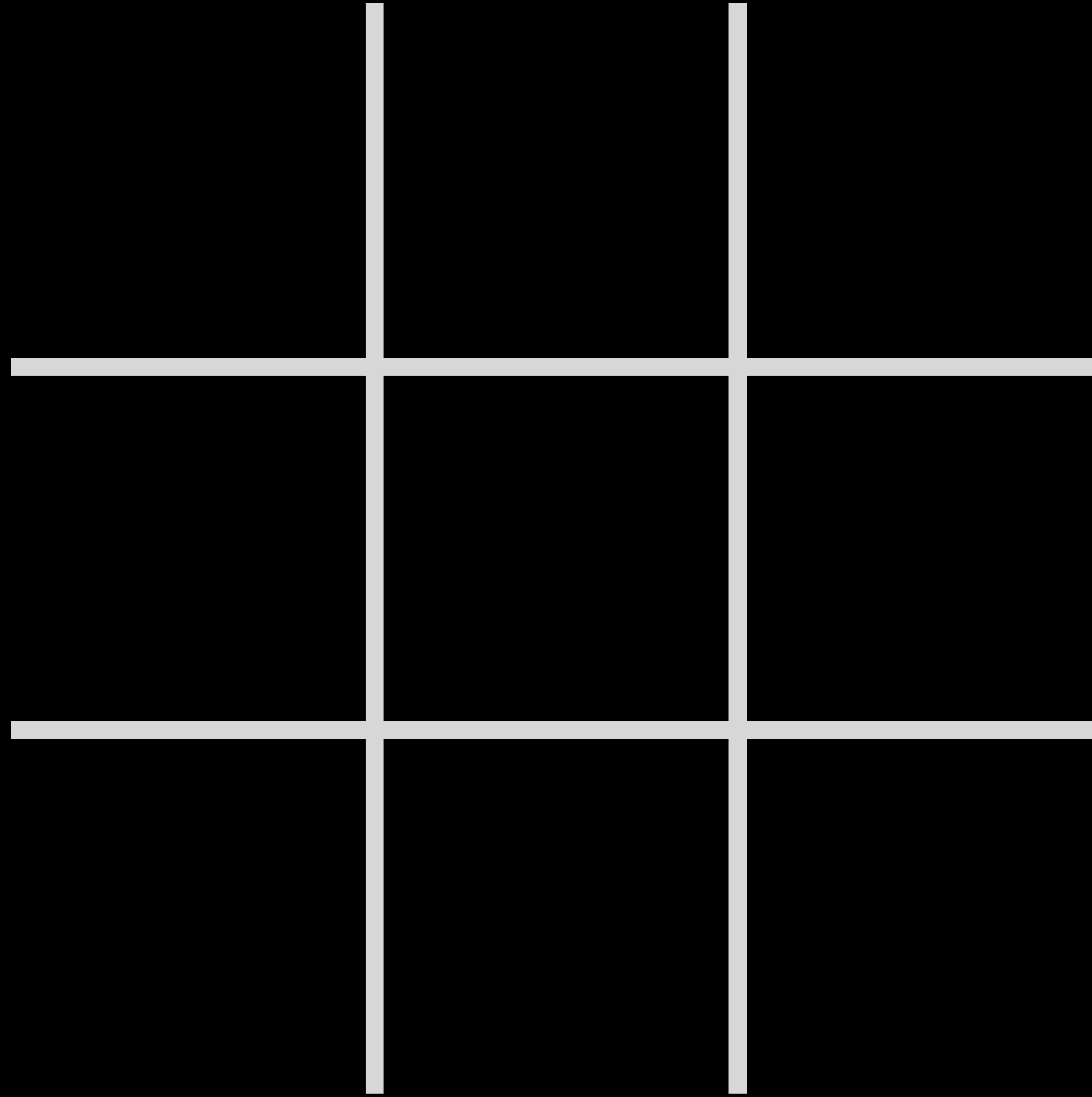
Minimax

- **MAX** (X) aims to maximize score.
- **MIN** (O) aims to minimize score.

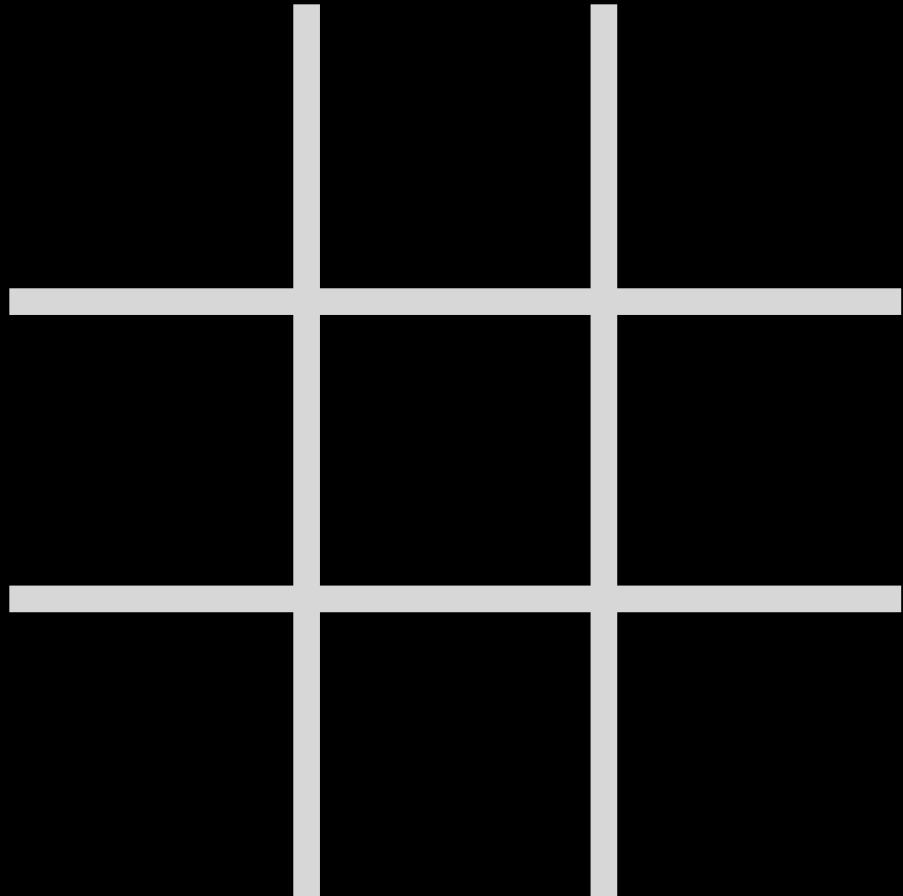
Game

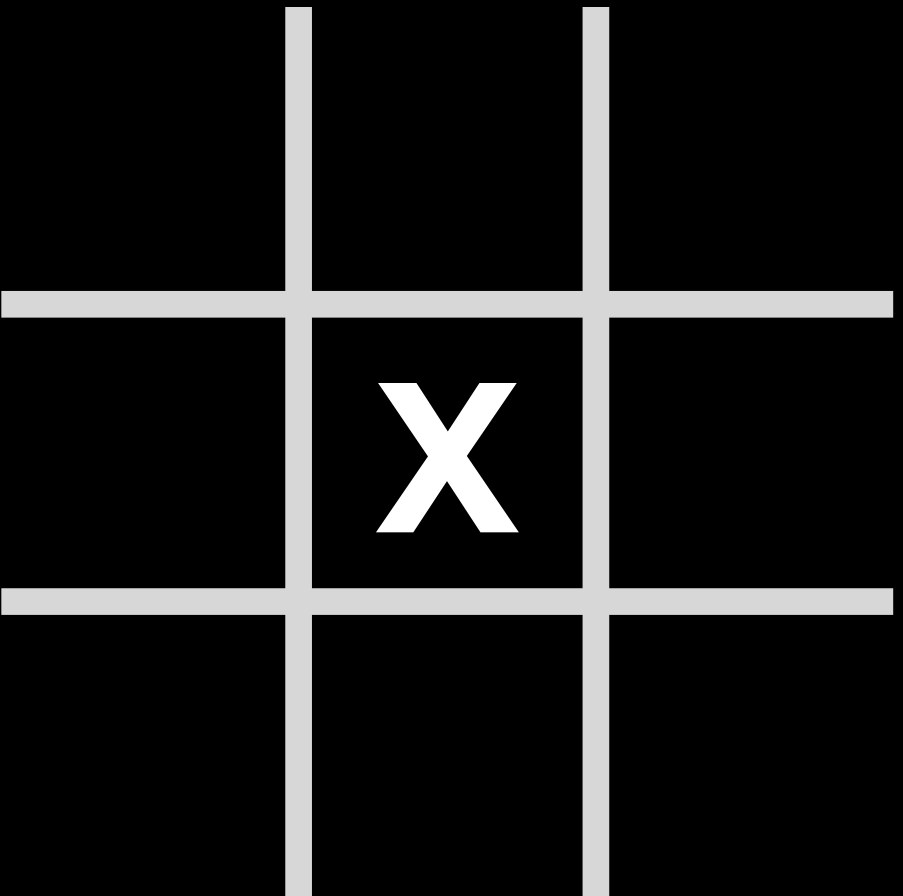
- S_0 : initial state
- $\text{PLAYER}(s)$: returns which player to move in state s
- $\text{ACTIONS}(s)$: returns legal moves in state s
- $\text{RESULT}(s, a)$: returns state after action a taken in state s
- $\text{TERMINAL}(s)$: checks if state s is a terminal state
- $\text{UTILITY}(s)$: final numerical value for terminal state s

Initial State



PLAYER(*s*)

PLAYER() = **X**

PLAYER() = **O**

ACTIONS(s)

$$\text{ACTIONS}\left(\begin{array}{c|c|c} & \text{X} & \text{O} \\ \hline \text{O} & \text{X} & \text{X} \\ \hline \text{X} & & \text{O} \end{array}\right) = \left\{ \begin{array}{c|c|c} \text{O} & & \\ \hline & & \\ \hline & & \end{array}, \begin{array}{c|c|c} & & \\ \hline & & \\ \hline & \text{O} & \end{array} \right\}$$

RESULT(s, a)

$$\text{RESULT}\left(\begin{array}{c|c|c} & \text{X} & \text{O} \\ \hline \text{O} & \text{X} & \text{X} \\ \hline \text{X} & & \text{O} \end{array}, \begin{array}{c|c|c} \text{O} & & \\ \hline & & \\ \hline & & \end{array}\right) = \begin{array}{c|c|c} \text{O} & \text{X} & \text{O} \\ \hline \text{O} & \text{X} & \text{X} \\ \hline \text{X} & & \text{O} \end{array}$$

TERMINAL(s)

TERMINAL(

o		
o	x	
x	o	x

) = false

TERMINAL(

o		x
o	x	
x	o	x

) = true

UTILITY(s)

$$\text{UTILITY}\left(\begin{array}{c|c|c} \text{o} & & \text{x} \\ \hline \text{o} & \text{x} & \\ \hline \text{x} & \text{o} & \text{x} \end{array}\right) = 1$$

$$\text{UTILITY}\left(\begin{array}{c|c|c} \text{o} & \text{x} & \text{x} \\ \hline \text{x} & \text{o} & \\ \hline \text{o} & \text{x} & \text{o} \end{array}\right) = -1$$

O	X	O
O	X	X
X	X	O

VALUE: 1

PLAYER(s) = O

MIN-VALUE:
 \emptyset

	X	O
O	X	X
X		O

MAX-VALUE:
1

O	X	O
O	X	X
X		O

MAX-VALUE:
 \emptyset

	X	O
O	X	X
X	O	O

VALUE:
1

O	X	O
O	X	X
X	X	O

VALUE:
 \emptyset

X	X	O
O	X	X
X	O	O

PLAYER(s) = O

MIN-VALUE:
 \emptyset

	X	O
O	X	X
X		O

MAX-VALUE:
1

O	X	O
O	X	X
X		O

MAX-VALUE:
 \emptyset

	X	O
O	X	X
X	O	O

VALUE:
1

O	X	O
O	X	X
X	X	O

VALUE:
 \emptyset

X	X	O
O	X	X
X	O	O

PLAYER(s) = X

MAX-VALUE:
1

	X	O
O	X	
X		O

MIN-VALUE:
0

	X	O
O	X	X
X		O

MAX-VALUE:
1

O	X	O
O	X	X
X		O

VALUE:
1

O	X	O
O	X	X
X	X	O

MAX-VALUE:
0

	X	O
O	X	X
X	O	O

VALUE:
0

X	X	O
O	X	X
X	O	O

MIN-VALUE:
-1

X	X	O
O	X	
X		O

VALUE:
-1

X	X	O
O	X	O
X		O

MAX-VALUE:
0

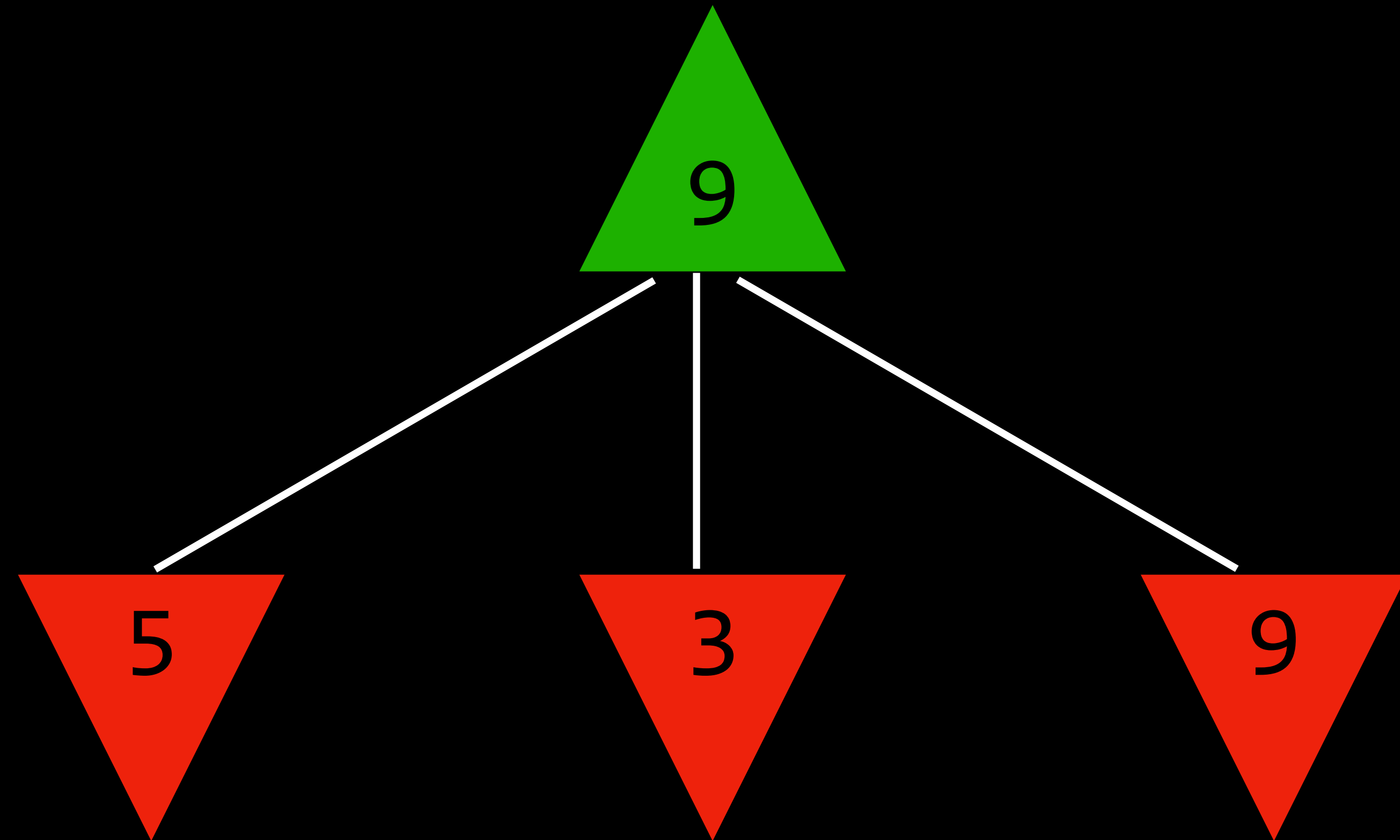
X	X	O
O	X	
X	O	O

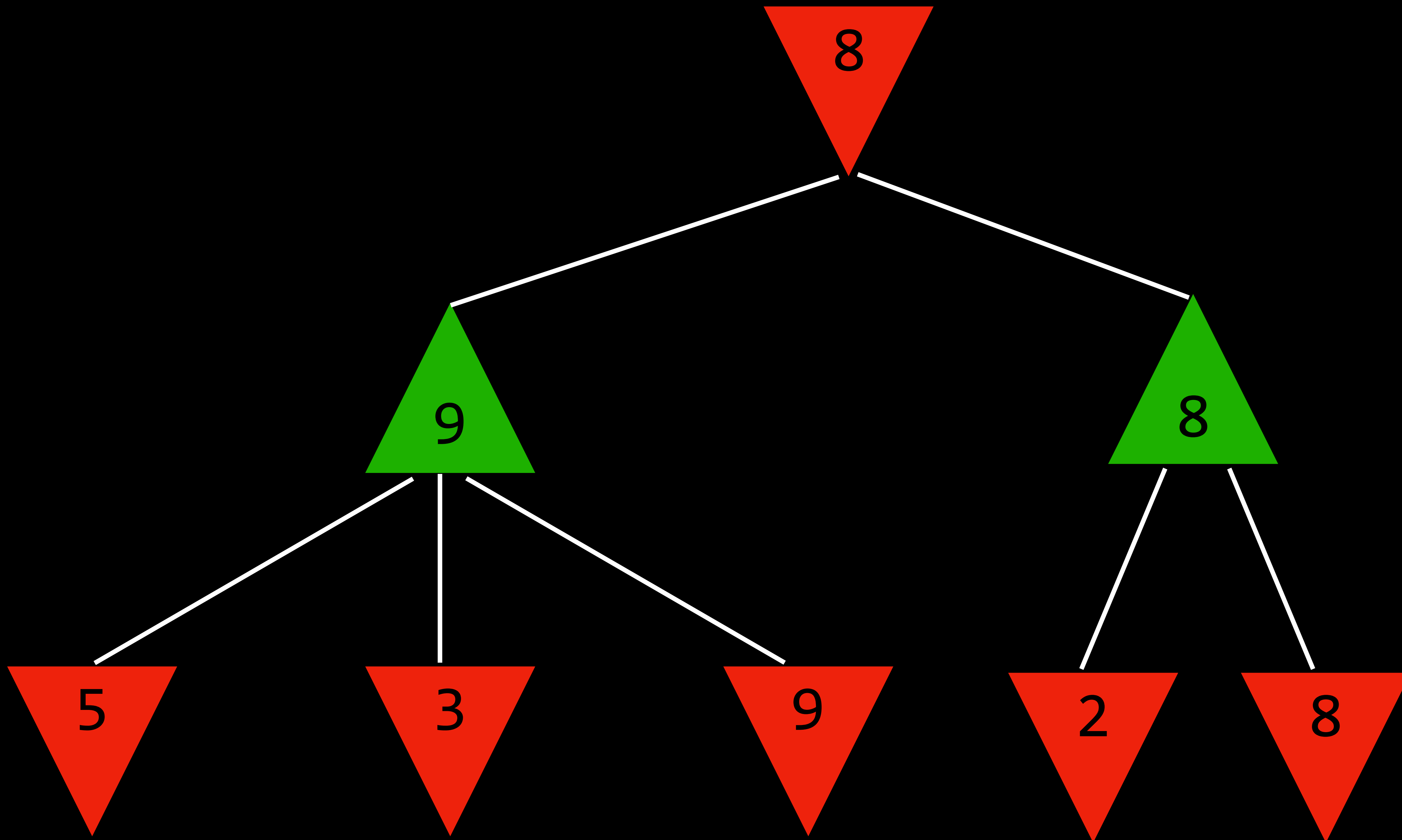
VALUE:
0

X	X	O
O	X	X
X	O	O

VALUE:
1

	X	O
O	X	
X	X	O





Minimax

- Given a state s :
 - **MAX** picks action a in $\text{ACTIONS}(s)$ that produces highest value of $\text{MIN-VALUE}(\text{RESULT}(s, a))$
 - **MIN** picks action a in $\text{ACTIONS}(s)$ that produces smallest value of $\text{MAX-VALUE}(\text{RESULT}(s, a))$

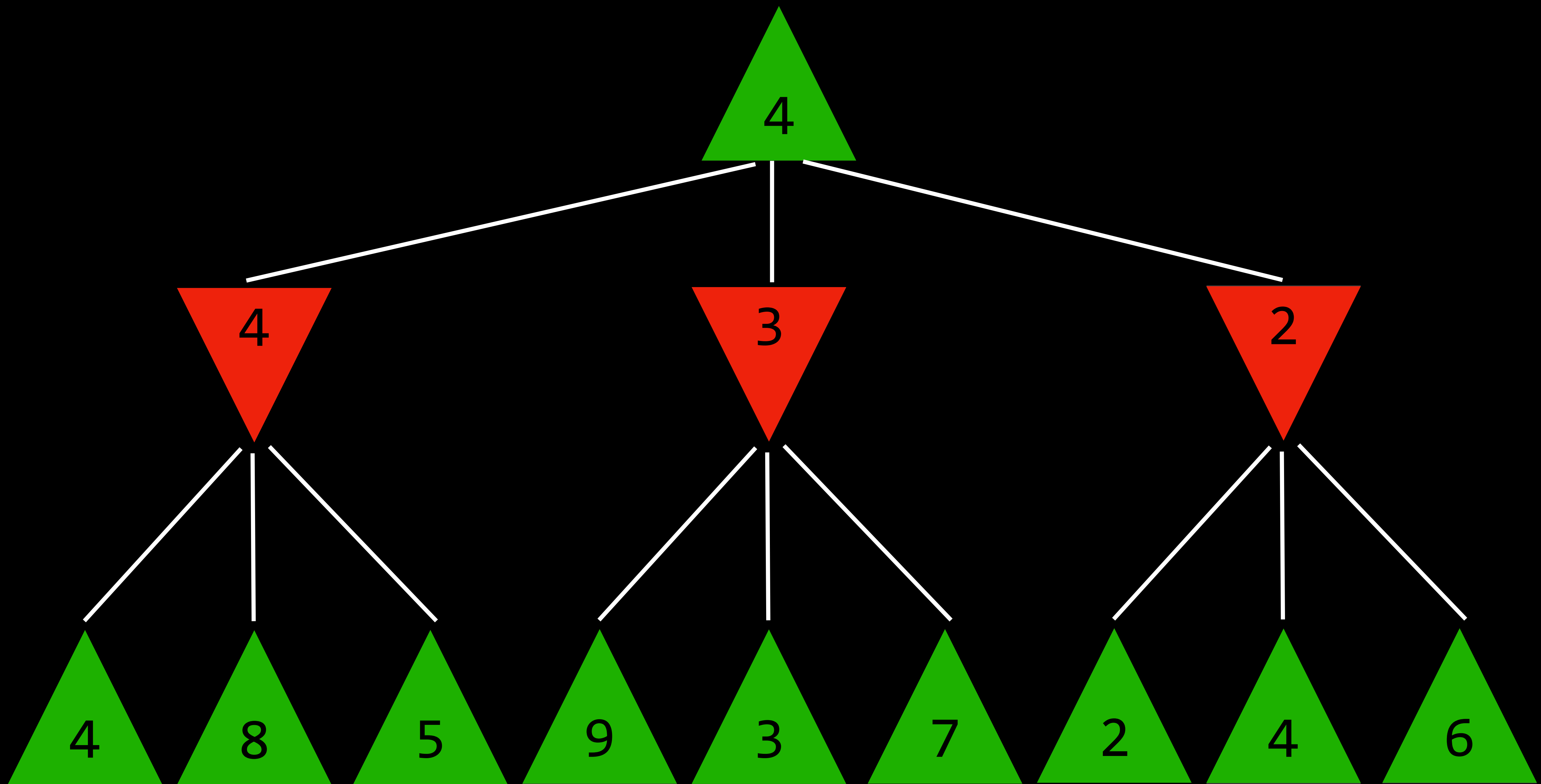
Minimax

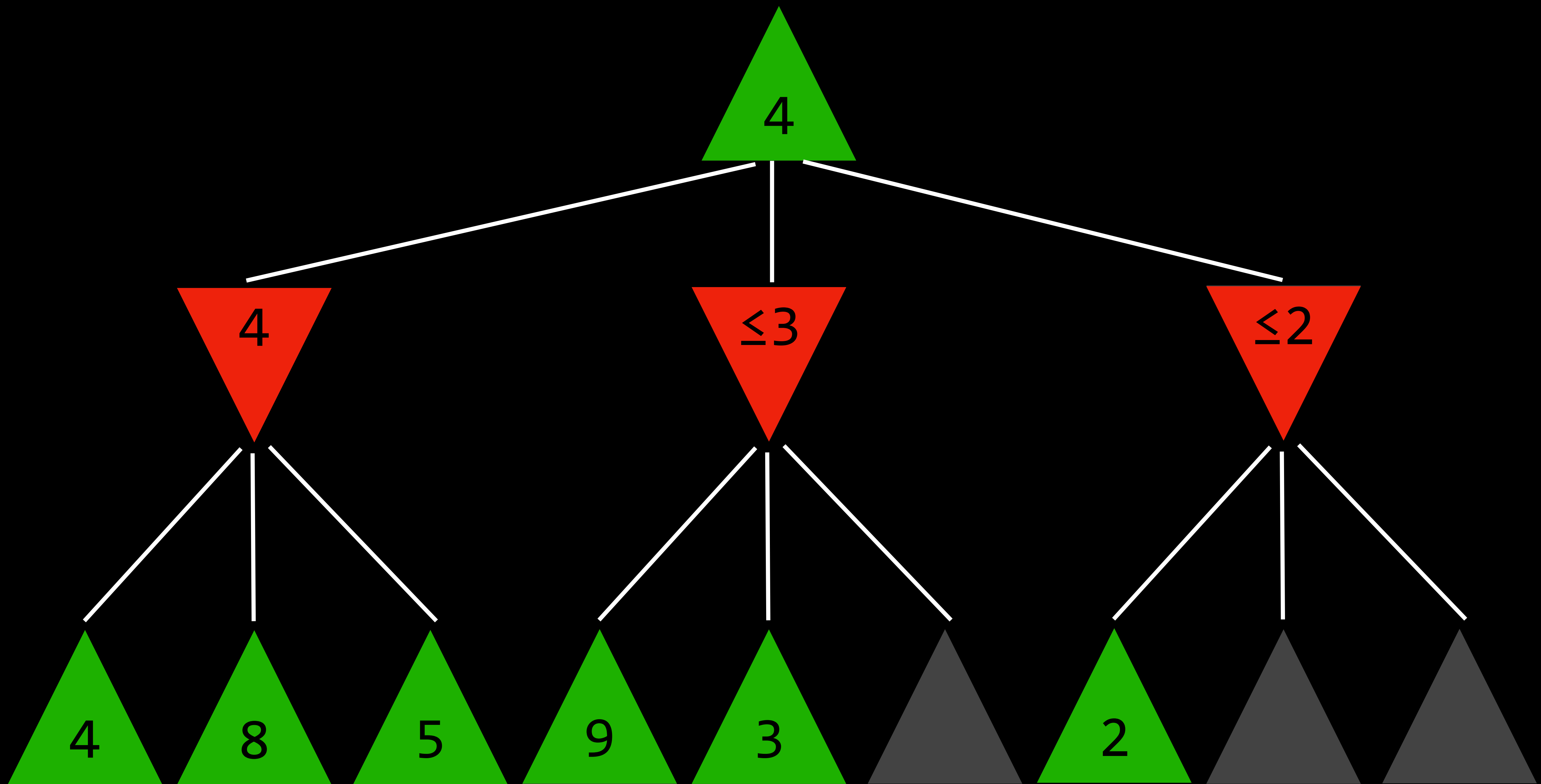
```
function MAX-VALUE(state):  
  if TERMINAL(state):  
    return UTILITY(state)  
   $v = -\infty$   
  for action in ACTIONS(state):  
     $v = \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(\textit{state}, \textit{action})))$   
  return  $v$ 
```

Minimax

```
function MIN-VALUE(state):  
  if TERMINAL(state):  
    return UTILITY(state)  
   $v = \infty$   
  for action in ACTIONS(state):  
     $v = \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(\textit{state}, \textit{action})))$   
  return  $v$ 
```

Optimizations





Alpha-Beta Pruning

255,168

total possible Tic-Tac-Toe games

288,000,000,000

total possible chess games
after four moves each

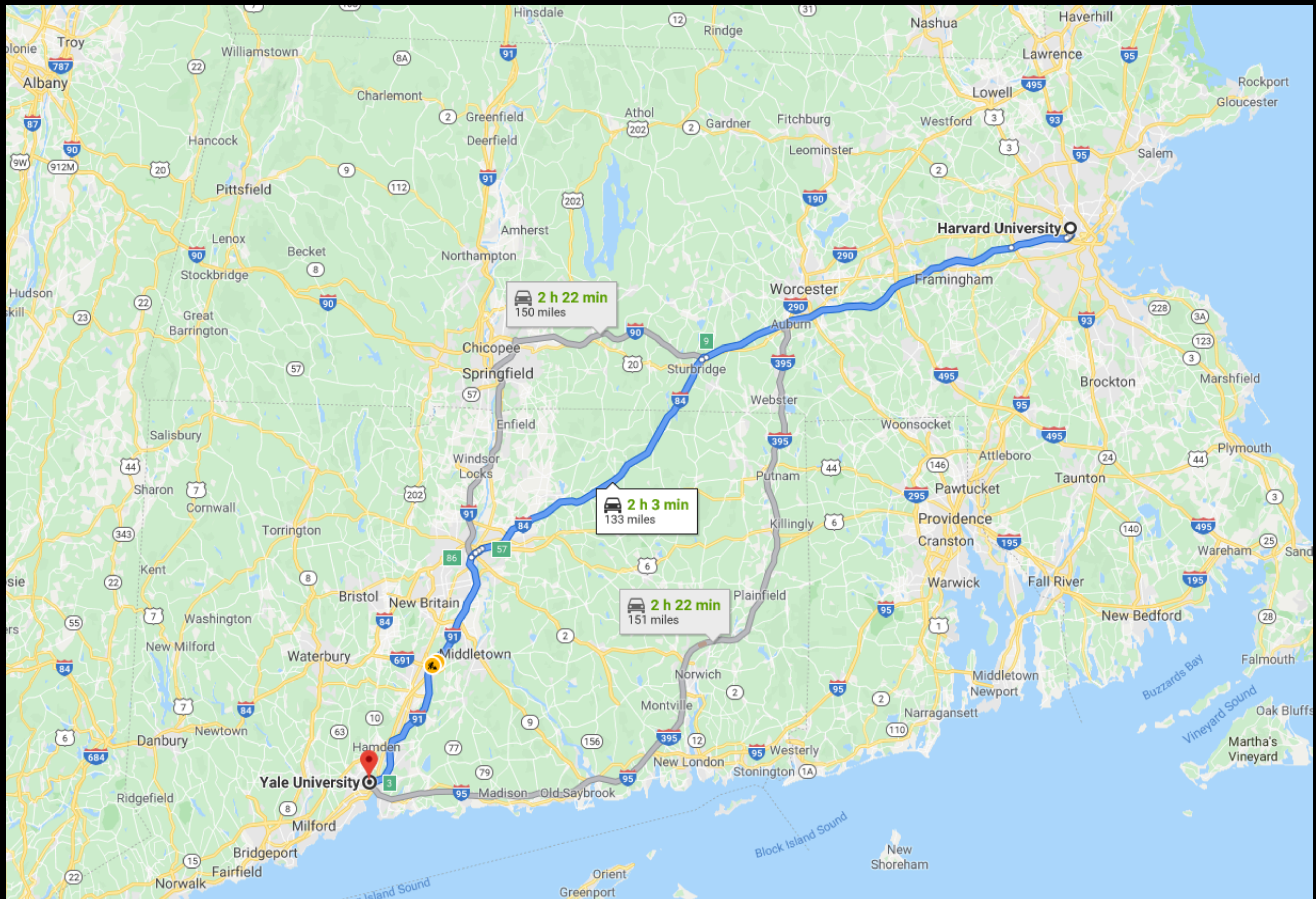
10^{29000}

total possible chess games
(lower bound)

Depth-Limited Minimax

evaluation function

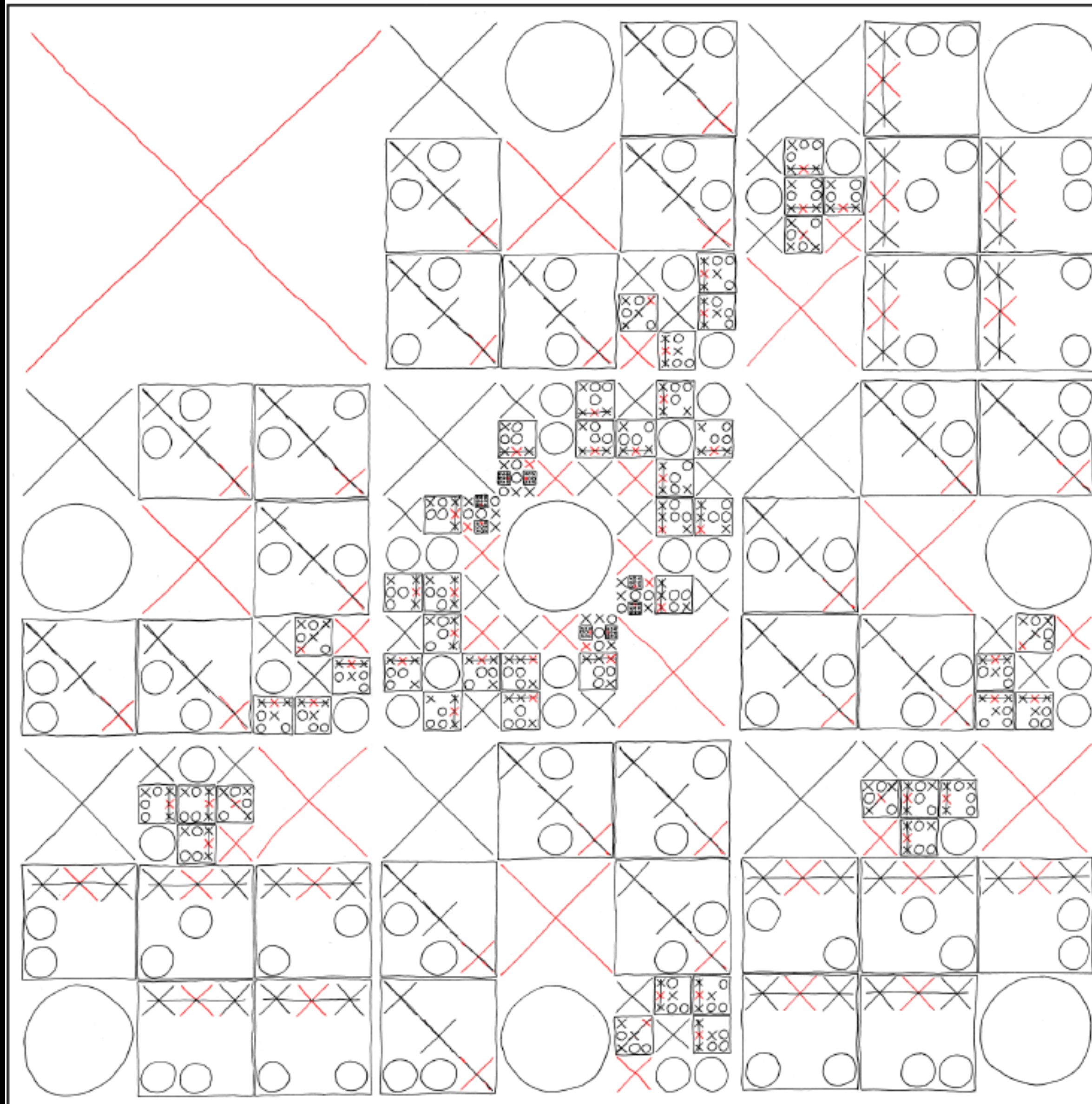
function that estimates the expected utility of the game from a given state



COMPLETE MAP OF OPTIMAL TIC-TAC-TOE MOVES

YOUR MOVE IS GIVEN BY THE POSITION OF THE LARGEST RED SYMBOL ON THE GRID. WHEN YOUR OPPONENT PICKS A MOVE, ZOOM IN ON THE REGION OF THE GRID WHERE THEY WENT. REPEAT.

MAP FOR X:



Search

Introduction to
Artificial Intelligence
with Python